



VOCONUIZMO IE EXPORTNO-IMPORTNO JE OBJEDINENIJE

STANKOIMPORT

DRILLING AND BORING MACHINES

BENCH DRILLING MACHINES
VERTICAL DRILLING MACHINES
RADIAL DRILLING MACHINES
JIG BORING MACHINES
HORIZONTAL BORING, DRILLING AND
MILLING MACHINES
PRECISION BORING MACHINES

VSESOJUZNOJE EXPORTNO-IMPORTNOJE OBJEDINENIJE

STANKOIMPORT

USSR

MOSCOW

This catalogue contains short specifications of the most common types of machine tools exported by the Vsesojuznoje Exportno-Importnoje Objedinenije "Stankoimport". Detailed pamphlets sent on request. All inquiries and correspondence to be forwarded to:

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The Machine Tools produced in the U.S.S.R. are outstanding for their high efficiency, convenience and safety in operation and long service.

The first class material, perfect modern design and skilful workmanship provide accuracy, high efficiency and durability of the Machine Tools.

Steady improvement of machine tool design in the U.S.S.R. aims at the increase of productivity, accuracy, reliability and dependability of machine in operation, as well as the reduction of operator's fatigue by improving and convenient placing of all operating controls and the all-increasing automatization of operation.

The Vsesojuznoje Export no-Import noje Objedine nije ``Stanko-Import noje Objedine nije '`Stanko-Import noje Objedine nije Objedine nije Objedine nije '`Stanko-Import noje Objedine nije Objedine nimport" is able to offer a wide range of Machine Tools both universal and special types including Automatic Transfer Machines and Automatic Workshops.



HIGH SPEED BENCH DRILLING MACHINE

MODEL 2A106



The 2A106 High Speed Bench Drilling Machine has been designed for the drilling of small diameter holes efficiently, and with the highest degree of accuracy.

6 spindle speeds are obtained by shifting the belt to various of the 3 step cone pulleys.

The spindle feed is hand operated and extremely sensitive.
The machine is fitted with a depth stop, quickly adjustable to any desired depth within its capacity.

The machine is equipped with a separate electric motor.

SPECIFICATIONS

 Maximum drill diameter, mm
 6
 Distance, end of spindle to base, mm: minimum
 25

 Distance, center of spindle to column, mm
 125
 Working surface of base, mm
 250×250



Spindle
Taper in spindle . . Morse No.1a (shortened)
Spindle speeds, r.p.m. . . 1545; 2900; 4500; 7400; 11050; 15000

Drive
220/380 volt, 3 phase, 50 cycle A.C.
motor:

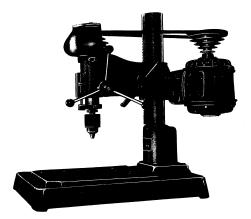
power, kW ... 0.6 speed, r.p.m. 3000

Weight
Net weight, kg approx. 82



BENCH DRILLING MACHINE

MODEL HC-12A



diameter holes.
5 spindle speeds are obtained by shifting the belt to various steps of the pulleys.
The spindle feed is hand operated and extremely sensitive.
The machine is fitted with a depth stop, quickly adjustable to any desired depth within its capacity.
The machine is equipped with a separate electric motor.





SPECIFICATIONS

DI ECILIE	
Capacity	Drive
Maximum drill diameter, mm	220/380 volt, 3 phase, 50 cycle A.C. motor:
mm	power, kW
maximum	Space Occupied Floor space, mm
Spindle Taper in spindle Morse No. 2b (shortened)	Height of machine, mm
Maximum travel of spindle, mm 100 Number of spindle speeds 5	. Weight
Range of spindle speeds, r.p.m 450—4500	Net weigth, kg approx. 12



VERTICAL DRILLING MACHINE

MODEL 2A125



The 2A125 Vertical Drilling Machine is designed for drilling, boring, reaming, facing and tapping operations. 9 spindle speeds and 9 feeds are obtained through speed and gear boxes. The automatic feed is engaged and disengaged by turning the hand-feed wheel. During the automatic feed the spindle can be fed manually.

The feed mechanism is provided with automatic overload release. The predetermined depth of drilling is limited by dial stops which automatically trip the feed. The spindle rotation is reversed also by means of a dial stop.





All controls and levers are grouped within convenient reach from the operator's working position. Special attention has been paid to lubrication. All main parts of the machine are lubricated automatically.

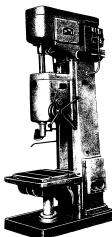
SPECIFICATIONS

	•
Capacity	Speeds and Feeds
Maximum drill diameter in steel of 50—60 kg/mm² tensile strength, mm Distance, end of spindle to table, mm: minimum 0 25 minimum 700 0	Number of spindle speeds
Distance, end of spindle to base, mm:	Drive
minimum 7500 maximum 1100 Distance, center of spindle to column, mm 250 Table Working surface of table, mm 500×375 Maximum vertical travel of table, mm 325	220/380 volt, 3 phase, 50 cycle A.C. motors: Spindle drive: Spower, kW 2.8 speed, r.p.m. 1500 Coolant pump: 0.1 power, kW 0.1 speed, r.p.m. 3000 Space Occupied
Spindle Taper in spindle Morse No.3 Maximum vertical spindle travel, mm 175 Vertical spindle head adjustment, mm 200	Floor space, mm



VERTICAL DRILLING MACHINE

MODEL 2A135



The 2A135 Vertical Drilling Machine is designed for drilling, boring, reaming, facing and tapping operations.

9 spindle speeds and 11 feeds are obtained through speed and feed gear boxes. The automatic feed is engaged and disengaged by turning the hand-feed wheel. During the automatic feed the spindle can be fed manually. The feed mechanism is provided with automatic overload release.

The predetermined depth of drilling is limited by dial stops which automatically trip the feed. The spindle rotation is reversed also by means of a dial stop.



All controls and levers are grouped within convenient reach from the operator's working position.

The machine is equipped with two motors.

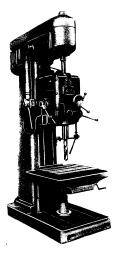
SPECIFICATIONS

Capacity Maximum drill diameter in steel of 50—60 kg/mm² tensile strength, mm Distance, end of spindle to table, mm: minimum	Speeds and Feeds Number of spindle speeds, r.p.m. 68—1100 Number of spindle speeds, r.p.m. 68—1100 Number of spindle feeds, mm per revolution 11 Range of spindle feeds, mm per revolution 0.115—1.6
minimum 705 maximum 1130 Distance, center of spindle to column, mm 300	220/380 volt, 3 phase, 50 cycle A.C. motors: Spindle drive: power, kW 4.5 speed, r.p.m
Table	power, kW 0.1
Working surface of table, mm 450×500 Maximum vertical travel of table, mm 325	speed, r.p.m
Spindle Taper in spindle Morse No. 4 Maximum vertical spindle travel, mm 225 Vertical spindle head adjustment, mm 200	Floor space, mm



VERTICAL DRILLING MACHINE

MODEL 2A150



The 2A150 Vertical Drilling Machine is designed for drilling, boring, reaming, facing and tapping operations.

12 spindle speeds and 9 feeds are obtained through speed and feed gear boxes.

The automatic feed is engaged and disengaged by turning the hand-feed wheel. During the automatic feed the spindle can be fed manually. The feed mechanism is provided with automatic overload release.





The predetermined depth of drilling is limited by dial stops which automatically trip the feed. All controls and levers are grouped within convenient reach from the operator's working position.

Special attention has been paid to lubrication. All main parts of the machine are lubricated automatically. The machine is equipped with two motors.

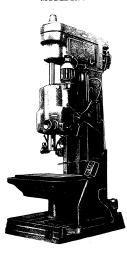
SPECIFICATIONS

Speeds and Feeds
Spindle drive: power, kW
power, kW
Floor space, mm



VERTICAL DRILLING MACHINE

MODEL 2170



The 2170 Vertical Drilling Machine is designed for drilling, boring, counterboring, reaming and facing operations.

12 spindle speeds and 9 spindle head feeds are obtained through speed and feed gear boxes. The spindle is mounted in a sliding head which moves together with the spindle along the column ways.

The working cycle of the machine is completely automatic. The automatic cycle consists of sliding head rapid traverse down (approach), feed and rapid return. The rapid down and up movements of the sliding head are





effected by a separate electric motor. The lengths of rapid traverse and feed are controlled by repositioning suitable depth stops. The machine is equipped with three motors.

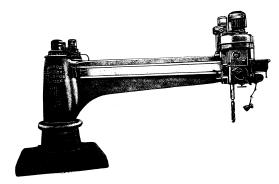
SPECIFICATIONS

Capacity Maximum drill diameter in steel of 50—60 kg/mm² tensile strength, mm 75	Number of sliding head feeds
Distance, center of spindle to column, mm	power, kW
Table and Base	Rapid sliding head traverse: power, kW
Working surface of table, mm 600×750 Maximum vertical travel of table, mm 350 Working surface of base, mm 680×720	speed, r.p.m
Spindle and Sliding Head	speed, r.p.m 3000
Taper in spindle Morse No.6 Maximum travel of sliding head, mm 500	Space Occupied Floor space, mm
Speeds and Feeds	Height of machine, mm
Number of spindle speeds 12 Range of spindle speeds, r.p.m 22—1018	Weight Net weight kg approx 3600



RADIAL DRILLING MACHINE

MODEL 2Г53



The 2F53 Radial Drilling Machine is designed for drilling a great number of holes in metal sheets and in structural shapes as well as for tapping these holes.

19 different spindle speeds and 18 spindle feeds are obtained through speed and feed gear boxes.

The spindle has both forward and reverse motions.

The spindle feed can be operated either by power or manually.

The traverse of the spindle head along the arm, clamping the spindle head and the swing of the arm around the column axis are accomplished manually.

nead and the swing of the arm on the column is obtained by manually.

The locking and unlocking of the arm on the column is obtained by hydraulic means.

The machine is equipped with three motors.

The modern design of the machine, its rigidity, high spindle speeds, together with the wide range of speeds and feeds provide for the effective application of the machine in boiler and metal structure works.





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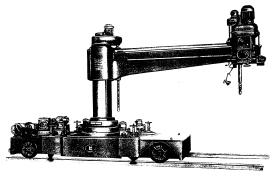
SPECIFICATIONS

Capacity Maximum drill diameter in mild steel, mm	Range of spindle speeds, r.p.m
minimum	220/380 volt, 3 phase, 50 cycle A.C. motors:
Distance, end of spindle to floor, mm: minimum	Spindle drive:
Spindle and Spindle Head	power, kW 0.6
Taper in spindle Morse No.5 Maximum vertical spindle travel (by power and manually), mm	speed, r.p.m. 1500 Coolant pump: 0.1 power, kW 0.1 speed, r.p.m. 3000
arm, mm	Space Occupied
Arm Maximum swing of arm 360°	Floor space, mm
Speeds and Feeds	Weight
Number of spindle speeds 19	Net weight, kg approx. 6000



TRAVELLING RADIAL DRILLING MACHINE

MODEL 2Д53



The 2Д53 Travelling Radial Drilling Machine has been designed for drilling, boring and reaming on large rivet joint and bridge girder assemblies. The machine is mounted on a rigid bogie, arranged on four wheels, which move along railway of standard gauge by means of a separate motor. While the machine is in operation the bogie is securely clamped on the rails by hydraulic means through separate electric motors.

19 different spindle speeds and 18 spindle feeds are obtained through speed and feed gear boxes. The spindle head to sperated either by power or manually.

The spindle head traverse and clamping on the arm are effected manually.

The elevating and lowering motion of the arm is operated by a separate motor. When starting the raising or lowering movements of the arm on the column the arm clamp is released automatically and when stopping these movements the arm is clamped automatically.

The swing of the arm around the column axis is accomplished manually.





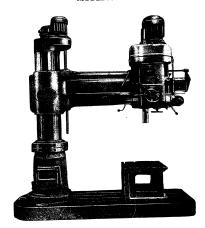
SPECIFICATIONS

SPECIFIC	ATIONS
Capacity Maximum drill diameter in mild steel, mm 35 Distance between spindle center and railway gauge center (radius of drillinol, mm:	Range of spindle speeds, r.p.m. 30—1700 Number of spindle feeds 18 Range of spindle feeds, mm per revolution 0.03—1.2 Arm traverse speed, m/min 0.75 Speed of bogle, m/min 10
minimum 1000	Drive
maximum 3400 Maximum distance, center of spindle to column, mm 3150 Distance, end of spindle to top of rail, minimum 900 maximum 2300 Distance between rail axes, mm 1592 Type of rail P 38/II-a according to	220/380 volt, 3 phase, 50 cycle A.C. motors: Spindle drive: power, kW speed, r.p.m. 1500 Arm traverse: power, kW power, kW 2,8 speed, r.p.m. 1500 Bogle travel: power, kW power, kW 1. speed, r.p.m. 1000
Spindle and Spindle Head	Hydraulic pumps (5 motors):
Taper in spindle Morse No. 5	speed, r.p.m
(by power and manually), mm 350 Maximum traverse of spindle head on arm, mm	Coolant pump: 0. power, kW
Arm	Space Occupied
Maximum vertical travel of arm, mm 1050 Maximum swing of arm	Floor space, mm
Speeds and Feeds	Weight
Number of spindle speeds 19	Net weight, kg approx. 1900



RADIAL DRILLING MACHINE

MODEL 255



The 255 Radial Drilling Machine is designed for drilling, boring, counterboring, reaming, facing and tapping operations.

19 different spindle speeds and 18 spindle feeds are obtained through speed and feed gear boxes.

The spindle has both forward and reverse motions, power feed and rapid hand traverse. The reverse of the spindle is effected through a multiple disc clutch or through a reversing motor.

The elevating and lowering motion of the arm is operated by a separate electric motor.

electric motor.

The locking and unlocking of the arm on the column and of the spindle head on the arm are obtained by hydraulic means. When starting the





raising or lowering movements of the arm on the column the arm clamp is released automatically and when stopping these movements the arm is clamped automatically. The traverse of the spindle head along the arm and the swing of the arm around the column axis are accomplished manually. All controls and levers are grouped on the spindle head within easy reach of the operator.

The machine is equipped with four motors.

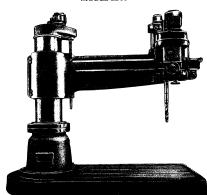
SPECIFICATIONS

Capacity	Range of spindle speeds, r.p.m. forward 30—1706 reverse 34—1706 Number of spindle feeds 18 Range of spindle feeds, mm per revolution 0.33—1.7 Drive 220/380 volt, 3 phase, 50 cycle A.C. motors: Spindle drive: Spindle drive: power, kW 4.6 speed, r.p.m 1500 Elevating and lowering arm motions: power, kW 0.0 Arm clamping: power, kW 0.0 speed, r.p.m 5500 Coolant pump: power, kW 0.0 speed, r.p.m 3000 Space Occupied
Maximum traverse of arm on column,	
mm	Floor space, mm
Speeds and Feeds	Weight
Number of spindle speeds 19	Net weight, kg approx. 4200



RADIAL DRILLING MACHINE

MODEL 2B55



The 2B55 Radial Drilling Machine is designed for drilling, boring, counterboring, reaming, facing and tapping operations.

19 different spindle speeds and 18 spindle feeds are obtained through speed and feed gear boxes.

The spindle has both forward and reverse motions, the reverse of the spindle being effected through either a driving clutch or reversing motor. The spindle feed is operated both by power and manually.

The elevating and lowering motion of the arm is operated by a separate electric motor.

The locking and unlocking of the arm on the column and of the spindle head on the arm are obtained by hydraulic means. When starting raising or lowering movements of the arm on the column the arm clamp is released automatically and when stopping these movements the arm is clamped automatically.





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The traverse of the spindle head along the arm and the swing of the arm around the column axis are accomplished manually.

All controls and levers are grouped on the spindle head within easy reach of the operator. The machine is equipped with four motors.

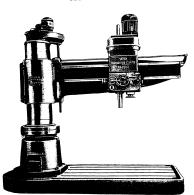
SPECIFICATIONS

Capacity Maximum drill diameter in mild steel, mm	Range of spindle speeds, r.p.m 30—1700 Number of spindle feeds 18 Range of spindle feeds, mm per revolution
mm: minimum 500	Drive
maximum	220/380 volt, 3 phase, 50 cycle A.C. motors:
Distance, end of spindle to table, mm:	Spindle drive:
minimum	power, kW
maximum	speed, r.p.m
minimum 700	power, kW 2.8
maximum	speed, r.p.m 1500
Working surface of base, mm 1300×2065	Arm and spindle head clamping:
Spindle and Spindle Head Taper in spindle	power, kW
Maximum vertical spindle travel, mm 359 Maximum traverse of spindle head on arm, mm	power, kŴ
Arm	Space Occupied
Maximum traverse of arm on column, mm	Floor space, mm
Speeds and Feeds	Weight
Number of spindle speeds 19	Net weight, kg approx. 960



RADIAL DRILLING MACHINE

MODEL 257



The 257 Radial Drilling Machine is designed for drilling, boring, counterboring, reaming, facing and tapping operations.

22 different spindle speeds and 18 spindle feeds are obtained through speed and feed gear boxes. The spindle has both forward and reverse motions, the reverse of the spindle being effected through a driving clutch. The spindle feed is operated both by power and manually.

A hydraulic single lever pre-selecting speed and feed changing system gives rapid changes from any one speed or feed in the range to any other during the operation of the machine.

The elevating and lowering motion of the arm is operated by a separate electric motor.

The locking and unlocking of the arm on the column and of the spindle head on the arm are obtained by hydraulic means. When starting the raising or lowering movements of the arm on the column the arm clamp is released





automatically and when stopping these movements the arm is clamped

automatically.

The traverse of the spindle head along the arm and the swing of the arm around the column axis are accomplished manually.

The machine is equipped with four motors.

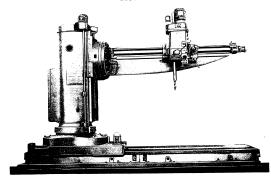
SPECIFICATIONS

Capacity Maximum drill diameter in mild steel, mm 75 Distance, center of spindle to column, mm 75 75 75 75 75 75 75	Range of spindle speeds, r.p.m. 11.2—1400 Number of spindle feeds 18 Range of spindle feeds 19 Drive 220/380 volt, 3 phase, 50 cycle A.C. motors: Spindle drive: power, k. m 1500 Elevating and lowering arm motions: power, k.W 1500 Arm and spindle head clamping: power, k.W 0.6 speed, r.p.m 1500
Maximum vertical spindle travel, mm 450 Maximum traverse of spindle head on arm, mm	Coolant pump: 0.1 power, kW. 0.1 speed, r.p.m. 3000
Arm	Space Occupied
Maximum traverse of arm on column, mm	Floor space, mm
Speeds and Feeds	Weight
Number of spindle speeds 22	Not woight by seems 10000



UNIVERSAL RADIAL DRILLING MACHINE

MODEL 2Π57



The 2II57 Universal Radial Drilling Machine has been designed for drilling, boring, reaming, tapping and spot facing on large or awkward work. Angular, vertical and horizontal holes of any casting or welded assemblies may be quickly and easily machined with the machine. For angular drilling both the arm and the spindle head can be swivelled in vertical planes.

The radial arm is of strong section and is accurately fitted to the column slides. The column base slides easily on the machine bed and can be rigidly locked in any position on the bed.

21 different spindle speeds and 18 spindle feeds are obtained through speed and feet gear boxes.

The spindle has both forward and reverse motions; the reverse of the spindle being effected through either a driving clutch or reversing motor. The spindle feed can be operated either by power or manually. The spindle head can be traversed along the arm both by power and manually.

All the locking, unlocking and traverse movements of the machine are operated by power; unclamping, swiveling and clamping of spindle head,





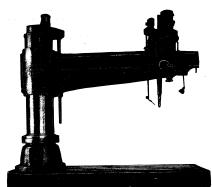
as well as clamping and unclamping of arm when swiveling are accomplished manually. The machine is equipped with nine motors.

SPECIFICATIONS		
Capacity Maximum drill diameter in mild steel, mm 75	200/380 volt, 3 phase, 50 cycle A.C. motors: Spindle drive:	
Maximum swing of arm 360°	Space Occupied Floor space, mm	
Range of spindle feeds, mm per revolution 0.1—2.12	Net weight, kg approx. 3500	



RADIAL DRILLING MACHINE

MODEL 258



The 258 Radial Drilling Machine is designed for drilling, boring, counterboring, reaming, facing and tapping operations.
21 spindle speeds and 18 spindle feeds are obtained through speed and feed gear boxes.
The spindle has both forward and reverse motions, the reverse of the spindle being effected through either a driving clutch or reversing motor. The spindle feed is operated both by power and manually.
The elevating and lowering motion of the arm is operated by a separate electric motor.
The locking and unlocking of the arm on the column and of the spindle head on the arm are obtained by hydraulic means. When starting the raising or lowering movements of the arm on the column the arm clamp is released automatically and when stopping these movements the arm is clamped automatically.
The spindle head is traversed along the arm by either a hydraulic motor or manually.





The swing of the arm around the column is accomplished manually. The machine is equipped with five motors.

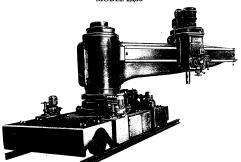
SPECIFICATIONS

DI MONTO	
Capacity Maximum drill diameter in mild steel, mm	Number of spindle feeds 18 Range of spindle feeds, mm per revolution 0.1—2.12
Distance, center of spindle to column,	Drive
mm: 500 maximum 3000 maximum 3000 Distance, end of spindle to table, mm: minimum 150 maximum 2000 Distance, end of spindle to base, mm: minimum 750 minimum 2000 Working surface of base, mm 1480×3175	220/380 volt, 3 phase, 50 cycle A.C. motors: Spindle drive: power, kW
Spindle and Spindle Head	speed, r.p.m
Taper in spindle	power, kW 0.6
	C C
Maximum traverse of arm on column, mm 1350 Maximum swing of arm 360°	Space Occupied Floor space, mm
Speeds and Feeds	707 1 1 1
Number of spindle speeds	Weight Not weight by approx 20000



TRAVELLING RADIAL DRILLING MACHINE

MODEL 2Д58



The 2Д58 Travelling Radial Drilling Machine has been designed for drilling, boring, reaming, tapping and spot facing on large or awkward

drilling, boring, reaming, tapping and spot facing on large or awkward work.

The machine is mounted on a rigid bogie, arranged on four wheels, which move along railway of standard gauge by means of a separate motor.

21 different spindle speeds and 18 spindle feeds are obtained through speed and feed gear boxes. The spindle has both forward and reverse motions, the reverse of the spindle being effected through either a driving clutch or reversing motor. The spindle feed can be operated either by power or manually.

The spindle head is traversed along the arm both by power and by hand. The arm is of strong section and can be swung radially through a complete circle.

Clamping of spindle head on arm, locking of outer column on inner one and bogie on rails are obtained by hydraulic means through separate electric motors.

The machine is equipped with nine motors.





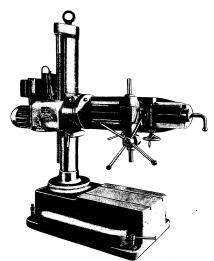
SPECIFICATIONS

SPECIFICATIONS		
Capacity Maximum drill diameter in mild steel, mm	Range of spindle speeds, r.p.m. 9—1000 Number of spindle feeds 18 Range of spindle feeds mm per revolution 0.1—2.12 Speed of bogie, m/min 10 10	
of drilling), mm:	Drive	
minimum	220/380 volt, 3 phase, 50 cycle A.C. motors: Spinlde trives 14 speet r.p.m. 1500 Bogle travel: power, kW 1.7 speed, r.p.m. 1000 Hydraulic pumps (6 motors):	
Spindle and Spindle Head	power, kW 0.6 speed, r.p.m	
Taper in spindle Morse No. 6 Maximum vertical travel of spindle (by power and manually), mm 500 Maximum traverse of spindle head on	speed, r.p.m. 1990 Coolant pump: power, kW 0.1 speed, r.p.m. 3000	
arm, mm	Space Occupied	
Arm Maximum swing of arm	Floor space, mm	
Number of spindle speeds 21	Net weight, kg approx. 25000	



PORTABLE RADIAL DRILLING MACHINE

MODEL 2A592



The 2A592 Radial Drilling Machine is designed for drilling holes on large or awkward work, where it is inconvenient or difficult to take the work to a machine.

The machine can be readily moved from one portion of the work to another, either by crane or on its own wheels.





Spindle head is of compact design and can be adjusted in vertical plane to any angle. It can be easily traversed along arm by means of hand wheel. Radial arm is accurately fitted to column slide and can be swung radially through a complete circle as well as swivelled in vertical plane to any angle.

The arm can be elevated or lowered by means of screw and nut mechanism.

Secure lock to all motions is provided.

SPECIFICATIONS

Capacity	Arm
Maximum drill diameter in mild steel, mm	Maximum arm travel, mm 840 Maximum swing of arm 360° Maximum swivel of arm 360°
spindle center line to column, mm	Speeds Spindle speeds, r.p.m 175; 432; 693; 980
Minimum and maximum distance from face of spindle to base, mm 25—870 Working surface of base, mm 450×590 Spindle	Drive 220/380 volt, 3 phase, 50 cycle A.C. motor: power, kW
Taper in spindle Morse No. 2	Space Occupied
Maximum spindle travel (by hand), mm	Floor space, mm
Maximum spindle head travel (by hand), mm	Weight
Maximum spindle head swivel 360°	Net weight, kg approx. 780



JIG BORING MACHINE

MODEL 2420



The 2420 Jig Boring Machine has been designed for drilling and boring holes in jigs, fixtures, dies, gauges or other special tooling where a high degree of accuracy on center distances between the holes is reguired.

The machine had built into it every necessary device and control to give it extrime accuracy and speed of operation.

For locating purposes the machine comprises a table movable in the longitudinal direction. This table is mounted on a saddle movable transversely. Both the table and saddle movements can be accomplished either manually or by power.

The vertical spindle head traverse is effected manually. The machine is driven by three speed A.C. motor.





SPECIFICATIONS

Maximum diameter of hole bored, mm Distance, center of spindle to column, mm Distance, end of spindle to table, mm: minimum	10 40 25	Accuracy of table and saddle locations, mm: dial reading 0.01 vernier reading 0.001 Speeds and Feeds Number of spindle speeds 6 Range of spindle speeds, r.p.m. 140—3200 Number of spindle feeds 3 Range of spindle feeds, mm per revolution 0.03—0.12
Taper in spindle Morse No. Maximum vertical travel of spindle (by power and manually), mm 1 Maximum vertical travel of spindle	. 1 00 80	Drive 220/380 volt, 3 phase, 50 cycle A.C. motor (3-speed): power, kW
Maximum cross travel of saddle (by	:00 :20 :60	Space Occupied Floor space, mm 1015×1125 Height of machine, mm 1675 Weight Net weight, kg approx. 830



JIG BORING MACHINE

MODEL 2430



The 2430 Jig Boring Machine is designed for drilling and boring holes in work pieces where accurate relative location of holes should be observed. It is efficiently used for the production of highly accurate instruments, fixtures and dies.

The machine is of the single column type, the spindle head being traversed vertically, while the rectangular table traverses in longitudinal and cross directions.

Indexing tables are furnished with the machine as a separate attachments.

Measurements of the longitudinal and cross movements of the table are effected by means of dials and a counting mechanism with pre-selective setting which can be arranged during boring.





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The table stops automatically in the preliminary determined position by means of an inductive pick-up unit.

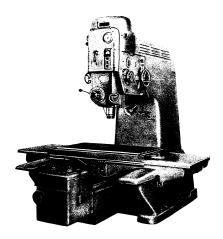
SPECIFICATIONS

Capacity Working surface of table, mm 560×280 Maximum table traverse, mm: longitudinal	Range of spindle speeds, r.p.m 145—2900 Number of spindle feeds 6 Range of spindle feeds, mm per revolu- tion of spindle 0.025—0.25
cross 250	Drive
Distance, spindle axis to column, mm 310 Minimum and maximum distance from	Power of electric motor, kW 0.7/1.7/2
spindle nose to table surface,	Space Occupied
mm	Floor space, mm 1460×1500
Taper in spindle Morse No. 2	Height of machine, mm 2060
Speeds and Feeds	Weight
Number of spindle speeds 6	Net weight, kg approx. 2300



JIG BORING MACHINE

MODEL 2450



The 2450 Jig Boring Machine has been designed for drilling and boring holes in jigs, fixtures, dies, gauges or other special tooling where a high degree of accuracy on center distances between the holes is required. Finish milling operations can be performed in this machine as well. The machine has built into it every necessary device and control to give it extreme accuracy and speed of operation.

One of the outstanding features of this machine is its micro-optical measuring device. This arrangement gives the following advantages:

The table locations are done with the highest precision;





The moving parts of table and saddle are free from any measuring functions and therefore do not influence on the measuring accuracy of the machine;

The measuring parts of the device are not subjected to any mechanical strain and retain their accuracy during the entire life of the machine. For locating purposes the machine comprises a table movable in the longitudinal direction. This table is mounted on a saddle movable transversely. Both the table and saddle movements can be accomplished either manually or by power.

The spindle is driven by a D.C. variable speed motor through a speed gear box.

gear box.

Both the spindle speed and feed are stepless variable.

The vertical spindle head traverse is effected manually.

The machine is equipped with four motors. The D.C. motors are fed from a motor-generator set.

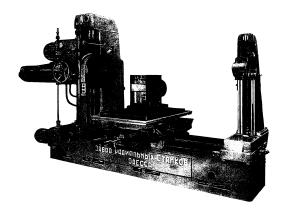
SPECIFICATIONS

	variable), r.p.m
Capacity Maximum drill diameter in mild steel, mm Maximum diameter of hole bored, mm Distance, center of spindle to column, mm Oblistance, end of spindle to table, mm: minimum 250	Variable), rp.lin Range of spindle feeds (stepless variable), mm per revolution 0.03—0.16 Milling feed of table and saddle, mm/min. 36 Speed of rapid movement of table and saddle, mm/min. 1006 Drive
Maximum	D.C.motors: Spindle drive: power, kW
Spindle and Spindle Head	speed, r.p.m
Taper in spindle special Maximum vertical travel of spindle (by power and manually), mm 250 Maximum vertical travel of spindle head, mm 250	Table and saddle traverse: 0.4: power, kW 0.4: speed, r.p.m. 200 220/380 volt, 3 phase, 50 cycle A.C. motors: Generator set:
Table and Saddle	power, kW
Working surface of table, mm	speed, r.p.m. 130 Coolant pump: power, kW 0.12 speed, r.p.m. 300
Accuracy of table and saddle loca-	Space Occupied
tions, mm: dial reading 0.01 vernier reading 0.001	Floor space, mm
Speeds and Feeds	Weight
Range of spindle speeds (stepless	Net weight, kg approx. 556



HORIZONTAL BORING, DRILLING AND MILLING MACHINE

MODEL 2613



The 2613 Table Type Horizontal Boring, Drilling and Milling Machine has been designed to meet the speed, rigidity and accuracy demanded of the present-day machine tool. The machine can be advantageously applied for drilling, boring, core drilling and reaming holes on work pieces with close tolerances on center distances between holes. Milling and tapping (without changing pick-off gears) operations can be performed in this machine as well.

The machine is of the universal type and has a face plate with a slide moving radially on it. The spindle and face plate have different speeds and are driven by a motor through a speed gear box. Axial feeds of spindle,





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radial feeds of face plate slide, vertical feeds of headstock and cross and longitudinal feeds of table are effected through a feed box.

Rapid traverse of all movable parts is accomplished by a separate motor. Interlocking devices prevent any engagement which may lead to breakages.

When jig boring accurate locating of table and headstock is obtained by means of scales, stops, dial indicators and gauge blocks.

The rotary table can be freely rotated either by power or manually through any angle. A secure clamping is provided at each 90°.

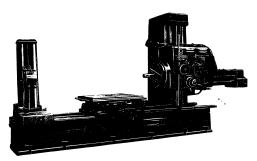
SPECIFICATIONS

Capacity Capacity	tical feeds of headstock and radial feeds of face plate silde (only spindle is revolving), mm per revolution 0.0125—1.5 Number of spindle, table, headstock and face plate slide feeds (spindle and face plate are revolving), mm per revolution 0.0125—12 Number of milling feeds 10 Number of Metric threads cut 14 Pitch of thread cut, mm minimum 0.5
Distance, spindle axis to table, mm: minimum	Speed of all rapid movements, m/min. 12 Drive
Speeds and Feeds Number of spindle speeds (face plate disengaged)	220/380 volt. 3 phase, 50 cycle A.C. motors: Main drive.
Range of longitudinal and cross feeds	Net weight, kg approx. 5900



HORIZONTAL BORING, DRILLING AND MILLING MACHINE

МОДЕТ. 262Г



The 262\(\triangleta\) Table Type Horizontal Boring, Drilling and Milling Machine has been designed to meet the speed, rigidity and accuracy demanded of the present-day machine tool. The machine can be advantageously applied for drilling, boring, core drilling and reaming holes on large cumbersome work pieces with close tolerances on center distances between holes. Milling with shell or face milling cutters, facing and tapping operations can be performed in this machine as well.

The machine is of the universal type and has a face plate with a slide moving radially on it. The spindle and face plate have different speeds and are driven by a two-speed motor through a speed gear box. Axial feeds of spindle, radial feeds of face plate slide, vertical feeds of headstock and cross and longitudinal feeds of table are effected through a feed box. A wide range of speeds and feeds is provided. The machine has a single lever control of speeds and a single lever control of speeds and as single lever control of reeds. Any speed and feed may be selected and obtained without stopping the machine.

Rapid traverse of all movable parts is accomplished by a separate motor. Single lever control of all rapid traverse motions is provided. Interlocking devices prevent any engagement which may lead to breakages.



A special design of clamping devices and ways eliminates backlashes and provides secure and accurate clamping of table and headstock when jig boring. Accurate locating of table and headstock is obtained by means of scales, stops, dial indicators and gauge blocks.

The built-in rotary table is mounted on balls and can be freely rotated by hand through any angle. A secure clamping is provided at each 90°.

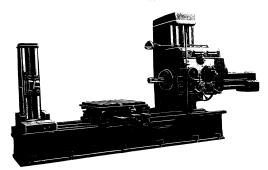
SPECIFICATIONS

Capacity B5	Range of spindle feeds, mm per revolution of spindle 0.05—16 Range of table and headstock feeds, mm per revolution of spindle 0.025—8 Range of table and headstock feeds, mm per revolution of face plate 0.05—16 Range of face plate slide feeds, mm per revolution of face plate 0.025—8
Working surface of table, mm . 1000×800 Maximum travel of table (by power and manually), mm: longitudinal	Speed of rapid axial movement of spindle, m/min
Headstock	Speed of rapid movement of face plate slide, m/min 1.2
Face plate diameter, mm	Drive
slide, mm	220/380 volt, 3 phase, 50 cycle A.C. motors: Main drive (two-speed):
minimum	power, kW
Speeds and Feeds Number of spindle speeds	Rapid traverse: 2.8 power, kW
Range of spindle speeds, r.p.m. 20—1000 Number of face plate speeds 15	speed, r.p.m
Range of face plate speeds, r.p.m 10—200 Number of longitudinal and cross	Floor space, mm
feeds of table, axial feeds of spindle, vertical feeds of headstock	
	Weight



HORIZONTAL BORING, DRILLING AND MILLING MACHINE

MODEL 262Д



The 262Д Table Type Horizontal Boring, Drilling and Milling Machine has been designed to meeth the speed, rigidity and accuracy demanded of the present-day machine tool. The machine can be advantageously applied for drilling, boring, core drilling and reaming holes on large cumbersome work pieces with close tolerances on center distances between holes. Milling with shell or face milling cutters and tapping operations can be performed in this machine as well.

The machine is of rigid construction. When designing, special attention was paid to the complete elimination of any vibration that may occur in any part of the machine during cuts.

The spindle is driven by a two-speed motor through a speed gear box. Axial feeds of spindle, vertical feeds of headstock and cross and longitudinal feeds of table are effected through a feed box. A wide range of speeds and feeds is provided.

The machine has a single lever control of speeds and a single lever control of feeds. Any speed and feed may be selected and obtained without stopping the machine.





Rapid traverse of all movable parts is accomplished by a separate motor. Single lever control of all rapid traverse motions is provided. Interlocking devices prevent any engagement which may lead to breakages. When jig boring accurate locating of table and headstock is obtained by means of scales, stops, dial indicators and gauge blocks.

The built-in rotary table is mounted on balls and can be freely rotated by hand through any angle. A secure clamping is provided at each 90°.

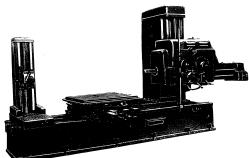
SPECIFICATIONS

Capacity	Range of spindle feeds, mm per re- volution of spindle 0.05-16
Diameter of spindle, mm	Range of table and headstock feeds, mm per revolution of spindle . 0.025—8 Speed of rapid axial movement of spindle, m/min 4.8 Speed of rapid longitudinal and cross
Table	movements of table and vertical
Working surface of table, mm 1000×800	movement of headstock, m/min 2.4
Maximum travel of table (by power	Drive
and manually), mm: longitudinal	220/380 volt, 3 phase, 50 cycle A.C. motors: Main drive (two-speed): power, kW
Headstock	speed, r.p.m
Distance, spindle axis to table, mm: minimum	Rapid traverse: power, kW
Speeds and Feeds	Space Occupied
Number of spindle speeds 18 Range of spindle speeds, r.p.m 20—1000 Number of longitudinal and cross feeds of table, axial feeds of spindle	Floor space, mm
and vertical feeds of headstock	Net weight, kg approx. 11350



HIGH SPEED HORIZONTAL BORING, DRILLING AND MILLING MACHINE

MODEL 2621



The 2621 Table Type High Speed Horizontal Boring, Drilling and Milling Machine has been designed to meet the speed, rigidity and accuracy demanded of the present-day machine tool. The machine can be advantageously applied for high speed drilling, boring, core drilling and reaming holes on large cumbersome work pieces with close tolerances on center distances between holes.

High speed milling with shell or face milling cutters and tapping operations can be performed in this machine as well.

The machine is of rigid construction. When designing, special attention was paid to the complete elimination of any vibration that may occur in any part of the machine during cuts.

The spindle is driven by a two-speed motor through a speed gear box. The maximum spindle speed is 2000 r.p.m. Axial feeds of spindle, vertical feeds of headstock and cross and longitudinal feeds of table are effected through a feed box. A wide range of speeds and feeds is provided.

The machine has a single lever control of speeds and a single lever control of feeds. Any speed and feed may be selected and obtained without stopping the machine.





Rapid traverse of all movable parts is accomplished by a separate motor. Single lever control of all rapid traverse motions is provided. Interlocking devices prevent any engagement which may lead to breakages. A special design of clamping devices and ways eliminates backlashes and provides secure and accurate clamping of table and headstock when jig boring. Accurate locating of table and headstock is obtained by means of scales, stops, dial indicators and gauge blocks.

The built-in rotary table is mounted on balls and can be freely rotated through any angle. A secure clamping is provided at each 90°.

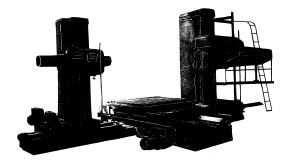
SPECIFICATIONS

Range of spindle feeds, mm per re- volution of spindle
Drive Driv
Space Occupied Floor space, mm 5070×2250 Height of machine, mm 2755 Weight Net weight, kg approx. 11600



HORIZONTAL BORING, DRILLING AND MILLING MACHINE

MODEL 2654



The 2654 Horizontal Boring, Drilling and Milling Machine is of the universal type and is provided with a built-in rotary table and a face plate with a slide moving radially on it. The machine is designed primarily for machining large and heavy work pieces weighing up to 8 tons and can be advantageously applied for boring, facing, drilling, counterboring and reaming holes on parts with close tolerances on center distances between holes.

reaming holes on parts with close tolerances on center distances between holes.

Face milling and tapping operations can be performed in this machine as well.

The machine incorporates a longitudinally moving column carrying on its vertical ways a headstock with boring spindle, a built-in face plate with radial slide, a built-in cross moving rotary table and a longitudinally moving bar support column with bearing block.

The table has no overhand over the ways in its extreme cross positions which considerably increases the accuracy of the machine when machining heavy work pieces.

The boring spindle and face plate are mounted on precision anti-friction bearings.





The nitrided spindle has high surface hardness. The spindle and the face plate are driven by an A.C. motor through a speed gear box. The design of the drive permits disengagement of the face plate rotation in the entire spindle speed range.

Speed changes are accomplished by a special mechanism arranged so as to prevent wear of slide gear teeth. Any speed may be selected without stopping the machine.

The feeds and set-up movements of column, headstock, spindle, face plate slide and table are effected by separate D.C. motors with a wide range of speed variation. The feed rate may be infinitely adjustable during the machine operation. Control of slow and rapid traverse set-up movements is obtained through a single lever and push-buttons.

An auxiliary hand wheel provides for fine axial adjustment of spindle. The built-in rotary table has a cross movement along its runway. Rapid table indexing is effected by an A.C. motor. Accurate indexing of table by hand is also provided. A built-in mechanism fitted with an indicator permits accuracy of indexing to be observed at every 90°.

Accurate locating of headstock and table is obtained by measuring rods with adjustable stops and an automatic electro-positive stop device.

This arrangement may, in some cases, be used instead of jigs.

The machine is provided with centralized clamping control of movable units. The automatic clamping of headstock and table on their ways is interlocked with the engagement and disengagement of the movable units and does not require the operator's assistance.

In order to increase the accurate performance of the machine clamping the headstock on the column ways is effected in two perpendicular planes.

All the machine movements are controlled from a centralized control station on the headstock and a duplicate portable station.

SPECIFICATIONS

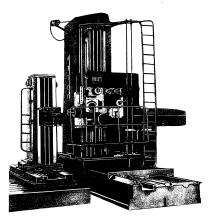
Capacity	Speeds and Feeds
Diameter of spindle, mm	80 Range of spindle speeds, r.p.m /.5—95 Number of face plate speeds
Face Plate	Range of feeds mm/min: Spindle 2—150
Diameter of face plate, mm	Headstock, column and table 1—75 Face plate slide 0.5—37
Table	Spindle 2.4—320
Working surface of table, mm: 180 length 180 width 150	Headstock, column and table 1.2—160 Face plate slide 0.6—800
Maximum cross travel of table, mm 160	220/380 volt, 3 phase, 50 cycle A.C. motor:
Headstock Distance, spindle axis to surface of table, mm:	Main drive: power, kW
minimum	Space Occupied
maximum	50 Floor space, mm
Headstock Column	Height of machine, mm
	Height of machine, mm

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HORIZONTAL BORING, DRILLING AND MILLING MACHINE

MODEL 265B



The 265B Floor Type Horizontal Boring, Drilling and Milling Machine has been designed to meet the accuracy, rigidity and speed demanded of the present-day machine tool. The machine can be advantageously applied for drilling, boring, core drilling and reaming holes on large and heavy work pieces with close tolerances on center distances between holes. Face milling operations can be performed in this machine as well.

The machine incorporates a cross movable column, carrying on its vertical ways a headstock with boring spindle and a stationary floor plate on which the work to be machined is fastened. A bar support column with bearing block is also mounted on the floor plate.



The machine has an extremely heavy 150 mm diameter spindle driven by a motor through a speed gear box.

Axial feeds of spindle, vertical feeds of headstock and horizontal feeds of headstock column are effected through a feed box.

Different pitches of threads cut are obtained by means of change gears. All the machine movements are controlled from a control station on the headstock and a pendant push-button station.

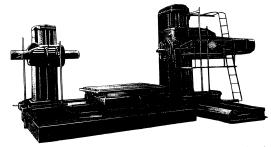
SPECIFICATIONS

Capacity Diameter of spindle, mm	Range of spindle feeds, mm per revolution of spindle 0.05—8.4 Range of milling feeds of headstock and headstock column, mm/min. 4.2—740
Floor Plate	Drive
Working surface of floor plate, mm 4000×6420	220/380 volt, 3 phass, 50 cycle A.C. motors: Main drive: 14
Headstock and Headstock Column	power, kW 3.2
Axial travel of spindle, mm 1350 Maximum vertical travel of headstock, mm 2000 Maximum travel of headstock column, mm 4800 Bar Support Column Maximum distance from end of spindle to bearing block of bar support	speed, r.p.m. 1500
Column, mm	speed, r.p.m. 1000
Speeds and Feeds	Space Occupied
Number of spindle speeds 16 Range of spindle speeds, r.p.m 3.35—600	Floor space, mm 9835×8000 Height of machine, mm 5720
Number of axial spindle feeds, ver-	Weight
tical headstock feeds and horizontal headstock column feeds	Net weight, kgapprox.63000



HORIZONTAL BORING, DRILLING AND MILLING MACHINE

MODEL 2657



The 2657 Floor Type Horizontal Boring, Drilling and Milling Machine is of the universal type and is provided with a stationary floor plate and a detachable rotary table. The Machine is designed primarily for machining large and heavy work pieces, regardless of their weight when placed upon the stationary floor plate, and of work pieces weighing up to 12 tons when being set on the detachable rotary table.

The machine can be advantageously applied for boring, facing, drilling, counterboring and reaming holes on parts with close tolerances on centre distances between holes.

Face milling and tapping operations can be performed in this machine as well.

The machine incorporates a cross movable column, carrying on its vertical ways a headstock with boring spindle, and a built-in face plate with a slide moving radially on it, a stationary floor plate, a detachable and longitudinally movable rotary table and an adjustable bar support column with a bearing block.

The boring spindle and face plate are mounted on precision anti-friction bearings.

bearings.
The nitrided boring spindle has high surface hardness. The spindle and the face plate are driven by an A.C. electric motor through a speed gear





box. The design of the drive permits disengagement of the face plate rotation in the entire range of the boring spindle speeds.

Speed changes are accomplished by a special mechanism arranged so as to prevent wear of slide gear teeth. Any speed may be selected without

stopping the machine.

The feeds and set-up movements of column, headstock, spindle, face plate slide and table are effected by seperate D.C. motors with a wide range of speed variation. The feed rate may be infinitely adjustable during the

machine operation.

Control of slow and rapid traverse set-up movements is obtained

machine operation.

Control of slow and rapid traverse set-up movements is obtained through a single lever and push-buttons.

An auxiliary hand wheel provides for fine axial adjustment of spindle. The detachable rotary table placed on the stationary floor plate can be traversed along its runway and indexed by a D.C. electric motor. An auxiliary easy indexing of table by hand is also provided. A built-in mechanism, fitted with an indicator, permits accuracy of indexing to be observed at every 90°. A circular scale provides for table index readings to any given angle.

Accurate locating of headstock and column is obtained by measuring rods with adjustable stops and an automatic electro-positive stop device. This arrangement may, in some cases, be used instead of jigs. An optical device ensures accurate alignment of spindle and bearing block of bar support column.

The machine is provided with centralized clamping control. The automatic clamping of headstock and column on their runways is interlocked with the engagement and disengagement of the movable units, and does not require the operator's assistance.

In order to increase the accurate performance of the machine clamping the headstock on the column ways is effected in two perpendicular planes.

All the machine movements are controlled from a centralized control station on the headstock and a duplicate portable station.

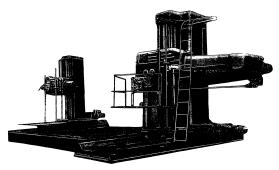
Capacity Diameter of spindle, mm 150 Taper in spindle Metric 80 Maximum axial travel of spindle, mm 1200 Face Plate Diameter of face plate Diameter of face plate nm 900 Maximum radial travel of face plate slide, mm 240	Range of spindle speeds, r.p.m. 7.5—950 Number of face plate speeds
Detachable Table	Spindle
Headstock Column Maximum cross travel of column, mm 3200 Speeds and Feeds Number of spindle speeds	Floor space, mm 10900×7200 Height of machine, mm

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HORIZONTAL BORING, DRILLING AND MILLING MACHINE

MODEL 2656



The 2656 Floor Type Horizontal Boring, Drilling and Milling Machine is designed primarily for machining large and heavy work pieces regardless of their weight.

The machine can be advantageously applied for boring, drilling, counterboring and reaming holes on work pieces with close tolerances on center distances between holes. Face milling and tapping operations can be performed in this machine as well.

The machine incorporates a cross movable column, carrying on its vertical ways a headstock with boring spindle, a stationary floor plate and a portable bar support column with a bearing block.

The machine has an extremely heavy 175 mm diameter nitrided boring spindle mounted on precision anti-friction bearings. The spindle is driven by an A.C. electric motor through a speed gear box.

Change of speeds is accomplished by means of a special mechanism, arranged so as to prevent wear of slide gear teeth. Any speed may be selected and obtained without stopping the machine.



The feeds and set-up movements of column, headstock and spindle are obtained through separate D.C. motors with a wide range of speed variation.

The feed rate may be infinitely adjustable during the machine operation.

The feed rate may be finance; descriptions of column, control of slow and rapid traverse set-up movements of column, headstock and spindle is effected by a single lever and push-buttons. An auxiliary hand wheel provides for fine axial adjustment of spindle. Accurate locating of headstock and column is obtained by end measuring rods with adjustable stops and an automatic electro-positive stop device.

stop device.

This device may, in some cases, be substituted for jigs. An optical reading device ensures accurate alignment of spindle and bearing block of

reading device ensures accurate alignment of spindle and bearing shock of bar support column.

The machine is provided with centralized clamping control. The automatic clamping of headstock and column on their runways is interlocked with the engagement and disengagement of the moving units and does not require the operator's assistance.

Clamping the headstock on the column ways is effected in two perpendicular planes thus improving the accuracy of the machine. All the machine movements are controlled from a centralized control station and a duplicate portable station.

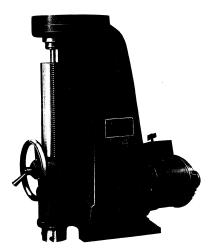
SPECIFICATIONS

Headstock Drive Distance, spindle axis to floor plate, 220/380 volt, 3 phase, 50 cycle	2.4—3200 1.2—1600
Distance, spindle axis to floor plate, 220/380 volt, 3 phase, 50 cycle	
Main drive: Main drive: Main drive: Main drive: Main maximum 2400 power, kW speed, r.p.m. Maximum travel of column, mm 3200 Space of speeds and Feeds Number of spindle speeds 22 Range of spindle speeds, r.p.m. 7.5—950 Range of fleeds, mmlmin 2—1500 Feedstock and column 1—750 Kg Weight Maximum Maximu	



PORTABLE BORING MACHINE FOR CYLINDER BLOCKS

MODEL 2685



This machine is designed for boring cylinder blocks in repair shops. When machining cylinder blocks, the machine is installed and bolted on the cylinder block.

The machine is driven from an individual electric motor.



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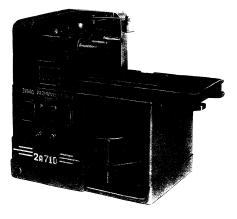
SPECIFICATIONS

Capacity Diameter that can be bored, mm: minimum maximum	80 120	Drive 220/380 volt, 3 phase, 50 cycle A.C. motor: power, kW 0.65 speed, r.p.m. 3000
mm	300	Space Occupied Floor space, mm 660×260 Height of machine, mm 705
Spindle speed, r.p.m	280 0.05	Weight Net weight, kg approx. 100



SINGLE END HORIZONTAL PRECISION BORING MACHINE

MODEL 2A710



The 2A710 Precision Boring Machine is designed for extremely accurate finish boring to size and alignment of bores with high grade surface finish. Depending on set-up one or several holes can be bored in one or two passes.

The operation cycle of the machine is semi-automatic.

The machine is supplied with fixtures by means of which clamping the work pieces, traverse, positioning, swiveling and other auxiliary operations are performed automatically.

When the machine is set up for wet boring a coolant system is supplied.





The number of spindle heads (of which there are five different types and sizes) depends upon the set-up.

The machine is equipped with two motors.

SPECIFICATIONS

Capacity	Speeds and recess Number of spindle speeds
Spindle Heads	Drive
Maximum number of heads set up on each bridge (depending upon their type and size)	380 volt, 3 phase, 50 cycle main drive A.C. motor power (depending on set-up), kW
Table	Hydraulic pump motor: power, kW1
Working surface of table, mm 400×600	speed, r.p.m 1000
Table travel, mm	Space Occupied
Distance from base of machine to working surface of table, mm 890 Distance from spindle axis to table surface (depending upon type and size of head), mm 230—270	Floor space, mm 1500×1000 Height of machine, mm 1350 Weight Net weight (without set-up), kg approx. 1900



DOUBLE END HORIZONTAL PRECISION BORING MACHINE

MODEL 2A715



The 2A715 Precision Boring Machine is designed for extremely accurate finish boring to size and alignment of opposed bores with high grade surface finish.

Depending on set-up one or several holes can be bored in one or two passes.

The operation cycle of the machine is semi-automatic.
The machine is supplied with fixtures by means of which clamping the work pieces, traverse, positioning, swiveling and other auxiliary operations are performed automatically.

When the machine is set up for wet boring a coolant system is supplied. The number of spindle heads (of which there are five different types and sizes) depends upon the set-up.

The machine is equipped with three motors.





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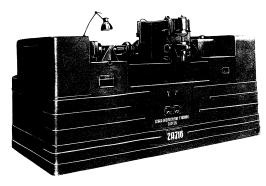
SPECIFICATIONS

Capacity	Speeds and Feeds Number of spindle speeds 1 Maximum spindle speed, r.p.m. 5000 Minimum feed of table (infinitely variable), mm/min. 10
Spindle Heads	Drive
Maximum number of heads set up on each bridge (depending upon their type and size)	380 volt, 3 phase, 50 cycle main drive motor power (depending on set-up), kW
Working surface of table, mm	speed, r.p.m. 1000 Space Occupied 1000 Floor space, mm 2015×1200 Height of machine, mm 1400 Weight Net weight (without set-up), kg approx. 3000
Distance from base of machine to working surface of table, mm 890 Distance from spindle axis to table	Floor space, mm



DOUBLE END HORIZONTAL PRECISION BORING MACHINE

MODEL 2A716



The 2A716 Precision Boring Machine is designed for extremely accurate finish boring to size and alignment of opposed bores with high grade surface finish.

The machine can be set up for boring either one or several holes in one or two passes.

The cycle of operations is semi-automatic. The machine is supplied with fixtures by means of which the clamping of work pieces, traverse, positioning, swiveling and other auxiliary operations are performed automatically.

When the machine is set up for work requiring cooling, a coolant pump is supplied.

The number of spindle heads (of which there are five different types and sizes) depends upon the set-up.

The machine is equipped with three electric motors.



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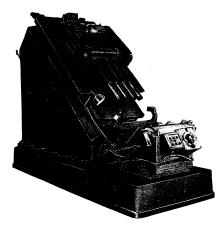
SPECIFICATIONS

Capacity	Speeds and Feeds
Diameter of hole that can be bored, mm: minimum 8	Number of spindle speeds
maximum 200	Minimum working feed of table (in- finitely variable), mm/min
Spindle Heads	Drive
Maximum number of heads set-up on each bridge (depending upon their type and size)	220/380 volt, 3 phase, 50 cycle main drive motor power (depending upon set-up), kW
Table	power, kW
Working surface of table, mm 600×800	speed, r.p.m 100
Table travel, mm 700	Space Occupied
Distance from base of machine to working surface of table, mm 925	Floor space, mm
Distance from axis of spindle to table (depending upon type and size of	Weight
head), mm	Net weight (without set-up), kg approx. 540



INCLINED MULTIPLE SPINDLE PRECISION BORING MACHINE

MODEL 2791



The 2791 Precision Boring Machine is designed and built to include the extreme accuracy required for finish boring by means of single-point tungsten carbide tools, which is known to industry as diamond boring or fine boring. The machine, when equipped with suitable fixtures, is especially applied for finish boring cylinder blocks of automatic engines. The inclined arrangement of the spindles assures a high accuracy of the machine owing to the close fit of the spindle slides to the machine ways. A better chip removal is secured by this arrangement as well.

—СТАНКОИМПОРТ

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The drive to the spindles is a smooth running spiral drive which permits spindle heads to be set at different spacings with a minimum of shut-down time for the machine. The spiral drive receives its power from two motors through V-belts.

The spindle feed is obtained by hydraulic means thus securing an infinite number of feeds.

The machine is equipped with a hydraulic fixture allowing work loading directly from the roll table, work inclination, then work locking and clamping.

The working cycle of the machine is completely automatic. The automatic cycle includes: tool approach, feed, starting and stopping spindle rotation, turning the spindles into withdrawal position, receding work from tools, and tool withdrawal without scoring the bores.

Work holding fixture, speed reducer and spindle heads are furnished as separate items to fit the requirements of the work.

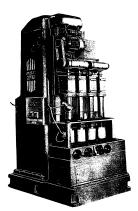
SPECIFICATIONS

Capacity Maximum diameter of holes bored, mm 200 Maximum travel of spindle slides, mm 450 Number of spindle heads according to set-up Number of tools in spindle head 1	Drive 220/380 volt, 3 phase, 50 cycle A.C. motors: Spindle heads (2 motors): power, kW
Speeds and Feeds	Floor space, mm
Spindle speed, r.p.m according to set-up Range of spindle feeds (infinitely variable), mm/min 0-300	Weight Net weight, kg approx. 12000



VERTICAL MULTIPLE SPINDLE PRECISION BORING MACHINE

MODEL 2792



The 2792 Precision Boring Machine is designed and built to include the extreme accuracy required for finish boring by means of single-point tungsten carbide tools, which is known to industry as diamond boring or fine boring. The machine, when equipped with suitable fixtures, is especially applied for finish boring cylinder sleeve liners, cylinder blocks and crank cases of automotive engines.

The drive to the spindles is a smooth running spiral drive which permits spindle heads to be set at different spacings with a minimum of shut-down time for the machine. The spiral drive receives its power from a motor through V-belts.

ЕСТАНКОИМПОРТ



The spindle feed is obtained by hydraulic means, thus securing an infinite number of feeds.

The working cycle of the machine is completely automatic. The automatic cycle includes: tool approach, feed, starting and stopping spindle rotation, and tool withdrawal without scoring the bores. Work holding fixture, speed reducer and spindle heads are furnished as separate items to fit the requirements of the work.

SPECIFICATIONS

Capacity		Spindle heads:	
Diameter of holes bored, mm:		power, kW	
	80	speed, r.p.m 1	500
	200	Hydraulic pump:	
Maximum travel of spindle slides, mm 4	150	power, kW	
Maximum number of spindle heads	4	speed, r.p.m 1	000
Number of tools in spindle head	1		
Speeds and Feeds		Space Occupied	
Spindle speed, r.p.m according to set- Range of spindle feeds (infinitely	•	Floor space, mm	
Spindle speed, r.p.m according to set-	•	Height of machine, mm	
Spindle speed, r.p.m according to set- Range of spindle feeds (infinitely	•		
Spindle speed, r.p.m according to set- Range of spindle feeds (infinitely variable), mm/min	300	Height of machine, mm	3550

VSESOJUZNOJE EXPORTNO-IMPORTNOJE OBJEDINENIJE "STANKOIMPORT"

EXPORTS AND IMPORTS:

Machine Tools

Woodworking Machinery

Metal Working Machinery (Presses, Hammers, Shears, Cold Forming Machines, Punching Machines)

Rolling Mills (imports)

Measuring Instruments and Apparatus (for metal industry)

Testing Machines and Instruments (for metals)

Optical Instruments and Equipment

Portable Electric and Pneumatic Tools (for metal and woodworking)

Metal and Wood Cutting Tools

Mechanic's Tools and Chucks Sintered Carbide and Hard-Alloy Products

Abrasive Products Ball and Roller Bearings

Microscopes of all types

Motion-Picture Equipment and Accessories

Geodetic Instruments and Equipment

Photographic Cameras Binoculars

Magnifiers

Lenses

Crude Optical Glass Blocks and Blanks

Design and specifications of the machine tools illustrated herein are subject to change without notice.

Vneshtorgizdat. Order No. 155



СТАНКОИМПОРТ

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CROSS-COUNTRY CAR ΓΑ3-69

OPERATION MANUAL



VSESOJUZNOJE OBJEDINENIJE
"T E C H N O P R O M I M P O R T"

CROSS-COUNTRY CAR ΓΑ3-69

OPERATION MANUAL





VSESOJUZNOJE OBJEDINENIJE
"'T E C H N O P R O M I M P O R T"

Moscow

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CAUTION

While operating the $\Gamma A3-69$ Automobile observe the following

rules:

1. Follow the maintenance recommendations outlined in this Manual.



Fig. 1.

- Fig. 1.

 2. Use gasoline of not less than 66 octane number and oils of such grades as recommended in the Lubrication Instructions.

 3. Regularly change the fine oil filter element.

 4. Change engine crankcase oil at regular intervals. Do not work the engine with insufficient oil in the crankcase.

 5. Drain the cooling system through two cocks, simultaneously opening the radiator cap and heater cock.

 6. Maintain the temperature of cooling water within the range of 8° to 90° C. In winter use a warm cover on the engine hood. Do not work the engine with insufficient water in the radiator.

 7. Check frequently the opening of the carburettor main jet needle. The needle should be turned off 1½ or 2 turns.

 8. The limiter throttle washer installed at the Manufacturer's Works between the carburettor and inlet manifold should be removed only after completion of running-in. In the lower rear part of the inlet pipe there is a plug for draining excess gasoline accumulating due to overchoking.
- choking.

 9. Enrichment of mixture by means of the choke button should be used with discretion, when starting a cold engine only.

Vneshtorgizdat. Order No. 0359/1077

10. Never race the engine and do not start the automobile with the engine insufficiently warmed up.

11. Fill the hydraulic brake system with a special brake fluid only. Never use the hand brake while the automobile is in motion. The hand brake is intended for parking only.

12. Engage the front driving axle for driving over difficult roads only.

12. Engage the front uriving and it.

13. Adjust in due time all assemblies and mechanisms of the automobile. Do not use the automobile with an excessive play in the clutch pedal and brake pedal and backlash in the steering gear.

14. Before putting a new automobile into service it should be run-in in conformity with instructions contained in this Manual.

SPECIFICATIONS

GENERAL DATA

Model	FA3-69, FA3-69A cross-country automobile with two driving axles
Load-carrying capacity: FA3-69	8 passengers or 2 passengers and 500 kg of load
ΓΑ3-69A	5 passengers and 50 kg of load 800
Overall dimensions, mm:	
length	3,850
ΓΑ3-69	1,850 1,750
height	
	2,030 1,920
Wheelbase, mm. Tread (front and rear wheels), mm. Ground clearance, mm. Turning radius, m.	2,300 1,440 210 6
Weight of automobile, kg: FA3-69 FA3-69A Maximum road speed, km/hr	1,525 1,535 90
Climbing ability on solid soil:	
with 800 kg trailer	30° 20° 66 octane number
the state of the s	
	ENGINE
Number of cylinders	four-stroke cycle gasoline engine 4 82 100
	· · · · · · · · · · · · · · · · · · ·

Displacement, litres				2.12
Compression ratio				6.5
Horsepower at 3600 r.p.m.				55
Maximum torque, kg.m				12.7
Firing order				1-2-4-3
Engine mounting			٠	floating, on three points
Cylinder head				of aluminium alloy of cast iron with short liners of anti-corrosion
Cylinders		•	•	cast iron with short liners of anti-corrosion
Pistons				of aluminium with two compression rings and two oil control rings
Crankshaft				of steel with counter-weights, on four bearings
C				symmetrical
Connecting rods	•	•	•	thin-walled, bimetallic type
Bearing shells		•		of steel, Forced lubrication
Camsuart		•	•	of journals. Driven by a pair of gears
Valves				Valve head diameter, mm:
				Inlet — 39 Exhaust — 36
Valve lifters				disc type with adjusting bolts
Valve data				
(0.35 mm clearance)				Inlet Valve:
(0.55 mm clearance)	•	•		opens — 9° hefore TDC
				opens — 9° before TDC closes — 51° past BDC
				Exhaust Valve:
				opens - 47° before BDC
				closes - 13° past TDC
T-1-4				on R. H. side of engine. In the center there
Inlet manifold		•	•	is a mixture heating chamber with automati-
•				cally controlled throttle valves
Lubricating system				combination forced and splash type
Oil suction bell	•		٠	floating type
Oil filters		:	:	two: coarse oil filter of plate type and fine
On inters		•		oil filter with replaceable filter element
Oil cooler				tubular type Operated by a cock located
Oil cooler				tubular type. Operated by a cock located
			•	near oil pump
Crankcase ventilation				near oil pump forced type
	:	:		near oil pump forced type relief valve located in oil pump cover.
Crankcase ventilation Lubricating system valves .		:		near oil pump forced type relief valve located in oil pump cover. Bypass valve in coarse oil filter body
Crankcase ventilation	:	:	:	near oil pump forced type relief valve located in oil pump cover. Bypass valve in coarse oil filter body mounted on L.H. side of frame.
Crankcase ventilation Lubricating system valves . Gasoline sediment bowl	:	:	:	near oil pump forced type relief valve located in oil pump cover. Bypass valve in coarse oil filter body mounted on L.H. side of frame. Diaphragm type with inverted sediment
Crankcase ventilation Lubricating system valves . Gasoline sediment bowl Fuel pump	:			near oil pimp forced type relief valve located in oil pump cover. Bypass valve in carse oil filter body mounted on L.H. side of frame. Diaphragm type with inverted sediment bowl. Equiponed with a manual fuel lift device
Crankcase ventilation Lubricating system valves . Gasoline sediment bowl				near oil pump forced type relief valve bocated in oil pump cover. Bypass valve in coarse oil filter body mounted on L.H. side of frame. Diaphragm type with inverted sediment bowl. Equipped with a manual fuel lift device K-22I type with adjusting needle
Crankcase ventilation				near oil pimp forced type relief valve located in oil pump cover. Bypass valve in carse oil filter body mounted on L.H. side of frame. Diaphragm type with inverted sediment bowl. Equiponed with a manual fuel lift device
Crankcase ventilation				near oil pimp forced type relief valve located in oil pump cover. Bypass valve in coarse oil filter body mounted on L.H. side of frame. Diaphragm type with inverted sediment bowl. Equipped with a manual fuel lift device K-22LI type with adjusting needle screen type with oil cup forced water circulation willed-tubes in three rows
Crankcase ventilation				near oil pump forced type relief valve bocated in oil pump cover. Bypass valve in coarse oil filter body mounted on L.H. side of frame. Diaphragm type with inverted sediment bowl. Equipped with a manual fuel lift device K-22I, type with adjusting needle screen type with oil cup forced water circulation gilled-tubes in three rows air-tight, equipped with two valves
Crankcase ventilation . Lubricating system valves . Gasoline sediment bowl . Fuel pump Carburettor Air cleaner				near oil pimp forced type relief valve located in oil pump cover. Bypass valve in coarse oil filter body mounted on L.H. side of frame. Diaphragm type with inverted sediment bowl. Equipped with a manual fuel lift device K-22LI type with adjusting needle screen type with oil cup forced water circulation gilled-tubes in three rows air-tight, equipped with two valves installed in front of radiator. Controlled
Crankcase ventilation . Lubricating system valves . Gasoline sediment bowl . Fuel pump . Carburettor . Air cleaner . Cooling . Radiator . Radiator filler cap .				near oil pump forced type relief valve bocated in oil pump cover. Bypass valve in coarse oil filter body mounted on L.H. side of frame. Diaphragm type with inverted sediment bowl. Equipped with a manual fuel lift device K-22I, type with adjusting needle screen type with oil cup forced water circulation gilled-tubes in three rows air-tight, equipped with two valves
Crankcase ventilation . Lubricating system valves . Gasoline sediment bowl . Fuel pump . Carburettor . Air cleaner . Cooling . Radiator . Radiator filler cap .				near oil pump forced type relief valve located in oil pump cover. Bypass valve in coarse oil filter body mounted on L.H. side of frame. Diaphragm type with inverted sediment bowl. Equipped with a manual fuel lift device K-2221 type with adjusting needle screen type with oil cup forced water circulation gilled-tubes in three rows air-tipht, equipped with two valves installed in front of radiator. Controlled from driver's seat opens at 7°—83° C
Crankcase ventilation Lubricating system valves Gasoline sediment bowl Fuel pump Carburettor Air cleaner Cooling Radiator Radiator Radiator blind Radiator blind				near oil pimp forced type relief valve located in oil pump cover. Bypass valve in coarse oil filter body mounted on L.H. side of frame. Diaphragm type with inverted sediment bowl. Equipped with a manual fuel lift device K-22I type with adjusting needle screen type with oil cup forced water circulation gilled-tubes in three rows air-tight, equipped with two valves installed in front of radiator. Controlled from driver's seat opens at 7°—83° C centrifugal type with self-adjusting seal
Crankcase ventilation . Lubricating system valves . Gasoline sediment bowl . Fuel pump				near oil pump forced type relief valve located in oil pump cover. Bypass valve in coarse oil filter body mounted on L.H. side of frame. Diaphragm type with inverted sediment bowl. Equipped with a manual fuel lift device K-2221 type with adjusting needle screen type with oil cup forced water circulation gilled-tubes in three rows air-tipht, equipped with two valves installed in front of radiator. Controlled from driver's seat opens at 7°-88° C centrifuga' type with self-adjusting seal six-blade type, belt-driven from crankshaft
Crankcase ventilation Lubricating system valves Gasoline sediment bowl Fuel pump Carburettor Air cleaner Cooling Radiator Radiator Radiator blind Thermostat Water pump				near oil pump forced type relief valve bocated in oil pump cover. Bypass valve in coarse oil filter body mounted on L.H. side of frame. Diaphragm type with inverted sediment bowl. Equipped with a manual fuel lift device K-22Il type with adjusting needle screen type with oil cup forced water circulation gilled-tubes in three rows air-tight, equipped with two valves installed in front of radiator. Controlled from driver's seat opens at 7°—83° C centrifugad type with self-adjusting seal six-blade type, belt-driven from crankshaft mounted on engine L.H. side under the hood.
Crankcase ventilation . Lubricating system valves . Gasoline sediment bowl . Fuel pump				near oil pump forced type relief valve located in oil pump cover. Bypass valve in coarse oil filter body mounted on L.H. side of frame. Diaphragm type with inverted sediment bowl. Equipped with a manual fuel lift device K-2221 type with adjusting needle screen type with oil cup forced water circulation gilled-tubes in three rows air-tipht, equipped with two valves installed in front of radiator. Controlled from driver's seat opens at 7°-88° C centrifuga' type with self-adjusting seal six-blade type, belt-driven from crankshaft

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Clutch Transmission Overall ratios: 1 st gear 2 nd gear 3 rd gear Reverse Transfer Case	two-range gear box with three speeds for- ward and one reverse	· Constitution of the cons	Light switches	two head lamps with traffic and country light. Two side lamps, one spotlight, tail light with «Stop» and license lamps, inspection lamp, hood lamp, instrument panel light; two instrument lights two: I are lamp, and so the light lamp two: for inspection lamp and trailer lamp C56-B type, electric, vibration type heat fuse, button type in lighting circuit, ordinary fuses in horn, tail light and instrument light circuits single wire type (positive pole grounded to the frame) instrument cluster (speedometer with odometer, gasoline level gauge, oil pressure gauge, ammeter and water thermometer). Green telitale lamp showing excessively high tempera-
axles Differential Axle shafts Transmission of pushing and torque	bevel gear with two satellites full floating type	Notice with a state of the stat	BODY AND	ture in radiator; country light red indicator lamp. BODY EQUIPMENT
reaction	by springs		Body:	
	NING GEAR two front wheels, two rear wheels, one spare	St. co. Inc. of St. co.	ГАЗ-69	all-metal, two-door type with folding tail- board and removable canopy all-metal, four-door type with luggage com-
	wheel low pressure, 6.50 × 16". Tread with non-		Body equipment ,	partment and removable canopy canopy, electric screen wiper with two wiper
Front wheel angles	skid pattern camber 1°30'; king pin inclination 5° caster			blades, rear view mirror, two sun visors, two mats, hand strap, body heater and screen defroster
Suspension	3°; toe-in 1.5 to 3 mm four longitudinal semi-elliptical springs, four hydraulic piston type two-way shock absor- bers		Windscreen	adjustable in special frame two cushioned, removable, with cushioned backrests
STEF	RING GEAR		ГАЗ-69	two folding semi-cushioned seats located along body side boards
Type Steering wheel Steering rods Foot brakes	globoid worm with twin roller	î	Body heating and ventilation	one cushioned seat with cushioned backrest ventilation port in front of windscreen controlled from driver's seat. Air is heated by water heater by warm air from electric ventilator
	transfer case		CAPAC	ITIES, LITRES
	C EQUIPMENT	A A A A A A A A A A A A A A A A A A A		
Storage battery	F20 type, 12 V, 18 A, shunt-wound machine with current and voltage regulator and circuit breaker of PP20 type oCT-54 type, 12V, 54 A-h BI type, with additional resistor cut-in during engine starting regular starting P20 type with centrifugal and vacuumatic spark advance control and octane selector		rA3-89A Fuel tank Cooling system Lubricating system (incl. Air cleaner Transmission housing Transfer case housing Front and rear axle casit Steering gear case Shock absorbers (each) Hydraulic brakes	filters) 60 12 5.5 0.25 0.8 1.1 1.1 0.75 0.33 0.145 6.4

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SERVICE ADJUSTMENT DATA

Valve to valve lifter clearance, mm:	Engine warm
inlet valves	0.20 0.25
exhaust valves	38 to 45
Brake pedal play, mm	8 to 14 10 to 15
Normal fan belt sag, mm Breaker point gap, mm	0.35 to 0.45
Spark plug gap, mm	0.7 to 0.8 80 to 90°C
Normal temperature of cooling water Tyre pressure, kg/sq.cm:	
front wheels	2 2 2
Lubricating oil pressure, kg/sq.cm:	
at 45 km/hr , , at idle speed, minimum	2 to 4 0.5
at rule speed, minimum	0.0

Engine cold 0.23 0.28

CONTROLS AND INSTRUMENTS Arrangement of controls and instruments is shown in Figs. 2 and 3. Two windscreen wipers and wiper switch are installed in the upper part of the windscreen.

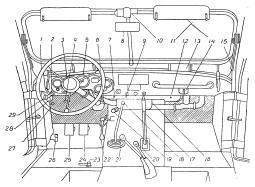


Fig. 2. Instruments and Controls

Located on the instrument panel are: instrument cluster consisting of the speedometer, ammeter, gasoline level gauge (main tank), thermometer for cylinder head cooling water, engine oil pressure gauge;

instrument illumination lamps, country beam indicator red lamp and green tell-tale lamp showing engine overheating.

The lighting master switch button has three positions: pressed all the way in — lighting is switched off; pulled halfway out — side lamps and tail light are on; pulled all the way out — head lamps and tail

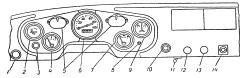


Fig. 3. Instrument Panel

1 — lighting master switch, 2 — gasoline level gauge, 3 — water temperature tell-tale lamp, 4 — oil pressure gauge, 5 — instrument light, 6 — speedometer, 7 — thernometer, 8 — country light indicator lamp, 9 — anmeter, 10 — ignition switch, 11 — instrument light switch, 12 — choke button, 13 — manual throttle control button, 14 — deforster switch.

light are on. Ignition switch is turned on by moving it clockwise. Choke knob pulling the knob out closes the choke. Manual throttle control to open throttle valve pull the button out. Defroster switch has three positions: middle — ventilator is switched on, — low speed of ventilator, right — high speed of ventilator. Cab lighting lamp.

Located on the lower edge of the instrument panel are: lighting lighting switch (operates with the master lighting switch turned ON only); cab lighting lamp switch.

Under the instrument panel there are: radiator blind control handle (to close — move back, to open — move forward); ventilation port door lever (to open — move back); inspection lamp socket; fuse block; spotlight switch.

spotlight switch

spotting switch.

Located on the floor are: lighting foot switch; clutch pedal; brake pedal; accelerator pedal; starter pedal; gear shift lever; front axle engagement lever; transfer case control lever; hand brake lever; three-way gasoline cock (FA3-69); steering column; horn button is mounted on steering column.

RUNNING-IN A NEW AUTOMOBILE

Service life of the automobile depends to a considerable extent on the care it receives at initial stages of operation, i. e. during running-in. When running in the automobile during the first 1000 km the following rules should be adhered to:

1. Do not drive the automobile at a speed of over 45 or 50 km/hr in high gear, 25 km/hr in 2nd gear and 15 km/hr in first gear.

Do not start the automobile with the engine insufficiently warmed up. Do not race the engine.
 Do not overload the automobile. Avoid driving over poor roads.
 When running in the automobile use a less viscous (winter) grade of oil.

grade of oil.

5. Check frequently the temperature of brake drums and adjust the brakes if necessary.

brakes it necessary.

6. Check frequently the temperature of wheel hubs and loosen the adjusting nut if the hubs are exceedingly heated.

7. Inspect all the attachments, tighten loose bolts and nuts.

8. Check carefully all piping for leaks and eliminate oil, water and brake fluid leaks.

BEFORE THE FIRST RUN

Check the water level in the radiator, oil level in the engine crankcase, electrolyte level in the storage battery, brake fluid level in the brake master cylinder, oil level in the air cleaner oil cup, tyre pressure, tightening of wheel nuts.

2. Check the oil level in the transmission housing, transfer case housing front and serve radia engine.

2. Check the on level in the damandson housing, trout and rear axle casings.

3. Lubricate all the points of the automobile that should be lubricated every 500 and 1000 km (see Lubrication Chart).

4. Start the engine and check all connections for oil, water and final leads. fuel leaks.

AFTER 500 KM RUN

Replace crankcase oil.
 Lubricate all the points of the automobile that should be lubricated every 500 and 1000 km (see Lubrication Chart).
 Tighten wheel nuts, steering arm nuts, universal joint nuts.

AFTER 1000 KM RUN (AT THE END OF RUNNING-IN)

1. Remove the seal and take out the limiter washer located between

the carburettor and inlet manifold flanges.

2. Tighten the cylinder head stud nuts in the sequence shown in Fig. 4. The nuts should be tightened on a cold engine.

3. Tighten the exhaust manifold to engine and exhaust manifold to

muffler attachments.

4. Tighten the generator bracket.5. Check fan belt tension and adjust if necessary.6. Check throttle valve and choke actuating parts and adjust if

7. Inspect and clean fuel pump sediment bowl.8. Adjust engine idle speed.9. Check the electrolyte level in the storage battery, add distilled water if necessary.

10. Tighten the terminals and coat them with vaseline.
11. Check condition and connections of electrical wiring.
12. Blow through the generator and starting motor with compressed air and inspect the commutator.

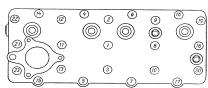


Fig. 4. Cylinder Head Stud Tightening Sequence

13. Adjust the play of the clutch and brake pedals.14. Check adjustment of foot and hand brakes.15. Check the fluid level in the brake master cylinder.16. Tighten rear axle shaft attachment nuts and front axle driving

16. Tighten rear axle shaft attachment nuts and none take flanges.

17. Tighten the attachments of the following parts: king pin plates, steering levers, transfer case brackets, front axle ball supports, spring clips, spring bolts, shock absorbers and all the other loose attachments.

18. Drain sediment from engine oil filters. Check operation of the coarse oil filter self-cleaner.

19. Change oil in engine crankcase, air cleaner, front and rear axle housings, transmission and transfer case housings.

20. Lubricate all the points that are to be lubricated after 500 and 1000 km (see Lubrication Chart).

21. During the following 3000 km do not drive the automobile continuously at a speed of over 70 km/hr and do not race the engine.

STARTING AND STOPPING THE ENGINE

Depending on temperature conditions the engine should be started as follows.

STARTING A WARM ENGINE

Turn the ignition switch on.
 Depress the starter pedal and keep it depressed until the engine fires, but not over 5 sec.
 If a warm and fully serviceable engine fails to start this may be caused by an exceedingly rich mixture due to choking or pumping of gasoline by the accelerator pedal.

To eliminate over-enrichment blow through the cylinders by smoothly depressing the accelerator pedal and crank the engine by the starting motor.

When starting a very hot engine it is recommended simultaneously with depressing the starter pedal to depress the accelerator pedal for scavenging the cylinders.

STARTING A COLD ENGINE AT A TEMPERATURE OVER -5° C

STARTING A COLD ENGINE AT A TEMPERATURE OVER —5° C

1. Prime the carburettor using the fuel pump hand lever.
2. Pull out the carburettor choke button as far as it will go.
3. Release the clutch, depressing the pedal all the way down.
4. Turn the ignition switch on.
5. Depress the starter pedal and keep it depressed not over 5 sec.
The intervals between each application of the starter should not be less than 10 or 15 sec.
6. As soon as the engine starts to fire under its own power, depress the choke button ½ of its travel and increase engine speed by the accelerator button or pedal.
An engine in good repair is usually started after first or second attempt. As the engine is warmed up, press the choke button in gradually.

attempt. As the engine is warmed up, press the choke button in gradually.

If the engine fails to start after three attempts it is necessary to scavenge the cylinders.

As a rule difficult starting of the engine with correct use of the choke is caused by the following:

1. No fuel supply to the carburettor.

No litel supply to the carburettor.
 Breaker point gap out of adjustment or breaker points burned.
 Faulty or soiled spark plugs.
 Faulty wiring.
 Start the automobile only after warming up the engine. To speed up warming close the radiator blind and hood cover flaps.

STARTING A COLD ENGINE AT LOW TEMPERATURES

To ensure prompt and reliable starting of the engine at low temperatures warm up the engine by the use of the starting heater or by filling the engine with hot water and oil.

To start the engine in cold weather the FA3-69 automobile is provided with a starting heater mounted under the hood on the L. H. side of the engine in the control of the contr

of the engine.

Prepare the automobile for starting in the following order:

1. Close the drain cock on the heater boiler and unscrew the boiler

1. Close the drain cock on the needs.

2. Light the starting heater torch (Fig. 5.) For this purpose screw in the torch tank plug, turn in the adjusting needle, make a few strokes with the pump, pour some gasoline into the burner cup and light up the gasoline. After 10 min open partly the adjusting needle and close the burner cap.

To facilitate placing of the torch into the heater boiler turn the
nt wheels of the automobile to the extreme right position.
 Remove the access hole cover on the left fender mudguard, re-

duce the torch flame and place the torch into the fire tube of the heater

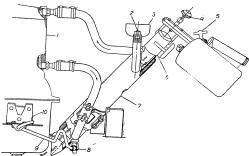


Fig. 5. Starting Heater

Cylinder block, 2 - boiler plug, 3 - funnel, 4 - heater torch adjusting needle,
 torch pump handle, 6 - torch burner, 7 - heater boiler, 8 - drain cock,
 g - drain cock
 g - drain cock pring.

5. Pour 4 liters of water into the heater boiler to the filter hole level, screw in the plug and increase the torch flame.
6. After 20 or 30 min, when the cylinder head is heated to 45 or 50° C, turn the crankshaft by the starting handle.
7. Remove the starting heater torch from the heater boiler and open partly the hood to ventilate the space under it.
8. Start the engine as described above.
9. As soon as the engine fires close the drain cock and fill the cooling system with water.
10. Put out the heater torch by unscrewing partly the torch tank filler plug.

filler plug.

STOPPING THE ENGINE

After working the automobile under a heavy load allow the engine to run at low idle speed for 2 min before stopping it.

The engine is stopped by turning the ignition switch off.
When the automobile is to be parked for a long time at a low temperature, drain water from the cooling system. The water is

drained through two cocks: one located on the radiator and the other — on the starting heater boiler. When draining the cooling system remove the radiator filler cap and open the heater cock on the

MAINTENANCE SCHEDULE

The life of the automobile will be extended in proportion to the attention paid to the regular maintenance and correct operation of the automobile. The Manufacturer recommends the following maintenance

DAILY MAINTENANCE

- 1. Check the fuel, water and oil levels and top up to the correct level.

- level.

 2. Check the fuel, water, oil and brake fluid leaks.

 3. Check the presence, good working order and reliability of fastening tools and equipment.

 4. Inspect and clean the storage battery, coat the terminals with vaseline and check attachment of cables. Clear ventilation holes.

 5. Check fan belt tension.

 6. Start the engine, listen to its operation noises, check functioning of the instruments.

 7. Check condition of springs and shock absorbers.

 8. Check tightening of the wheels. Inspect the tyres and check tyre pressure.
- Check connection of steering rods.
 Check service ability of the steering gear, brakes, horns and electric lighting.

1,000 KM MAINTENANCE

- 1. Check fan belt tension.
 2. Check functioning of the radiator cap valves.
 3. Drain sediment from the sediment bowl.
 4. Check connections of the electric wiring.
 5. Check electrolyte level in the storage battery and add distilled er if necessary.
 6. Check and adjust the play of the clutch and brake pedals.
 7. Check and adjust the foot brake.
 8. Check the level of the brake fluid in the brake master cylinder.
 9. Check attachments of the steering gear case, steering levers, ring arm, generator bracket. steering arm, generator bracket.

 10. Lubricate the automobile in accordance with Lubrication Chart.

3,000 KM MAINTENANCE

Perform operations listed in 1,000 km maintenance.
 Inspect the tyres. Interchange the wheels together with tyres.
 Adjust wheel toe-in.

6,000 KM MAINTENANCE

- Perform all operations listed in 3,000 km maintenance.
- Tighten the exhaust manifold and muffler attachments.
 Inspect fuel pump attachments, condition of the flexible hose check all connections for tightness.
 Drain sediment from the fuel tanks.
- 4. Drain sediment from the Tuel tanks.
 5. Clean the breaker points and adjust gap. Check ignition timing.
 6. Inspect the spark plugs and adjust spark plug gap.
 7. Tighten the generator bracket fastenings.
 8. Check functioning of the radiator cap valves.
 9. Check operation of the governor.
 10. Inspect condition of electric wiring.
 11. Inspect condition of generator and starter brushes and commutator. Blow out the generator and starter and clean their commutators.
- tators.

 12. Check horn attachment.
 13. Check head lamp adjustment.
 14. Remove the wheel hubs, clean the brakes and change lubricant in wheel hubs. Check and adjust backlash in the steering knuckle

- cant in wheel nuos. Check and adjust backlash in the steering knuckle and king pins.

 15. Tighten brake plate attachments. Adjust wheel bearings.

 16. Inspect condition of steering rod heads.

 17. Inspect condition of the shock absorbers, add fluid, if necessary.

 18. Remove and blow out the front axle and rear axle breathers, also the transfer case and transmission breathers.

 19. Inspect condition of the propeller shafts, their joints and convections.
- mections 20. Check and adjust the hand brake.
- 20. Check and adjust the hand brake.

 21. Check and adjust toe-in of the front wheels.

 22. Check condition of the spring rubber bushes.

 23. Remove the propeller shafts and tighten flange attachments, check and adjust the axial play in the bearings of the front axle and rear axle drive gears and in the bearings of the transfer case lower shaft.

 - Check fastening of the body parts.
 Lubricate the automobile in accordance with Lubrication Chart.

12,000 KM MAINTENANCE

- 1. Perform all operations listed in 6,000 km maintenance.
 2. Disassemble and clean the carburettor. Check the fuel level in the float chamber. Adjust closing of the choke valve, and idle speed and the main jet needle as well.
 3. Check crankcase vent pipes and inlet manifold and remove dirt describe.
- deposits.
- Remove and clean the coarse oil filter.
 Check functioning of the centrifugal and vacuumatic spark advance mechanisms.

- 6. Remove the starting motor, disassemble, clean and lubricate.
- 7. Remove and clean the fuel sediment bowl.
- 8. Inspect wheel hub bearing, change lubricant and clean the brake system as follows:
 - a) Remove wheel hubs.
- b) Flush out the hubs, steering knuckles and bearings and check their condition.
 - c) Clean and wipe the brake drums and plates.
- d) Disassemble and clean the wheel brake cylinders. Flush the piping with alcohol or brake fluid. Lubricate the pistons with castor oil or brake fluid.
 - e) Check wear of brake linings.
- Remove the front wheel brakes steering knuckles; remove the joints and change lubricant.
- g) Tighten the attachments of the steering rods and levers and the attachment of the rear brakes to the axle shaft housing flanges.
 - h) Pack the hubs with fresh grease and put them in place.
 - i) Adjust wheel bearings.
 - j) Fill the brake system with fluid and bleed the system.
 - 9. Lubricate the automobile in accordance with Lubrication Chart.

SEASONAL MAINTENANCE

- In accordance with Lubrication Chart change oil in the engine crankcase, transmission, transfer case, steering gear and front and rear axles.
 - 2. In autumn clean and flush out the body heating system.
 - 3. Change specific gravity of electrolyte according to the season.

YEARLY MAINTENANCE

- 1. Remove the shock absorbers, take out the valves, flush out the valves and body.
- 2. Remove the springs, disassemble them and lubricate. Inspect
- 3. Remove the upper cover of the transfer case, check axial play of the countershaft. If a considerable play is discovered, remove the rear cover and adjust the play using adjusting shims. Check the axial play in the bearings of the lower shaft and adjust the play using adjusting shims.
- shims.

 4. Remove the main brake, disassemble, clean, lubricate and adjust the shoe to drum clearance.

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LUBRICATION

The Lubrication Chart is shown in Fig. 6. The Chart comprises all the points to be lubricated, lubrication intervals and grades of lubricant used. Symmetrical lubrication points located on the opposite side of the automobile are shown in dotted lines. Figures indicate lubrication intervals expressed in kilometers of operation. When operating the automobile over dusty roads lubricate all 1,000 km points every 500 km. Lubricant grades are shown on the Chart by letters, the meaning of which is explained in the Table below.

LUBRICANT TABLE

Symbol	Summer Grade (over + 5°C.)	Winter Grade (below + 5°C.)							
М	Industrial oil Grade 50 Engler viscosity $5.76 \div 7.86^{\circ}$ at 50° C.	Mixture of industrial oil Grade 50 (60 per cent) and spindle oil Grade AV (40 per cent) Engler viscosity 3.5 — 4.5° at 50° C.							
н	Transmission oil								
С	Grease. Melting point 75° C. Penetration 270—330 at 25° C.	Grease, Melting point 70° C. Penetration 330—360 at 25° C.							
У	Universal, water-resistant grease with high melting point (120°). Penetration 175-210 at 25°C.								
T	Brake fluid (Substitute 50 per cent castor oil and 50 per cent alcohol).								
Α	Spindle oil Grade AV. Engler viscosity 2.05-2.26° at 50° C.								
Γ	Graphite li	ıbricant							
AM	Grease. Melting point 1.15° C. Penetration 220—270 at 25° C.								

EXPLANATORY NOTES TO LUBRICATION CHART

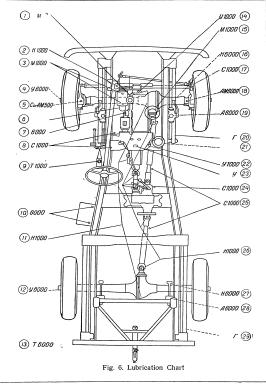
- 1. Engine crankcase. Check oil level daily. Change oil every 1,500 or 2,000 km. $\,$
- or 2,000 km.

 2. Steering gear case. Check oil level and top up, if necessary. Change oil in spring and fall.

 3. Generator 2 oilers, 5 drops each.

 4. Front wheel hub bearings. Change lubricant.

 - 5. Steering knuckle pin.
- 6. Coarse oil litter. Drain sediment when changing crankcase oil.
 7. Ignition distributor. Rotate oiler on distributor body one turn.
 Apply 1 or 2 drops of engine oil on breaker arm pivot and cam brush.



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8. Pedal shaft and clutch release drive shaft.

9. Brake master cylinder. Check fluid level and bring it to 20 mm below filler hole rim. Do not use mineral oils.

10. Storage battery terminals. Coat with vaseline at least twice a

- 11. Transmission, transfer case, front and rear axle casings. Check oil level and top up, if necessary. Change oil every 6000 km and every spring and fall.
 - 12. Rear wheel hub bearing. Change lubricant.
 - Accelerator shaft bearings 2 or 3 drops.
 - 14. Water pump bearings.
- 15. Carburettor air cleaner. Flush out and change oil. Under severe dust conditions clean daily.
 - 16. Shock absorber bracket hinges.
 - 17. Steering rod joints.
- 18. Steering knuckle joints. Add 150 g. In spring and fall or every 12,000 km flush out knuckles and pack 300 g of lubricant.

19. Front shock absorber housings. Add fluid. Once a year remove, flush out and replace fluid.

20. Front spring leaves. Lubricate when necessary but not less

than twice a year.

21. Fine oil filter. Drain sediment every 1000 km and each time when changing crankcase oil. Replace filter element every 1,500 or 2,000 km simultaneously with changing crankcase oil.

22. Clutch release bearing. Turn oil cup cover two or three turns.
23. Drive gear shaft bearing. Pack with lubricant during overhaul.
24. Transfer case lever shaft.

Splines of front and rear propeller shafts. 2 or 3 shots of a

grease gun.
26. Joints of front, rear and intermediate propeller shafts. Lubricate

20. Joints of north, the action with fluid oil only.

27. Shock absorber bracket hinges.

28. Rear shock absorber housings. Add fluid. Once a year remove,

29. Rear spring leaves. Lubricate when necessary but not less than

twice a year.
In addition to operations listed in Lubrication Chart do the follow-

ing:
1. Every 2,000 km change engine crankcase oil. If the filter element has not been replaced and the crankcase oil becomes cloudy, change oil every 1,000 km. Drain oil from the crankcase and filters immediately after stopping the engine. Simultaneously with changing the crankcase oil clean both oil filters.

If the engine crankcase becomes excessively dirty flush it out with fluid oil. To do this pour in 3 litres of oil, remove the spark plugs

and turn the crankshaft in the course of 1 or 2 min. Drain and refill with fresh oil.

Simultaneously with changing crankcase oil replace fine oil filter element.

4. Change oil in the air cleaner simultaneously with changing the crankcase oil. If the air cleaner, screen becomes clogged flush it out in kerosene, blow out with compressed air and dip in fresh oil. When working over dusty roads change oil in the cup daily.

5. Pack water pump bearings with lubricant until it oozes through check hole. Wipe off excess lubricant.

the check hole. Wipe off excess lubricant.

6. In spring and fall change lubricant in the cases of transmission, transfer case, front and rear axles. If the oil is heavily contaminated, flush out the cases with kerosene. To flush — pour l or 1,5 liters of kerosene into the case, lack up the wheels, start the engine and allow it to run for 2 or 3 min, then drain kerosene and refill with fresh oil.

Refill the cases of the transmission, transfer case, front and rear axles to the level of the filler plugs, using a special oil gun.

7. Every season change oil in the steering gear case. To drain — remove the lower R. H. bolt of the front cover. Refill to the level of the filler plug.

the filler plug.

8. Universal joints of the needle bearing type are lubricated with fluid oil. Force the oil in by an oil gun fitted with a special end piece until the oil appears from the valve located on the crosspiece.

Lubricate the propeller shaft splines by applying two or three shots of the lubricating min.

Lubricate the propeller snart spines by applying two or times shows of the lubricating gun.

9. The pin of the transfer case levers, shock absorber bracket joints, steering rod pivots and pedal shaft should be packed with grease until it oozes from the joints.

10. When changing lubricant in wheel hubs, flush out the hubs and bearings, then pack the bearings and hub with grease. The layer of lubricant in the hub should be 10 to 15 mm thick.

11. The pivots of the front and rear shock absorber brackets should be lubricated simultaneously with wheel hubs because access to bracket grease fittings is possible with removed wheels only. Every 6,000 km apply two or three shots of lubricating gun using fluid lubricant; remove excess lubricant sets. cant; remove excess lubricant.

12. Clutch release bearing should be lubricated by screwing in the lubricator cap two or three turns.

13. Every 6,000 km add fluid into the shock absorbers to the filler plug level. Once a year remove the shock absorbers and flush them out with gasoline. Place new 0.8 mm gaskets under valve plugs.

14. As the lubricant in the oil cups of the clutch release bearings and distributor shaft is used up, remove the oil cups and pack with

15. Fill the distributor oil cup with lubricant. Apply engine oil to the breaker arm pivot and felt wick.

CARE AND SERVICE ADJUSTMENTS

ENGINE

The automobile is powered with a four cylinder, four-stroke cycle gasoline engine. The design of the engine is shown in Figs. 7 and 8 $\,$

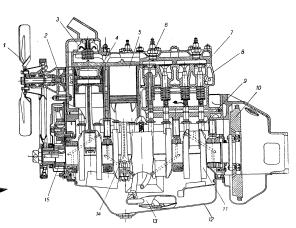


Fig. 7. Engine Longitudinal Section 1 — fan. 2 — water pump, 3 — thermostat, 4 — piston, 5 — cylinder liner, 6 — spark plug, 7 — cylinder head, 8 — cylinder block, 9 — camshaft, 10 — flywheel, 11 — crankshaft, 12 — crankcase, 13 — oil suction bell, 14 — connecting rod, 18 — timing gears.

CARE OF THE ENGINE

Tighten cylinder head bolt nuts every 1,000 km and after each removal of the cylinder head.
 Remove carbon deposits from the cylinder head and piston

crowns.

Formation of carbon may be diagnosed by detonation noises, engine overheating, loss of power, excessive gasoline and oil consumption.

Remove the cylinder head and scrape off the carbon deposits.

3. Every 40,000 to 50,000 km the piston rings and connecting rod bearing shells should be replaced by new parts of repair size. Worn piston rings cause loss of power, increase oil consumption, reduce

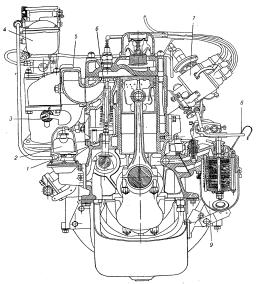


Fig. 8. Engine Cross Section

1 — valve filter, 2 — fuel pump, 3 — mixture heating regulator, 4 — carburettor, 5 — manifold, 6 — valve, 7 — inguition distributor, 8 — oil dipstick, 9 — coarse oil filter.

compression, result in heavy smoking through crankcase vent hole; besides, the carburettor becomes restricted with resinous residue.

When replacing piston rings remove carbon deposits from the piston ring grooves and from the holes in the oil control ring grooves.

Depending on the degree of wear the connecting rod shells must be replaced by new standard or 0,05 mm undersized shells.

4. If valve knocking is discovered adjust the valve to lifter clearan-

- ces in the following sequence:

 a) Jack up the front axle, place it on some support, remove the right front wheel and mudguard;
 - b) Remove the valve box covers;

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- c) Bring No. 1 piston to TDC on the compression stroke, turning the crankshaft until the ball on the flywheel coincides with the pointer on the clutch housing;
- d) Check the clearances of No. 1, 2, 4 and 6 valves by a feeler gauge. On a cold engine the clearances should be 0.23 mm for inlet valves and 0.28 mm for exhaust valves. On a warm engine 0.20 mm and 0.25 mm, respectively;
- e) To adjust clearances hold the lifter by a wrench, loosen the lock nut and turn the adjusting screw, as necessary. Having adjusted the clearance tighten the lock nut and recheck clearance.
- f) Turn the crankshaft through one complete revolution. Check and adjust the clearances of the remaining valves, if necessary.

COOLING SYSTEM

The engine is equipped with a forced water circulation system. To maintain normal engine operating temperature (80 to 90°C) and to improve warming up, the cooling system is equipped with a thermostat located in the cylinder head pipe union and a radiator blind controlled by the handle from the driver's seat. Pulling the handle out closes the blind, and pressing it in opens the blind.

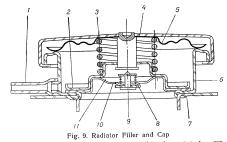
The thermometer unit for the control of engine temperature is installed in the cylinder head. Besides, there is a green tell-tale light flashing on when the temperature of water increases up to 92—98°C.

To reduce formation of scale fill the cooling system with soft water with small salt content.

In winter it is recommended to use liquids with a low freezing point — «antifreeze», consisting of ethylene-glycol (55 per cent) and water.

When the automobile is parked for a long time in a cold place drain water from the cooling system through two cocks: one located on the lower radiator cap (Fig. 9) seals the radiator hermetically, and connects the cooling system with outside air through two valves. The steam outlet valve opens at an over-pressure of 0.28 to 0.38 kg/sq. cm. The inlet valve opens when the vacuum in the system reaches 0.01 to 0.12 kg/sq. cm and admits outside air.

The water pump (Fig. 10) is of a centrifugal type. It is sealed by a self-adjusting seal. Dribbling of water through the check hole shows



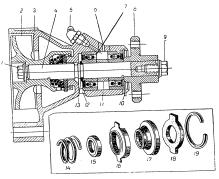


Fig. 10. Water Pump

1 — impeller attachment bott, 2 — impeller, — water nump 4 — shaft, 5 — grease litting, 2 — the parties, check note, 2 — bearings, etc. — the parties, etc. — the parties of the part

that the seal needs servicing. The water pump bearings are lubricated through a grease fitting until the lubricant emerges from the joints. To repair the seal remove the water pump from the engine and press out the pump impeller together with the seal using the puller tool shown in Fig. 11.

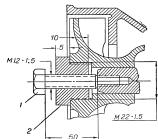


Fig. 11. Removing Water Pump Impeller 1 — puller screw, 2 — puller nut. Dimensions are shown in mm.

To facilitate the starting of the engine in winter the automobile is equipped with a starting heater installed on the left-hand side of the engine.

The care of the cooling system is confined to regular removal of scale, adjustment of fan belt tension and regular lubrication of the water pump bearing.

It is recommended to flush out the system by a powerful jet of clean water with disconnected hoses. The radiator should be flushed out through the lower pipe union. The engine water jacket should be flushed out through the upper pipe union with the thermostat removed.

Fan belt tension is adjusted by turning the generator. The normal slack of the belt is 12 to 20 mm.

LUBRICATING SYSTEM (Fig. 12)

The engine is provided with a lubricating system of a combination type. The crankshaft and camshaft bearings and valve lifters are forced lubricated. Other parts are splash lubricated.

The oil is poured into the engine crankcase through the filler pipe closed hermetically by the cap. From the crankcase the oil is drawn through the floating oil suction bell into the gear oil pump installed

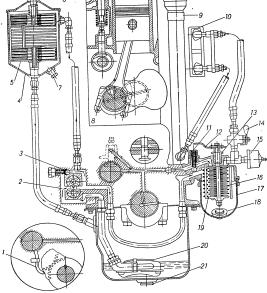


Fig. 12. Engine Lubrication Diagram

I — timing gear lubricating pipe 2 — oil pump. 3 — relief valve, 4 — fine oil filter, 5 — filter tendement, 6 — oil tendement, 6 — coarse oil filter piper, 6 — filter tendement, 6 — coarse oil filter piper, 6 — filter tendement, 6 — coarse oil filter drain plug, 9 — filter plates, 20 — oil filter drain plug, 6 — filter plates, 20 — oil filter piper, 6 — filter plates, 6 — oil filter drain plug, 6 — filter plates, 6 — oil filt

on the outside of the engine crankcase and developing a pressure of 2 to 4 kg/sq. cm. The oil is filtered twice, in coarse and fine oil filters. The coarse oil filter is cleaned automatically each time the starter button is depressed. The crankcase ventilation is of a forced type. The

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cooling of oil is ensured by the oil cooler controlled by the cock installed near the coarse oil filter. Operation of the lubricating system is controlled by the oil pressure gauge.

There are two valves in the engine lubricating system: the relief valve installed on the oil pump cover which limits maximum pressure;

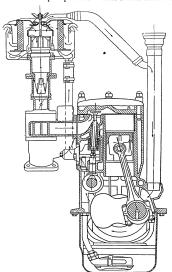


Fig. 13. Engine Crankcase Ventilation

and the bypass valve located on the coarse oil filter, which ensures circulation of oil should the filter become clogged.

A sudden oil pressure drop may be caused by the blockage of the relief valve. In this case remove the oil pump cover, dismantle and flush out the relief valve. Before replacing the pump cap lubricate the pump gears with grease, otherwise the pump will not draw the oil from the crankcase.

The crankcase oil level is measured by the oil dipstick. The oil level should be between the «O» and «Ts marks.

The oil cooler should be turned ON in summer and when the engine is working under heavy load.

The replaceable element of the fine oil filter should be changed each time when the crankcase oil is changed or at an earlier date when the oil shows an evidence of being murky or cloudy. Replace the filter element as follows:

- 1. Mark the position of the filter cap on the body, and remove the
- cap.
 2. Remove the drain plug, drain sediment and wipe the body
- Replace the filter element, screw IN the plug and refill the filter with fresh oil.
 Check condition of the body cap gasket and change it if neces-

- 4. Circle 3.3.

 5. Replace the cap.
 6. Add oil into the engine crankcase to the «Π» mark on the
- Start the engine, check for oil leaks and add oil to the «Π» mark. Engine crankcase ventilation (Fig. 13) operates due to a difference in the vacuum in two points of the air cleaner to which inlet and outlet tubes are connected. Ventilation cleans the crankcase from gasoline vapours and exhaust gases that break through the piston rings.

 Do not operate the engine with insufficiently tight ventilation system as this will result in dust getting inside the crankcase.

 Check the ventilation system regularly for tightness and remove sludge.

sludge.

A normal engine oil pressure should be 2 to 4 kg/sq.cm at a speed of 45 km/hr. On a cold engine the pressure may reach 4.5 kg/sq.cm and drop down to 1.5 kg/sq.cm in hot weather. At low idle speed the minimum oil pressure should be equal to at least 0.5 kg/sq.cm.

A drop of pressure below 1.0 kg/sq.cm at medium speed shows that something is out of order in the system.

FUEL SYSTEM (Fig. 14)

The fuel system consists of fuel tanks, filter-sediment bowl, fuel pump, carburettor, air cleaner, inlet manifold and connecting pipes. The automobile is equipped with either two fuel tanks (FA3-69) or one fuel tank (FA3-69A). The tanks are equipped with air-tight caps provided with double valves which prevent loss of gasoline vapours. The tank is equipped with a shut-off valve, two gasoline level indicators (dipstick and electric type) and a drain plug. With a two-tank arrangement a three-way cock is installed used for switching over from the main tank to the auxiliary tank. The care of the tank consists in regular inspection and flushing out of the cap valves; draining sediment and flushing out the tank.

The filter-sediment bowl of a plate type is installed on the left-hand side of the automobile frame. The care of the sediment bowl consists in regular draining of sediment through the drain plug and periodical washing of the filter element.

The fuel pump of a diaphragm type has a hand lever for priming gasoline. On the running engine the hand priming lever should be held down by a spring.

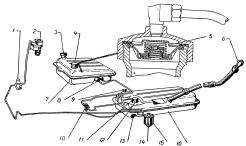


Fig. 14. Fuel System

1 — fuel pump, 2 — carburettor, 3 and 6 — fuel tank filler caps, 4 — valve pipe plug, 5 — inlet and outlet valve assembly, 7 — auxiliary tank, 8 — shut-off valve, 9 — gasoline level dipstick, 10 — three-way cock, 11 — outlet pipe, 12 — gasoline level indicator rheostat, 13 — tank drain plug, 14 — filler-sediment bowl, 16 — main luet tank, 15 — filler-sediment bowl, 16 — main luet tank,

The care of the fuel pump consists in regular washing of the screen filter installed in the upper part of the pump and replacement of the cork gasket, should it become damaged.

The automobile is equipped with a K-22Д down-draft carburettor with automatic mixture control effected by two jets and elastic Venturi plates. The carburettor is fitted with an acceleration pump, economizer mechanically driven from the throttle valve, and a needle for adjusting the carburettor under operational conditions. The diagrammatic view of the carburettor is shown in Fig. 15.

The carburettor has a provision for four types of adjustment: the main metering system is adjusted by turning the needle of the main jet; the acceleration pump is adjusted by means of the pump drive rod; the economizer is adjusted by screwing the nut on the acceleration pump rod; and the idle speed is adjusted by the screw located in the idle speed passage and the screw controlling the opening of the throttle valve.

The economizer starts to operate when the throttle valve lever is 6.2-6.8 mm short of the stop. The moment of switching on of the economizer is adjusted by turning the nut on the acceleration pump rod. See that the economizer drive rod is connected to the end hole of the

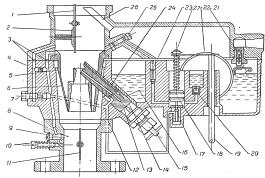


Fig. 15. Carburettor Diagram

1 — choke, 2 — choke safety valve, 3 — idle speed air jets, 4 — idle speed emulsion jet, 5 — Venturi pilock, 6 — Venturi spring plates, 7 — idle speed jet, 8 — vacuumatic governor tube hole, 9 — idle system upper outlet opening (slot), 10 — idle speed adjusting serve, 11 — introlte valve, 12 — gaskets, 18 — main jet, 17 — compensating istems, 18 — introlte valve, 18 — gaskets, 18 — main jet, 17 — compensating istance in the property of the prop

Adjustment of the idle speed is carried out on a warmed-up engine subsequent to checking the ignition system.

Turning the throttle valve screw IN (Fig. 16) opens the throttle and increases engine speed. Turning the idle speed screw OUT increases the quantity of the fuel mixture.

Before making adjustments, turn the throttle valve screw IN 1½ or 2 turns and turn the idle speed screw OUT also 1½ or 2 turns.

To adjust:

To adjust:

1. Turn the throttle valve screw OUT to set the minimum steady idle speed.

2. Turning the idle speed screw IN, make the mixture leaner until the engine begins to misfire, then back it off a little for smooth engine performance.

3. Check adjusment by depressing the accelerator pedal and releasing it abruptly. If the engine stalls increase engine speed by turning the throttle valve screw $\ln 1/\epsilon$ of a turn. The working mixture is heated by the exhaust gases in the middle part of the inlet pipe. Intensity of heating is controlled by the choke operated automatically by means of a bimetal spring and weight.

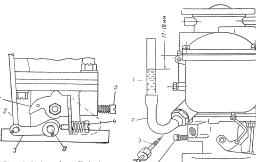


Fig. 16. Linkage from Choke to Throttle Valve

I — throttle valve lever, 2 — choke to throttle rod, 3 — lever with cam, 4 — screw adjusting opening of throttle valve at idle speed, 5 — idle speed adjusting screw, 6 — pin.

Fig. 17. Measuring Gasoline Level in Float Chamber 1 — glass tube, 2 — rubber pipe, 3 — adjusting needle, 4 — idle speed screw

Fuel consumption during operation depends on the condition of the automobile and proper adjustment of the fuel system.

Condition of the running gear can be determined to a considerable extent by free running. The automobile running over a level road at a speed of 30 km/hr must cover at least 150 m from the time the clutch is released to the complete stop.

is released to the complete stop.

The length of the free run depends on the lubrication of the running gear, adjustment of wheel bearings and brakes, and condition of tyres. Fuel consumption is considerably influenced by correct setting of the ignition advance angle. The ignition should be set so that with the engine running on gasoline of 66—70 octane number, infrequent detonation knocks will be heard if the automobile has been accelerated in first gear by abrupt depression of the accelerator pedal.

To bring fuel consumption to a minimum it is necessary to adjust properly the opening of the carburettor main jet needle. It is recom-

mended that the needle be opened 11/2 or 2 turns, depending on ope-

mended that the needle be opened 1-/2 or Z turns, depending on operational conditions.

Adjust correct gasoline level in the float chamber. Checking is effected by means of two tubes made of rubber and glass screwed into an opening in the adjusting needle (Fig. 17). Normally, the gasoline level should be 17 to 19 mm below the carburettor split surface. To change the level bend the tongue on the lever to which the float is soldered.

The care of the carburettor consists in regular washing and blowing out of jets, cleaning the Venturi plates from deposits, inspecting the gaskets and checking carburettor adjustments.

IGNITION SYSTEM

The ignition system consists of a 12~V storage battery, generator, ignition switch, ignition coil, distributor-breaker and spark plugs. The ignition wiring system is shown in Fig. 18.

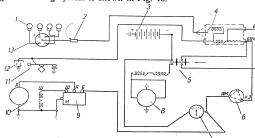


Fig. 18. Ignition Wiring System

1 — spark pluga. 2 — suppressor resistor, 3 — storage battery. 4 — ignition coll, 5 — starter switch, 6 — ignition switch, 7 — ammeter, 8 — starting motor, 9 — current and woltage regulator, 19 — generator, 11 — breaker, 12 — condenser, 13 — distributor.

The spark plugs of M12V type with 18 × 1.5 mm thread are used. When replacing a spark plug see that the length of the threaded part does not exceed 12 mm. A normal electrode gap is 0.7 to 0.8 mm. Adjust the spark plug gap by bending the side electrode only. The ignition coil of bi type is equipped with an additional resistor closed by the starter switch during engine starting.

The H. T. circuit includes suppressor resistors to reduce radio interference created by the operation of the ignition system.

The P-20 distributor with the centrifugal and vacuumatic spark

advance control and octane-selector (Fig. 19) is installed on the L. H. side of the engine being driven by the oil pump shaft.

The care of the ignition system consists in regular inspection of spark plugs, adjustment of the spark plug gap, replacement of faulty

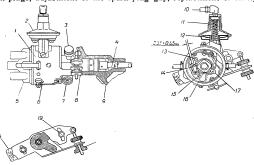


Fig. 19. Distributor

7 — distributor body, 2 — vacuumatic spark advance unit body, 3 — oiler, 4 — distributor baber, 50, 6 — t. terminal, 7 — condenser, 8 — octane selector utis, 9 — over the condenser, 8 — octane selector utis, 9 — over the condenser, 8 — octane selector utis, 9 — over the condenser, 8 — over the condenser t

or soiled spark plugs, checking and adjusting the breaker point gap, cleaning the breaker points, setting the ignition, timely lubrication of the distributor and servicing the current source and wiring (see Electric Equipment Section).

To adjust the breaker point gap crank the engine by the starting handle to set the breaker points to maximum opening position, then loosen the screw of the fixed contact plate and turn the adjusting eccentric screw to set the required clearance by means of a feeler gauge.

eccentric screw to set the required clean the points by a special plate included in the Driver's Kit.

The ignition is set using the notches on the flywheel. A ball pressed into the flywheel corresponds to TDC in cylinder No. I. In addition there are divisions ± 12° from TDC.

Set the ignition as follows:

1. Remove the distributor cap and check the breaker point gap.

2. Remove the cover of the access hole on the flywheel near the starter.

3. Remove No. I spark plug.
4. Place the thumb over the spark plug hole and crank the engine slowly until the compression stroke is felt.
5. Continue to crank the engine slowly until the notch on the flywheel (marked by figure 4) is lined up with the pointer on the clutch housing. wheel (History Agence 7)
housing.
6. Disconnect the tube of the vacuumatic control.
7. Remove the distributor cap and make sure that the rotor contact lines up with No.I spark plug contact in the distributor cap.
8. Set the octane selector to the zero division by means of adjusting nuts

8. Set the octane selector to the zero division by means of adjusting nuts.

9. Loosen the distributor to cylinder block attaching screw and turn the distributor body clockwise so as to close the contacts.

10. Switch ON the inspection lamp, connecting one lead to the ground and the other one to the L. T. terminal of the ignition coil.

11. Turn the ignition switch ON and rotate slowly the distributor body counter-clockwise until the lamp flashes up.

12. Secure the distributor body to the cylinder block by screws, replace the distributor cap and insert the central cable. Inspect the order of H. T. cable connection, beginning with cylinder No. I. The cables should be connected in the order 1—2—4—3 in a clockwise direction.

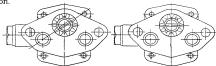


Fig. 20. Position of Oil Pump Shaft Slot

(viewed from above)

A — prior to installation in cylinder block,

B — after installation.

The final adjustment of ignition setting is carried out during road tests with the engine running on gasoline of 66—70 octane number. For this purpose drive the warmed up automobile in high gear at a speed of 25—30 km/hr and depress sharply the accelerator pedal as far as it will go. If weak detonation knocks are heard, the ignition is now considered timed. If detonation is strong turn the distributor body clockwise one division of the octane-selector scale. If there is no detonation turn the distributor body counter-clockwise.

If the oil pump has been removed from the engine, correct coupling of its shaft with the distributor shaft should be achieved by installing the oil pump as follows:

1. Bring the engine crankshaft to a position corresponding to TDC on the compression stroke in cylinder No. I.

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2. Turn the oil pump shaft so that its slot is brought to the position shown in Fig. 20,A.

3. Put the oil pump in place carefully so that the pump gears will mesh with the camshaft gear, the pump shaft will turn and the slot for the distributor shaft lug will take a horizontal position, shown in Fig. 20.8 the distrib

POWER TRANSMISSION

The power transmission of the automobile comprises the clutch, transmission, transfer case, propeller shaft, front and rear axles.

CLUTCH (Fig. 21)

The clutch is of the dry, single plate type with a vibration damper. The care of the clutch consists in adjusting the play of the clutch pedal and regular lubrication of the release collar bearing, release

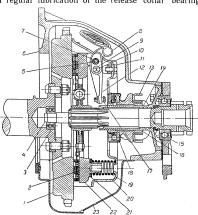


Fig. 21. Clutch

I — flywheel, 2 — driven pales, 3 — clutch shaft front bearing, clutch shaft, 5 — pull back lever pin, 6 — clutch housing, 7 — r bearing, 8 — weights, 9 — pin, 10 — roller, 11 — pull back bracket, 12 — pull back lever, 13 — engagement fork, 14 — front mission cover, 15 — bearing, 16 — engagement sleeve, 17 — pull lever adjusting screw, 18 — thrust bearing, 19 — spring, 20 — lever adjusting screw, 18 — thrust bearing, 19 — spring, 20 — lever adjusting screw, 18 — thrust bearing, 19 — spring, 20 — washer, 22 — pressure plate, 29 — clutch lower hou

shaft and clutch pedal pin. The play of the clutch pedal should be 38 to 45 mm. Play, is adjusted by changing the length of the pusher connecting the release yoke with the clutch release shaft lever (Fig. 22). Adjustment by the use of the pull back lever adjusting bolt should be availed.

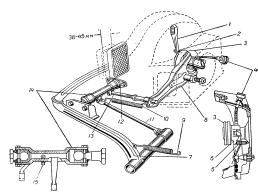


Fig. 22. Clutch Release Linkage

1 — pull back lever, 2 — pull back lever adjusting screw, 3 — thrust bearing, 4 — oiler, 5 — release collar retracting spring, 6 — release collar, 7 — clutch pedal; 6 — release tolk, 9 — clutch pedal return spring, 10 — release fork pull back spring, 11 — clutch release shaft rod, 12 — clutch release shaft bracket support on engine, 13 — release fork pusher, 14 — clutch release shaft, 15 — shaft oller.

The clutch release bearing is lubricated through an oil cup located on the R. H. side of the clutch housing. The release shaft and clutch pedal pin are lubricated through grease fittings.

TRANSMISSION (Figs. 23 and 24)

The two-range gearbox has three speeds forward and one reverse. The constant mesh and 2nd speed gears have helical teeth, while the 1st speed and reverse speed gears have straight teeth. The 2nd and high gears are fitted with synchronizers. The gear shift mechanism and lever are mounted in the side cover.

To ensure proper synchronizer operation and noiseless shifting of gears the gear shift lever should be moved smoothly, without jerks. Shift from the 2nd speed to the 1st only after reducing the automobile speed down to 5 km/hr.

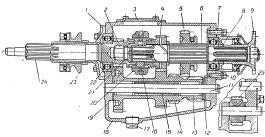


Fig. 23. Transmission. Longitudinal Section

cap, 2 — roller bearing, 3 — upper cover, 4 — 2nd speed gear, 5 — 1st speed slide gear, 6 — main shalt, 7 — rear cover, 8 — bearing spacer is shaft attachment flange, 10 — ball bearing, 11 — countershalt pivot, 1/2 washers, 13 — roller bearing, 14 — countershalt cluster gear, 15 — spacer, 16 — transmission case, 20 — 2nd and 3rd speed gear, 2/2 — roller bearing locking ring, 2/2 — ball bearing, 2/3 — clutch collar, 2/4 — drive gear shalt, 2/5 — reverse speed gear.

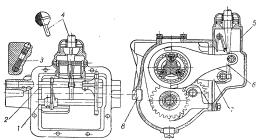


Fig. 24. Gear Shift Mechanism 2 - gear shift shaft, 3 - lock, 4 - gear shift lever, 5 - gear shift mechanism cover,
 6, 7 - shift forks, 8 - case check plug.

The care of the transmission consists in changing the oil every $6,000~\rm{km}$ of operation, and seasonal replacement of oil (in spring and fall) as well as in regular checking of the oil level and topping up after $1,000~\rm{km}$ of operation.

The oil level in the transmission housing should be at the lower edge of the control plug.

TRANSFER CASE (Fig. 25)

TRANSFER CASE (Fig. 25)

The transfer case serves to transmit engine torque to the rear and front axles and to increase traction of the wheels. The case has two low gears with 1.15 and 2.78 ratios. Control of the transfer case is by two levers. The left-hand lever disengages the front axle (forward position) and engages it (backward position). The right-hand lever is the gear shift lever having three positions: front — the 2.78 gear engaged, neutral — the transfer case inoperative, and rear — the 1.15 gear engaged. The low speed may be engaged only after stopping the automobile and engaging the front axle being intended for use only over extremely difficult roads.

The countershaft and the driven shaft of the transfer case are carried on tapered roller bearings. Bearing adjustment is accomplished by means of adjusting shims laid under the bearing caps.

The transfer case control system incorporates an interlock mechanism preventing the low gear to be engaged when the front axle is disengaged and the front axle to be disengaged with engaged low gear.

The care of the transfer case consists in regular lubrication, checking the attachment of the propeller shaft flanges and adjustment of shaft play.

PROPELLER SHAFTS

The automobile is equipped with three propeller shafts: intermediate — between the transmission and transfer case, front, and rear — between the transfer case and front and rear axles.

The propeller shafts are installed with splined ends directed towards the transfer case.

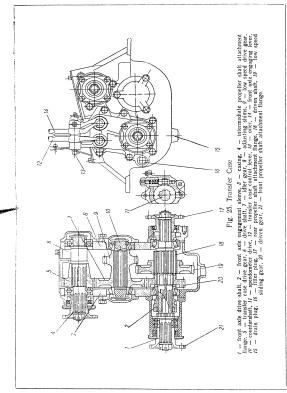
wards the transfer case.

The care of the propeller shafts consists in regular lubrication of universal joints, splines, sliding yokes, cleaning the shafts from dirt and inspection of seals. If a splined connection is to be disassembled see that during reassembly the pointer marks are lined up.

REAR AXLE (Fig. 26)

The rear axle includes a split casing with axle shaft sleeves. The sleeves accommodate: the bevel main drive and differential with two bevel satellites and axle shaft gears. The axle shafts are inserted into the splined holes of the axle shaft gears.

The care of the rear axle consists in regular lubrication, tightening



loose attachments, adjustment of bearings and adjustment of gear mesh (when replacing or repairing the main drive).

When lubricating the rear axle, add oil to the filler plug level and clean the breather air hole.

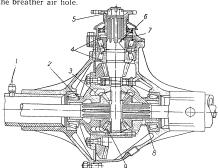


Fig. 26. Rear Axle Fig. 26. Rear Axle for the first parameter f and f and f and f axle shall gear thrust washer, f and f are gear positioning shims, f and f axis shall gear thrust washer, f and f are first piece bearing adjusting shims, f and f are in the first parameter f axis where.

The tightening of the double tapered bearing of the end piece is adjusted by means of shims placed between the inner bearing races. The end piece should be free to rotate and have no axial play.

After adjustments check the bearings for heating during operation. If the bearing is heated considerably, increase the thickness of the adjusting shims.

The differential bearings are adjusted by changing the thickness of shims laid between the inner bearing races.

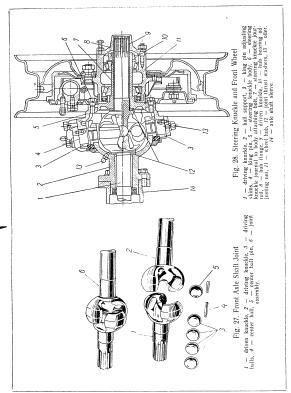
The adjustment of main drive bevel gear mesh is effected by changing the places of shims at outer races of the end piece bearing and at inner races of the differential bearings. The total thickness of shims in each pair of bearings should remain unchanged.

The side play of the gear teeth should be within 0.2 to 0.6 mm as measured on the drive gear end piece at a radius of 40 mm.

After adjustments check the bearings for heating in motion.

FRONT AXLE (Figs. 27 and 28)

The middle part of the front axle (main drive bevel gear and differential) is identical with the rear axle and is adjusted in a similar



WHEEL HUBS

(Figs. 28 and 29)

The hubs of the front and rear wheels rotate in two tapered roller bearings which require adjustment in operation for elimination

of axial play.
Adjust the wheel bearings as follows:

1. Jack up the wheel.
2. Remove the hub flan-

ge.

3. Remove the lock nut and take off the lock

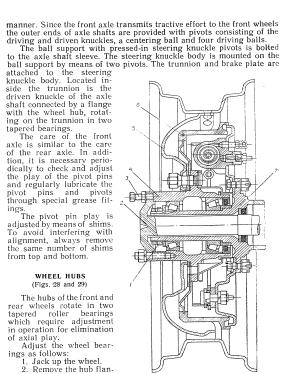


Fig. 29. Rear Wheel Hub 1 — Bearing adjusting nut, 2 — axle shaft flange,
 3 — flange removing bolt, 4 — hub, 5 — wheel disc,
 6 — brake drum, 7 — axle shaft sleeve.

4. Loosen the bearing adjusting nut.

Clock ease of wheel rotation.
 Check ease of wheel rotation.
 Tighten the wheel nut sufficiently to enable the wheel to be rotated by hand though not too easily.
 Back off the nut 2 or 2½ faces, replace the lock washer and lock

nut.
8. Check bearing adjustment by feeling the heating of the wheel

hub in motion.

RUNNING GEAR AND STEERING GEAR

STEERING GEAR (Fig. 30)

The steering gear comprises the worm mechanism and steering rods. The care of the steering gear consists in lubricating the steering mechanism and rod joints, checking their attachments, adjusting the steering gear for mesh and backlash.

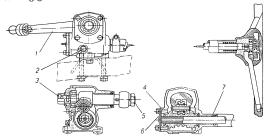


Fig. 30. Steering Gear 1 — Steering arm, 2 — filler plug, 3 — mesh clearance adjusting screw, 4 — worm bearing adjusting shims, 5 — steering arm shaft, 6 — front cover, 7 — steering shaft.

With a properly adjusted steering mechanism the steering wheel should have no backlash when the automobile is driven straight ahead. When the steering wheel is turned to any extreme position the backlash reaches 30°. If in the straight ahead position the backlash exceeds 40 mm along the steering wheel rim it is necessary to adjust clearance of the steering couple displacing axially the steering arm shaft by means of the adjusting screw located on the upper cover of the steering gear case. Before making any adjustments inspect steering case attachments and condition of joints.

Worn worm bearings are adjusted by reducing the number of shims

laid under the front cover of the steering gear case. For making adjustments the steering gear should be removed from the automobile. Tightening of bearings is checked with the removed steering arm shaft. The effort necessary for rotating the steering wheel, applied to the wheel rim should be 0.22 to 0.45 kg. In the assembled mechanism this effort should be 0.7 to 1.2 kg.

BRAKES (Figs. 31, 32 and 33)

The automobile is equipped with independent foot and hand brake systems. The foot or service brake has a hydraulic drive and is applied to all four wheels. The hand or parking brake is operated mechanically and is applied to the power transmission.

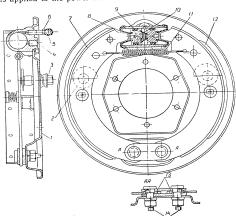


Fig. 31. Wheel Brake I — Brake shield, 2 — adjusting eccentric, 3 — eccentric head, 4 — wheel cylinder, 5 — cap, 6 — bleeder valve, 7 — front shoe, 8 — housing, 9 — piston, 10 — spring, 11 — pull back spring, 12 — rear shoe, 13 — locating eccentries, 14 — pirs.

The care of the brakes consists in adjusting the brake shoe clearance, the play of the brake pedal, the length of the hand brake cable and in regular filling the hydraulic system with brake fluid.

As the brake shoe linings become gradually worn the shoe to drum clearances are increased. With correct clearances full braking should take place during the first half of the brake pedal travel. The brakes are adjusted by means of two eccentrics whose hexaliedral ends project outside. outside.

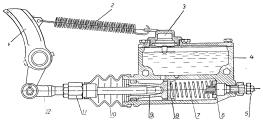


Fig. 32, Brake Master Cylinder

1 — brake pedal, 2 — pedal spring, 3 — filler plug, 4 — body, 5 — brake line, 6 — ves, 7 — plunger spring, 8 — collar, 9 — plunger, 10 — housing, 11 — pusher, 12 — pedal yoke.

To adjust the brakes:

- 1. Jack up the wheel.
 2. Rotating the wheel turn the adjusting eccentric of the front brake shoe until the shoe brakes the wheel.
 3. Loosen the eccentric gradually until the wheel is free to rotate

- again.
 4. Adjust the rear brake shoe in the same way.
 5. Adjust the brakes of the remaining wheels.
 6. Check the brake drums for heating while the automobile is in

motion.

Do not check brake adjustment by turning the brake shoe supporting pins. These pins have to be adjusted during replacement of brakes or linings only.

The play of the brake pedal is determined by the clearance between the pusher and the piston of the brake master cylinder. The clearance should be 1.5 to 2.5 mm which corresponds to a brake pedal play of 11 to 14 mm. The adjustment is carried out by changing the length of the pusher which is done by screwing it on the pedal fork (See Fig. 32). The hydraulic brake system is filled with 0.4 liters of special brake fluid.

fluid.

Fill the system as follows:

I. Remove the floor mat and the access hole cover, unscrew the filler plug of the brake master cylinder and fill it with fluid.

2 Remove the cap from the bleeder valve on the rear right wheel cylinder and slip a rubber hose 350 to 400 mm long on the valve. Dip the other end of the hose into a glass container of 1 liter capacity, half-full of brake fluid.

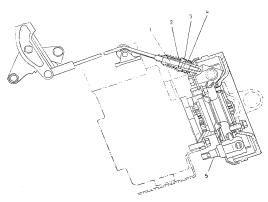


Fig. 33. Hand Brake Linkage I — cable end, 2 — lock nut, 3 — nut, 4 — brake shoe expander rod, 5 — adjusting screw

3. Loosen the bleeder valve ½2 or ¾4 of a turn and pump the brake pedal a few times, depressing it sharply and slowly releasing it. This will make the fluid fill the pipes and expel air out of them. Bleed the system until the air bubbles cease to emerge from the hose dipped in the container with fluid. While bleeding the system add fluid in the brake master cylinder.

4. Screw in the wheel cylinder bleeder valve tightly and replace the cap. Turn the valve IN with depressed brake pedal.

5. The brakes should be bled in the following sequence: rear right, front right, front left and rear left.

6. After bleeding fill the brake master cylinder 15 or 20 mm below the upper edge of the hole and screw in the plug tightly.

With correct shoe to drum clearances and absence of air in the system the depressed brake pedal should go down not farther than half of its travel after which the foot should feel a resistance. If the pedal

moves lower it is an evidence of excessive clearances. If no resistance is felt it shows that the system is air-bound.

Efficient functioning of the hand brake is ensured by correct setting of the brake shoe springs. The stronger springs painted black should be installed on the right-hand side. The weaker springs painted red should be installed on the left-hand side.

The hand brake needs adjustment when the lever travel is insufficient for the full braking which is caused by excessive clearances between the brake shoes and drum or by excessive length of the brake cable.

cable.

To adjust the shoe to drum clearance turn the adjusting screw all the way IN then back it OFF 4 to 6 clicks (1/3 or 1/2 of a turn).

To adjust the length of the brake cable move the lever handle into the third tooth space of the segment gear (counting from the rear end). Then unscrew the lock nut and nut of the cable and screw the cable end piece IN until braking begins. Lock the cable in this position.

SUSPENSION (Fig. 34)

The automobile suspension consists of four semi-elliptic springs and four hydraulic shock absorbers.

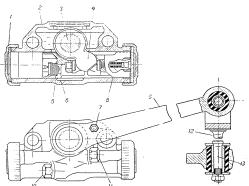


Fig. 34. Shock Absorber

Shock absorber cylinder cover, 2 — shock absorber body, 3 - shaft, 4 — cam, 5 — inlet valve, 6, 8 — shock absorber pistons, 9 — shock absorber lever, 10 — compression stroke valve plug, 11 valve plug, 12 — shock absorber bracket, 13 — bracket att

Placed between the springs leaves are gaskets of plywood soaked in mineral oil. The springs are enclosed in boots filled with graphite lubricant. The springs are attached by spring bolts with rubber sleeves. Two way piston type shock absorbers are installed on all wheels.

The care of the suspension consists in regular cleaning, inspection of attachments, periodical lubrication and adding fluid to

periodical lubrication and adding fluid to the shock absorbers.

When topping up the shock absorbers without removing them from the automobile disconnect the shock absorber bracket, and add fluid by small portions, rocking the lever.

TYRES

The automobile is equipped with low pressure tyres $6.50 \times 16^{\prime\prime}$. The care of the tyres consists in the following:

pressure tyres 6.50×16°. The care of the tyres consists in the following:

Daily, before work check tyre pressures (2 kg/sq. cm for front wheels, 2.2 kg/sq. cm for rear wheels). Check condition of tyre valves and presence of valve caps.

After work inspect the tyres, remove foreign articles from them. Keep oil and gasoline away from the tyres.

If the automobile is to stand idle for more than 10 days, the tyres should be relieved by jacking the automobile and placing it on trestles. Do not allow the automobile to stand on deflated tyres.

Removed tyres should be stored in a dry place at a maximum temperature of +20° C and a relative air humidity of 50 to 80 per cent. Store the tyres in a vertical position on wooden racks and the tubes — slightly inflated on hangers with a half-rounded shelf. From time to time the tyres and tubes should be turned over.

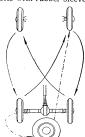
During operation check frequently the tyre pressure. Incorrect pressure renders engagement and disengagement of the front axle difficult, causes overheating of the transfer case and results in premature wear of the tyres. During stops inspect the tyres and remove stuck nails and similar articles.

To ensure uniform wear of the tyres interchange them every 3,000 km, as shown in Fig. 35. If the tyres wear irregularly, adjust the toe-in by changing the length of the steering tie rod. The toe-in should be within 1.5 to 3.0 mm.

The tyres should be mounted as follows:

1. Prior to mounting check condition and cleanliness of the wheel rim.

1. Prior to mounting check condition and cleanliness of the wheel rim.



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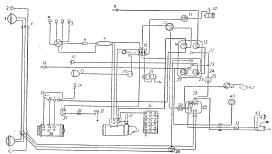


Fig. 36. Wiring Diagram

I—head lamp, 2—side lamp, 3—connection panel, 4—spark plugs, 5—suppressor resistor, 6—suppressor resistor, 7—distributor, 8—ignition coil, 9—thermometer unit, 10—ignition switch, 11—fan switch, 12—defroster ventilator, 13—thermometer, 14—a ammeter, 15—isuse block, 16—socket, 17—pressure gauge unit, 18—spark, 18—spark, 19—spark, 19—sp

2. Powder the tyre and tube with talc.
3. Install the tyres in accordance with the arrows pointing in the direction of rotation.

4. See that the tube valve is properly installed in the rim, without deformation. Before inserting the second tyre bead into the rim inflate the tube enough to make it unfold.

5. Put caps on tyre valves to protect valve cores from dirt.

ELECTRIC EQUIPMENT

The electric equipment comprises the generator with current and voltage regulator, storage battery, lighting system, starting motor and instruments.

The general wiring diagram is shown in Fig. 36.

GENERATOR

The generator is a shunt-wound two-brush machine driven by the fan belt. Service the generator as follows:

Every 1,000 km check the attachment of the generator and generator pulley and inspect all contact connections.

Every 6,000 km do the following:

1. Inspect generator brushes, check their contact with the commutator, check brush pressure (1,250 to 1,750 g). Replace the brushes if the pressure is less than 800 g.

2. Blow out the commutators with compressed air and wipe with a cloth soaked in gasoline.

3. Should the commutator become badly worn clean it with fine emery paper.

emery paper.

Lubricate the generator bearings as described in the Lubrication Chart.

CURRENT AND VOLTAGE REGULATOR

The current and voltage regulator type PP-20 is installed under the engine hood being closed by a hermetic cap and sealed. The current and voltage regulator consists of the circuit breaker, current limiting regulator and voltage regulator (Fig. 37).

Every 6,000 km check the regulator adjustment and clean its contacts.

The circuit breaker is checked as follows (Fig. 38):

1. Disconnect the cable from the "B" terminal of the current and voltage regulator and cut in a check ammeter between this cable and the "B" terminal.

voltage regulator and cut in a check ammeter between this cable and the "B" terminal.

2. Cut in a check voltmeter between the "Я" terminal and ground.

3. Start the engine, increase its speed and mark the voltage at which the circuit breaker contacts close (closing of contacts is determined by the deviation of the ammeter pointer). This voltage should be 12. 2 to 13. 2 V.

4. When decreasing engine speed determine by the ammeter the return current at which the circuit breaker contacts open. The current should be 0.5 to 6.5 A.

return current at which the circuit breaker contacts open. The current should be 0.5 to 6.5 A.

The current limiting regulator should be checked as follows:

1. Jack up both automobile axles. Engage the front axle.

2. Cut in a check ammeter as shown in Fig. 38.

3. Switch on the starting motor a few times in order to slightly discharge the storage battery.

4. Start the engine and smoothly engage the high gear. Depress the accelerator pedal until the speedometer reads 41 to 46 km/hr which corresponds to 1,800—2,000 r.p.m. of the engine.

5. Switch on all the current consumers on the automobile. The check ammeter should register 17 to 19 A. In 11/2 or 2 min the battery will be charged and the charging current will be less than 10 A.

The voltage regulator must be checked as follows:

1. Jack up both axles and engage the front axle.

2. Cut in a check voltmeter between the "B" terminal and ground.

3. Cut in a check ammeter installed on the instrument panel.

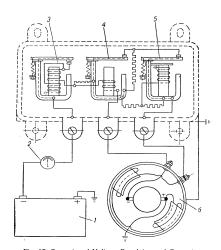


Fig. 37. Current and Voltage Regulator and Generator Hook-Up I — storage battery, 2 — ammeter, 3 — circuit breaker, 4 — current limiting regulator, 5 — voltage regulator, 6 — generator.

4. Increase engine RPM until the speedometer reads 41 to 46 km/hr. If with the fully charged battery the check voltmeter registers more than 15.5 V this is an evidence that the current and voltage regulator is out of order.

5. Disconnect the storage battery with the engine running.

6. Switch on the current consumers so that the generator load is 10 A as shown by the check ammeter. The voltage registered by the voltmeter after 10 minutes' operation should be 14.2 to 14.8 V.

After 24,000 km of operation remove the current and voltage regulator from the automobile, open it, inspect and tighten all terminals. Inspect and clean the contacts with a special abrasive plate and wipe with paper.

with paper.

Check the armature to core clearances on the voltage regulator and current limiting regulator (Fig. 39). The clearance should be 1.4 to

.5 mm with closed contacts. Check the clearance as shown in Fig. 39. To adjust the clearance loosen the screws and move the contact bracket. Subsequent to cleaning the contacts and adjusting the clearance check functioning of the voltage regulator. To increase generator voltage increase armature spring tension by tightening the adjusting nut.

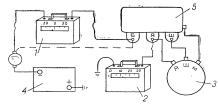


Fig. 38. Current and Voltage Regulator Checking Diagram I — ammeter, 2 — voltmeter, 3 — generator, 4 — storage battery, 5 — current and voltage regulator.

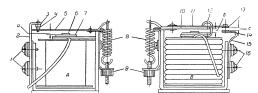


Fig. 39. Checking PP₂O Current and Voltage Regulator Clearances A — in voltage regulator and current limiting regulator. B — in circuit breaker.

A — in voltage regulator and current limiting regulator. B — in circuit breaker.

— contact bracket attachment screws. 2 — contact bracket.

— contact bracket attachment screws. 1 — current carrying plate. 2 — shacket.

— spring. 9 — adjusting nut. [D — armature. II — current carrying plate. 1 2 — shacket.

B — moving contact. 14 — fixed contact. 16 — contact bracket. 16 — contact

B — armature to core clearance in voltage regulator and current limiting regulator.

B — armature to core clearance in voltage regulator and current limiting regulator.

Clearance.

The clearances of the current limiting regulator are checked and adjusted in the same manner as in the voltage regulator. To increase current — increase spring tension. In the circuit breaker the armature to core clearance should be $1.3 \ \text{to} \ 1.5 \ \text{mm}$ with opened contacts. The clearance between contacts should be $0.7 \ \text{to} \ 0.9 \ \text{mm}$. Adjustment of the armature to core clearance core clearance between contacts should be $0.7 \ \text{to} \ 0.9 \ \text{mm}$.

rance is done by bending the armature limiting shackle. The contact clearance adjustment is done by bending the contact bracket. To increase voltage at which the contacts close increase spring tension.

STORAGE BATTERY

The automobile is equipped with the 6CT-54 storage battery, 12 V, 54 A-h at 10 hour discharging rate. The specific gravity of the electrolyte in the fully charged battery in temperate climate should be 1.285 in winter and 1.270 in summer. At a temperature below —35° C the specific gravity should be increased up to 1.310. In the south regions in summer bring the specific gravity down to 1.240.

Avoid discharging the battery in excess of 50 per cent in summer and 25 per cent in winter. The electrolyte specific gravity in relation to the degree of battery charging is given in the Table. The specific gravity should be tested by a special hydrometer taking into account temperature corrections.

perature corrections.

SPECIFIC GRAVITY OF ELECTROLYTE AT 15° C

Full charge	25 % discharge	50% discharge
1.310	1.270	1.230
1.285	1.245	1.205
1.270	1.230	1.190
1.240	1.200	1.160

It should be noted that in cold weather the storage battery capacity is reduced by 1 or 2 per cent with each degree of temperature reduction. As a rule the electrolyte level in the battery should be 10 to 15 mm above the screen protecting cell plates. The level is checked by means of a glass tube with an inside diameter of 3 to 5 mm. Insert the tube into the filler opening until it touches on the screen, close the top hole with the thumb and remove the tube. The height of the electrolyte in the tube corresponds to the height of the electrolyte above the screen. Add distilled water if necessary.

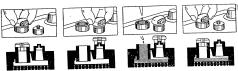


Fig. 40. Sequence of Storage Battery Refilling Operations

Add water in the sequence shown in Fig. 40. Unscrew the filler plug and slip it tightly over the ventilation hole tapered tip located near the filler hole. Add water almost up to the rim of the filler hole. Remove the plug from the ventilation hole and slip it in the filler hole. The electrolyte level will then drop to normal height.

To check the storage battery and determine the state of its charge—check the specific gravity of the electrolyte. In addition, every month check each cell with a resistance fork. When checking the battery with a resistance fork fitted with a resistor corresponding to 150 A the voltage of each cell of a charged battery should be not less than 1.5 V at least during 5 sec.

at least during 5 sec.

The care of the battery consists in regular inspections, cleaning, charging and maintaining proper level and specific gravity of the elec-

Charging and maintaining proper level and specific gravity of the electrolyte.

Daily servicing:

1. Clean the battery from dirt. Wipe off spilled electrolyte. Clean corroded terminals and cable ends and coat them with vaseline.

2. Check condition of battery attachments.

2. Clear battery air vents.

After 1,000 km but not rarer than every 10—15 days in winter and

5—6 days in summer, do the following:
1. See that the electrolyte level is at the proper height. Add distillwater, if necessary.

2. Check the specific gravity of the battery solution for state of

charge.

3. See that the terminals are tight and the battery case is in good condition.

HEAD LAMPS

The head lamps are equipped with a semi-sealed optical unit incorporating a steel reflector, lens, and a two-filament bulb with socket and cap. The lower 50 c.p. filament located in the reflector focus is used for the country light; the upper 21 c.p. filament is for traffic light. The lens is held in place by bent reflector tongues. To replace a broken lens:

1. Unbend the reflector tongues, remove the damaged lens and rubber gasket.

2. Straighten up the reflector tongues and put in place the rubber

gasket.
3. Install a new lens and bend the tongues.
To adjust the head lamp beams:
1. Place the unloaded vehicle on a level floor, squarely facing an adjusting screen 7.5 m from the head lamps and remove head lamp

2. Turn the light on and see that the connections are correct and both head lamps flash on simultaneously.

54

3. Turn on the country light, cover one head lamp and adjust the other one by means of adjusting screws so that the hot spot on the screen is at a height of 725 mm from ground and 490 mm from the extensibility contains

screen is at a height of 725 mm from ground and 490 limit from the automobile center line.

4. Repeat the adjustment for the other lamp so as to position the upper limits of both hot spots on the same height.

The spollight lamp installed to the left of the windscreen serves for additional lighting of the road. The switch for this lamp is located under the light socket to the left of, and below, the instrument panel. The spollight lamp can be turned by the driver's hand through an opening in the canopy side flap.

STARTING MOTOR (Fig. 41)

The four-pole, four-brush type CT20 starting motor with series excitation is used. The starter pinion is engaged automatically by the overrunning clutch.

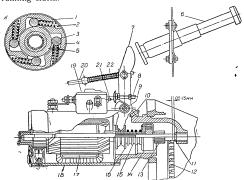


Fig. 41. Starting Motor and Engagement Mechanism

1 — outer case, 2 — spring, 3 — roller, 4 — sleeve body, 5 — inner case, 6 — petal, 7 — engagement lever, 8 — adjusting rod, 9 — spring floor spring floor plants, 10 — spring floor plants, 10 — spring floor plants, 10 — over-rounding-time spring, 16 — bushing, 17 — starting motor plantsure, 18 — starting motor body, 19 — switch, 20 — rod leading to coarse filter, 21 — rod, 22 — spring floor body, 19 — switch, 20 — rod leading to coarse filter, 21 — rod, 22 — spring floor body, 19 — switch, 20 — rod leading to coarse filter, 21 — rod, 22 — spring floor body, 19 — switch, 20 — rod leading to coarse filter, 21 — rod, 22 — spring floor body, 19 — switch, 20 — rod leading to coarse filter, 21 — rod, 22 — spring floor body, 19 — switch, 20 — rod leading to coarse filter, 21 — rod, 22 — spring floor body, 19 — switch, 20 — rod leading to coarse filter, 21 — rod, 22 — spring floor body, 19 — switch, 20 — rod leading to coarse filter, 21 — rod, 22 — spring floor body, 20 — rod leading to coarse filter, 21 — rod, 22 — spring floor body, 20 — rod, 22 — rod, 22 — rod, 22 — rod, 22 — rod, 23 — rod, 24 — rod,

The drive clutch should be adjusted with the starting motor removed from the engine.

1. The clearance between the starter pinion and thrust washer in the extreme engaged position should be from 0.5 to 1.5 mm. The clearance may be adjusted by the special adjusting screw.

2. The contacts of the electric starter switch should start to close when the starter pinion has moved away from the thrust washer no more than 4 mm which is ensured by turning the adjusting rod OUT. After the contacts of the starter switch have closed the drive rod of the coarse oil filter should have an additional Imm travel.

3. The contacts cutting in the additional resistor of the ignition coil should close either simultaneously with the electric starter switch or somewhat earlier.

The care of the starting motor consists in checking its connections and cables every 1,000 km. After 12,000 km the starting motor should be removed and blown out with compressed air. Inspect condition of the commutator and brushes. Brush spring tension should be 850 to 1,400 g.

Care of the instruments:

- 1. When removing the remote water thermometer and oil pressure gauge units as well as the gasoline level gauge rheostat insulate the cable ends to avoid short-circuiting. When installing the oil pressure gauge unit see that the "Bepx" (Top) mark is facing upwards.

 2. See that the cooling water level does not drop too low as this may cause damage to the water temperature gauge unit due to overheating.
- Once a year check the readings of the water temperature gauge by removing the unit and dipping it into hot water whose temperature is measured by a reference thermometer.
- 4. Once a year check the readings of the oil pressure gauge by means of a reference pressure gauge.

SPEEDOMETER AND FLEXIBLE SHAFT

The speedometer drive shaft is lubricated by a wick soaked with vaseline oil and placed in the hole in the speedometer tail piece. The hole is covered with a stamped brass plug. Every 25,000 km remove the speedometer, take out the plug and soak the wick with vaseline oil. Every 25,000 km or earlier if the automobile is operated in hot climate, add vaseline oil to the flexible shaft sheath. In winter vaseline oil should be replaced by spindle oil. Pack lubricant into the sheath by an ordinary grease gun.

by an ordinary grease gun.

BODY

The Γ A3-69 automobile is equipped with an all-metal open type two-door body with folding tailboard and removable canopy. The front seats are cushioned with collapsible backrests. Threeman seats located along the boards have semi-cushioned seats and backrests.

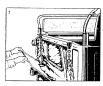
For transportation of goods the side seats are raised and secured

For transportation of goods the side seats are raised and secured by straps.

The automobile is equipped with a canvas canopy fixed on a dismountable metal frame. The doors are covered with removable side flaps. The frame, canopy and side flaps are stored inside the body so as not to block useful space: the two frame bows are so placed as to form side rails; the bow connecting members are secured under the side seats, the folded canopy is stored under the driver's seat and the side flaps are placed between the double walls of the tailboard.

Tool boxes are situated under the rear seats. The starting heater torch is secured in the left front tool box. The reserve oil can is located in the right front tool box. The rear boxes are empty.

The FA3-69A automobile is equipped with an all-metal, open type, four-door body. The rear part of the body is provided with a luggage compartment.





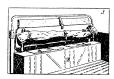
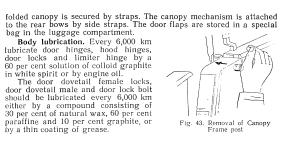




Fig. 42. Folding ΓΑ3-69 Automobile Canopy 1 — placing side flaps between double walls of tail board, 2 — placing folded canopy under front left seat, 3 — placing bow braces, 4 — conversion of bows into rails.

The canvas canopy is fixed on a dismountable frame. Both the canopy and frame are stored in the luggage compartment behind the rear seat. To fold the canopy remove two bolts attaching the canopy to the windscreen then disengage the two frame posts by depressing the dowel (Fig. 43) after which the canopy can be folded back, the mechanism is also folded and the canopy is placed on top of it. The



HEATING AND VENTILATION

The automobile is heated by hot water from the engine cooling system (Fig. 44). The water enters the special heater radiator mounted behind the instrument panel. The heater heats the air which is then forced into the body through a port located in front of the windscreen. The air is forced in by the oncoming air flow.

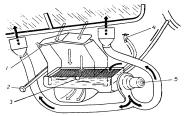
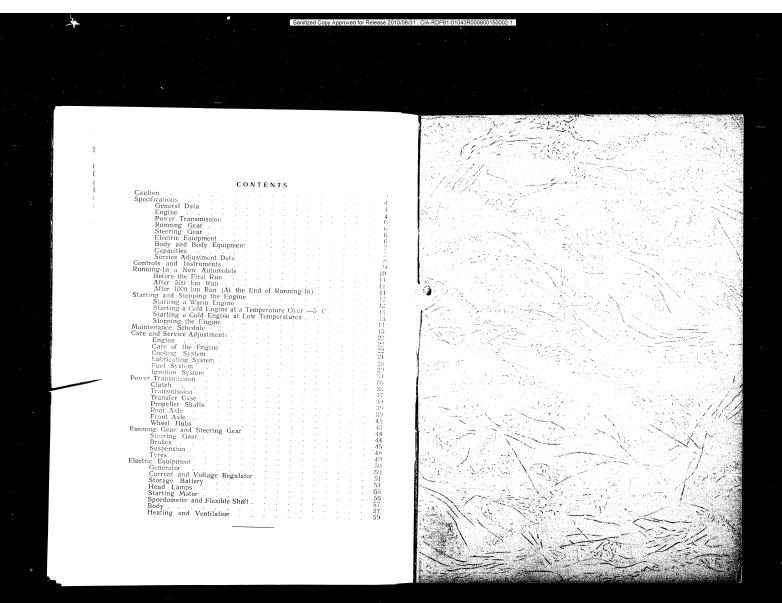


Fig. 44. Body Heating and Ventilation Diagram l- heater port, 2- port handle, 3- windscreen defroster ventilator motor switch, l- cock for control of delivery of hot water from cylinder head to heater radiator, 5- windscreen defroster ventilator motor.

Temperature control inside the body is effected by opening the heater port and the water shut-off cock located on the engine cylinder head. Windscreen defrosting is ensured by warm air supplied by the electric ventilator. The ventilator motor switch has three positions: middle — off, left — low speed, right — high speed.



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CABLES: STANKOIMPORT MOSCOW





VSESOJUZNOJE EXPORTNO-IMPORTNOJE OBJEDINENIJE STANKOIMPORT US S R MOSCOW

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LAPPING MACHINES
HONING MACHINES



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STANKOIMPORT

USSR

MOSCOW

This catalogue contains short specifications of the most common types of machine tools exported by the Vsesojuznoje Exportno-Importnoje Objedinenije "Stankoimport".

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The Machine Tools produced in the USSR are outstanding for their high efficiency, convenience and safety in operation and long service.

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Steady improvement of machine tool design in the USSP single-

Machine Tools.

Steady improvement of machine tool design in the USSR aims at the increase of productivity, accuracy, reliability and dependability of machine in operation, as well as the reduction of operator's fatigue by improving and convenient placing of all operating controls and the all-increasing automatization of operation.

The Vsesojuznoje Exportuo-Importnoje Objedinenije "Stanko-import" is able to offer a wide range of Machine Tools both universal and special types including Automatic Transfer Machines and Automatic Workshops.



HYDRAULIC UNIVERSAL GRINDING MACHINE

MODEL 3110



The 3110 Hydraulic Universal Grinder is designed for both external and internal cylindrical and taper grinding as well as for face grinding of parts held either between centers or in chucks.

The headstock and wheel head are of the swiveling type. The headstock spindle is driven by a two-speed electric motor through a Vee-belt drive.

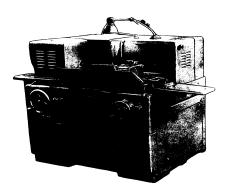
The table traverse is hydraulically operated.

	DI LICIT I	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	
Capacity		Speeds	
Height of centers, mm	70	Grinding wheel speed, r. p. m.	3000
Distance between centers, mm Maximum swing, mm	200 130	Internal grinding wheel speed, r, p, m,	15000
Recommended diameter of grinding, mm:		Drive	
Minimum	3		
Maximum	25	220/380 volt, 3 phase, 50 cycle	
Maximum grinding length, mm	200	A. C. motors:	
Diameter of hole ground, mm:		Headstock (two-speed mo-	
Minimum	6	tor): Power, kW	0.35/0.225
Maximum	25	Speeds, r. p. m.	3000/1500
Maximum length of hole	50	Wheel head:	
ground, mm	30	Power, kW	1
Table		Speed, r. p. m.	3000
		Hydraulic pump:	
Maximum table traverse, mm Swivel range of table	+ 5°:7°	Power, kW	0.6 1500
Swiver range of table		Speed, r. p. m.	1300
Wheel Head		Coolant pump: Power, kW	0.125
Maximum cross travel of		Speed, r. p. m.	3000
wheel head, mm	100	Speed, 1. p. m	
Maximum length of wheel		Space Occupied	
head rapid withdrawal, mm	15		
Maximum swivel of wheel	- 001	Floor space, mm	1085 970
head	180°	Height of machine, mm	1200
Diameter of grinding wheel,			
mm:	140	Weight	
Maximum	200	Net weight, kg	approx. 850
Maximum			



PRECISION CYLINDRICAL GRINDING MACHINE

MODEL 3153 M



The 3153 M Precision Cylindrical Grinder is designed for external cylindrical \mathcal{C}_{S}

The 3153 M Precision Cymurcal order of the 3153 M Precision Cymurcal grinding.

The work is driven by a two-speed A. C. motor.

The wheel head is mounted on roll ways.

The machine provides for high precision grinding, and it can be operated in a scated position.

All the main and most of the auxiliary motions of the machine are operated automatically.

Table and wheel head traverses are operated hydraulically.

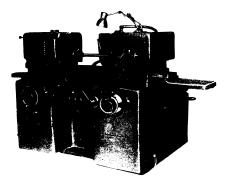
СТАНКОИМПОРТ

SPECIFIC	CATIONS
Capacity	Speeds
Height of centers over table, mm . 70 Distance between centers, mm . 500 Maximum swing, mm . 130 Recommended diameter of grinding, mm: Minimum . 7 Maximum . 30	Grinding wheel speeds, r. p. m. 1800; 2200 Work speeds, r. p. m. 150; 250; 300: 400: 500; 800 Range of table traverse speeds (hydraulic), m/min 0.2—6
Table	Drive
Maximum table longitudinal travese, mm 590	Power of electric motors, kW 4.4
Wheel Head Maximum cross travel of wheel head, mm	$\begin{array}{cccc} \textbf{Space Occupied} \\ \hline Floor space, mm & . & . & . 2000 \times 1260 \\ Height of machine, mm & . & . & 1250 \\ \hline \end{array}$
table: Minimum 0.0025 Maximum 0.025 Maximum grinding wheel di-	Weight
mensions, mm , , , $400 \times 40 \times 127$	Net weight, kg approx. 2100



HYDRAULIC UNIVERSAL GRINDING MACHINE

MODEL 312 M



The 312 M Universal Grinder is a high precision machine designed for both center- and chuck-type grinding operations.

The proportions of swing and length together with the swiveling headstock and wheel head enable this machine to grind all kinds of precision tool room work, as well as many small parts, on a production basis. This includes straight grinding, shoulder grinding, taper grinding, face grinding and internal grinding. The wheel head is fully universal and may be swiveled for grinding tapers longer than the width of the wheel. The machine is arranged for both hand and automatic feed to the wheel head at each table reversal.

The table is in two sections, the traversing carriage and the upper portion on which the headstock and footstock are mounted.

The top table can be swiveled for taper grinding. The carriage traverses

on which the headstock and footstock are mounted.

The top table can be swiveled for taper grinding. The carriage traverses either by hand or by hydraulic power. The hydraulic traverse gives smooth,

СТАНКОИМПОРТ

uniform speed to the carriage in either direction at any speed in the range of 0.2 to 6 m/min, and can be adjusted exactly to the requirements of the work. The stroke and reversal of the table are controlled by adjustable dogs. Power for the headstock drive is obtained from a 0.65 kW two-speed motor. The headstock unit may be swiveled for grinding tapered holes.

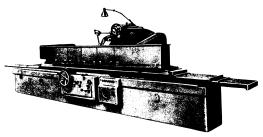
SPECIFICATIONS

or Ectr.	CHILOTE
Capacity Height of centers, mm 110 Distance between centers, mm 500	Work speeds, r. p. m 150: 250: 300: 400: 500: 800 Table traverse speeds (hydrau-
Maximum swing over table, mm	lic), m/min.: Minimum 0.2 Maximum 6
mm: Minimum	Drive 220 380 volt, 3 phase, 50 cycle A. C. motors:
Maximum 50 Maximum length of hole ground, mm	Speed, r. p. m 3000 Headstock:
Table Maximum traverse of table, mm	Speeds, r. p. m 1500 3000 Hydraulic pump:
Wheel Head Maximum cross travel of wheel head, mm	Coolant pump: Power, kW . 0.125 Speed, r. p. m. 3000
Speeds Speed of grinding wheel spindle, r. p. m	Space Occupied Floor space, mm
Speeds of internal grinding wheel spindle, r.p. m 8000 and 17000	



HYDRAULIC UNIVERSAL GRINDING MACHINE

MODEL 3141



The 3141 Hydraulic Universal Grinder is designed for the accurate and rapid performance of a large variety of grinding operations.

The proportions of swing and length together with full universal features of headstock and wheel head enable this machine to grind all kinds of precision tool room work, as well as many other parts, on a production basis. This includes straight grinding, shoulder grinding, taper grinding, face grinding.

The headstock unit has a type of drive and grand shape, madanism.

and internal grinding.

The headstock unit has a type of drive and speed change mechanism offering instantaneous changes of an infinite number of speeds ranging from 60 to 500 r.p.m. The headstock is fully universal and when swiveled as much as 90° enables face grinding of work with diameters larger than double height of centers. height of centers.

mergin or centers.

The work is driven either by face plate driver or by chuck mounted on the headstock spindle. For internal grinding, chucks may be applied with or

without work rests.

The wheel head is fully universal and may be swiveled for grinding tapers longer than the width of the wheel. The machine is arranged for both hand and hydraulic automatic feed to the wheel head at each table reversal.

CTAHKOUMITOPT

The table is in two sections, the traversing carriage and the upper portion.

The table is in two sections, the traversing earriage and the upper portion on which the headstock, footstock and work rests are mounted.

The top table can be swiveled for taper grinding. The carriage traverses either by hand or by hydraulic power. The hydraulic traverse gives smooth, uniform speed to the carriage in either direction at any speed in the range of 0.08 to 8 m/min, and can be adjusted exactly to the requirements of the work.

The stroke and reversal of the table are controlled by adjustable dogs.

SPECIFIC	CATIONS
Capacity	Without removing main grinding wheel 200
Maximum swing over table, mm	Diameter of hole that can be ground, mm: Minimum
Height of centers, mm	Maximum 300
Minimum 175	Speeds
Maximum	Range of work spindle speeds
Diameter that can be ground, mm:	(infinitely variable), r.p. m. 60-500 Speed of internal grinding
Minimum with wheel	wheel spindle, r. p. m 8400
340 mm diameter 10	Table traverse speeds (hydrau- lie), m/min.:
Maximum with work	Minimum 0.08
rest	Maximum 8
diameter 440	Drive
diameter	220/380 volt, 3 phase, 50 cycle
m 11 77 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	A. C. motors:
Table, Headstock and Footstock	Wheel head:
Maximum traverse of table,	Power, kW 10
mm	Speed, r. p. m
Swivel range of table + 10°; -2°	Internal grinding attach-
Taper hole in headstock	ment: Power, kW 1
spindle Morse No. 5	Power, kW
Taper hole in footstock spindle Morse No. 4	Hydraulic pump:
Headstock swivel	Power, kW 2.8
Headstock Swiver	Speed, r. p. m
Wheel Head	Coolant pump:
	Power, kW 0.125
Maximum cross travel of	Speed, r. p. m
wheel head, mm 395	Headstock drive:
Grinding wheel dimensions (diameter \times face \times hole),	A. C. motor:
mm:	Power, kW 1.7 Speed, r, p, m 3000
Cross slide swiveled 400 × 50 × 207	D. C. generator:
General usc 600 × 63 × 305	Power, kW 0.47—0.69
Wheel head swivel (wheel	D. C. motor:
400 mm diameter) 360°	Power, kW 0.25—0.5
Cross slide swivel 360°	Speeds, r. p. m 350-3000
Internal Grinding Attachment	Space Occupied
Spindle dimensions, mm 80×400	Floor space, mm 6540 × 2250
Maximum length of hole that	Height of machine, mm 1650
can be ground, mm:	*******
Main grinding wheel re-	Weight
moved 300	Net weight, kg approx. 6000



HYDRAULIC CYLINDRICAL GRINDING MACHINE

MODEL 3151



The 3151 Hydraulic Cylindrical Grinder is designed for precision center-type grinding operations. The machine meets in every detail all the require-ments of plain cylindrical and taper grinding in large or small lots of work, with assured accuracy and fine finish. The work is set on dead centers and is driven by a driving dog fixed in the headstock face plate. The headstock spindle is driven by a constant speed motor mounted on the headstock. Three work speeds are available,

work speeds are available.

The grinding wheel head is supported by large, well spaced guides. The rapid advance of wheel slide to the work, the cross feed at each table reversal and the rapid back movement of the wheel to its starting position are operated hydraulically. Manual cross feed of wheel is also provided.

The table is in two sections, the traversing carriage and the upper portion, on which the headstock, footstock and work rests are mounted. The top table is pivoted at its center and can be swiveled for taper grinding. The traverse of the table is automatic with head working the assistance are recommended.

of the table is automatic with hand motion for positioning purposes.

СТАНКОИМПОРТ

Power table traverse, hydraulically operated, provides an infinitely variable range of table speeds and can be adjusted exactly to the requirements of the work.

The stroke and reversal of the table are controlled by adjustable dogs.

The machine enables grinding up to a positive stop and provides means for compensating for wheel wear.

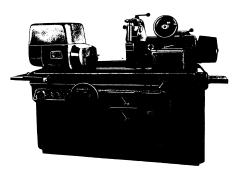
SPECIFICATIONS

Capacity		Graduation of cross feed dial,	
Maximum swing over table, mm	200	mm Grinding wheel dimen- sions, mm	0.005
Distance between centers, mm	750	Minimum diameter	450
Height of centers, mm	110	Maximum diameter .	600
Distance between wheel and		Face	63
work centers (without hy-		Hole diameter	305
draulic back movement of wheel), mm:		Speeds	
Minimum	230	Work speeds, r. p. m.,	: 150: 300
Maximum	400	Table traverse speeds (hydrau-	
Diameter that can be		lic), m/min.:	
ground, mm:		Minimum	0.10
Minimum with wheel		Maximum	10
440 mm diameter	10		
Maximum with work		Drive	
rest	60	220/380 volt, 3 phase, 50 cycle	
Maximum without work		A. C. motors:	
rest and wheel 600 mm		Wheel head:	
diameter	200	Power, kW	7
		Speed, r. p. m.	1500
		Headstock:	
Table, Headstock and For	otstock	Power, kW	1
Martinian toning of table		Speed, r. p. m.	1000
Maximum traverse of table	780	Hydraulic pump:	
(hydraulic or by hand), mm	780	Power kW	1.7
Maximum swivel of table,		Speed, r. p. m.	1500
degrees	6	Coolant pump:	
Taper hole in headstock and		Power, kW	0.125
footstock spindles \	lorse No. 4	Speed, r. p. m.	3000
		Space Occupied	
Wheel Head		Floor space, mm 31	00×1800
Maximum cross travel of		Height of machine, mm	1475
wheel head, mm:			1110
Manual	200	Weight	
Hydraulic (advance) .	50	Net weight, kg app	rox. 3200
my uraunt (auvance) .	30	aret weight, ag app	3200



CYLINDRICAL PLUNGE-CUT GRINDING MACHINE

MODEL 3152



The 3152 Cylindrical Plunge-Cut Grinder is designed for center-type grinding operations. The machine meets all the requirements of external cylindrical and taper grinding in large or small lots of work, with assured accuracy

and fine finish.

The work is set on dead centres and is driven by a driving dog fixed in the headstock face plate.

the neadstock tace plate.

The headstock spindle is driven by a constant speed motor mounted on the headstock. Three work speeds are available.

The rapid advance of wheel to the work, the slow cross feed of wheel (plunge-cut grinding) and the rapid back movement of the wheel to its starting position are operated hydraulically. Manual cross feed of wheel is also provided.

The machine enables grinding with automatic retreation of wheel is

The machine enables grinding with automatic retraction of wheel after the final size of work (according to 3rd class of accuracy) is reached.

СТАНКОИМПОРТ

The machine also enables manual grinding up to a positive stop and provides means for compensating for wheel wear.

The table can be swiveled for taper grinding. The traverse of the table is operated hydraulically. The machine can be used for both plunge-cut and traverse grinding.

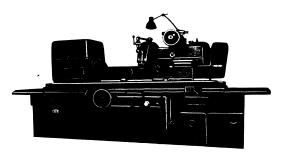
SPECIFICATIONS

Capacity	Maximum diameter 600
Maximum swing over table,	Face 63
mm	
Distance between centers, mm 50 Height of centers, mm 11	of morale (where on our contra
Distance between wheel and	ding), mm
work centers (without hy-	Speeds and Feeds
draulic back movement of	
wheel), mm: Minimum 23	Work speeds, r.p. m
Maximum 40	g draulic), m/min.:
Diameter that can be ground,	Minimum 0.1
mm: Minimum with wheel	Maximum 10 Range of wheel cross feeds
450 mm diameter , . , 1	p (plunge-cut grinding),
Maximum with work	mm/min, 0.1—1 5
rest 6	0 Drive
Maximum without work rest with wheel 600 mm	220 380 volt, 3 phase, 50 cycle
diameter 20	
	Wheel head:
Table, Headstock and Footstock	Power, kW
Maximum traverse of table,	Speed, r. p. m
mm	D Power, kW
Maximum swivel of table ±6 Taper hole in headstock and	Speed, r. p. m 1000
footstock spindles Morse No.	Hydraulic pump: Power, kW 1.7
	Speed, r. p. m
Wheel Head	Coolant pump:
Maximum cross travel of	Power, kW 0.125
wheel head, mm:	Speed, r. p. m 3000
Manual 200 Hydraulic (advance) . 56	
Graduation of cross feed dial,	Floor space, mm 2650 × 2020
mm 0.000	5 Height of machine, mm 1475
Grinding wheel dimen- sions, mm:	Weight
Minimum 450	



HYDRAULIC CYLINDRICAL GRINDING MACHINE

MODEL 3160



The 3160 Hydraulic Cylindrical Grinder is designed for precision centertype grinding operations. The machine meets in every detail all the requirements of plain, cylindrical and taper grinding in large or small lots of work, with assured accuracy and fine finish.

The work is set on dead centers and is driven by a driving dog fixed in the headstock face plate. The headstock spindle is driven by a constant speed motor mounted on the headstock. Three work speeds are available.

The grinding wheel head is supported by large, well spaced guides. The rapid advance of wheel slide to the work, the cross feed at each table reversal and the rapid back movement of the wheel to its starting position are operated hydraulically. Manual cross feed of wheel is also provided.

The table is in two sections, the traversing carriage and the upper portion, on which the headstock, footstock and work rests are mounted. The top table is pivoted at its center and can be swiveled for taper grinding. Power table

СТАНКОИМПОРТ

traverse, hydraulically operated, provides an infinitely variable range of table speeds and can be adjusted exactly to the requirements of the work.

The stroke and reversal of the table are controlled by adjustable dogs.

The machine enables grinding up to a stop and provides means for compensating for wheel wear.

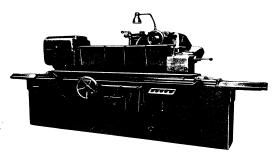
SPECIFICATIONS

Capacity Maximum swing over table, min	Graduation of cross feed dial, mm 0.005
wheel), mm: Minimum	Speeds Work speeds, r.p.m. 60: 120: 240 Table traverse speeds (hydraulic), m/min: Minimum 0.1 Maximum 10
Maximum with work rest	Drive 220/380 volt, 3 phase, 50 cycle A.C. motors: Wheel head: Power, kW
Table, Headstock and Footstock Maximum traverse of table, mm	Headstock:
Wheel Head Maximum cross travel of wheel head, mm: Manual	Space Occupied Floor space, mm . 4320 × 2250 Height of machine, mm . 1500 Weight Net weight, kg . approx. 6000



HYDRAULIC CYLINDRICAL GRINDING MACHINE

MODEL 3161



The 3161 Hydraulic Cylindrical Grinder is designed for precision centertype grinding operations. The machine meets in every detail all the requirements of plain cylindrical and taper grinding in large or small lots of work, with assured accuracy and fine finish.

The work is set on dead centers and is driven by a driving dog fixed in the headstock face plate. The headstock spindle is driven by a constant speed motor mounted on the headstock. Three work speeds are available.

The grinding wheel head is supported by large, well spaced guides. The rapid advance of wheel slide to the work, the cross feed at each table reversal and the rapid back movement of the wheel to its starting position are operating the starting of the starting position are operating the starting of the starting position are operating the starting position are operating the starting position are operating the starting of the starting position are operating the starting product of the starting position are operating the starting product of the starting position are operating the starting product of the

and the rapid back movement of the wheel to its starting position are operated hydraulically. Manual cross feed of wheel is also provided. The table is in two sections, the traversing carriage and the upper portion, on which the headstock, footstock and work rests are mounted. The top table is pivoted at its center and can be swiveled for taper grinding. The traverse of the table is automatic with hand motion for positioning purposes.

СТАНКОИМПОРТ

Power table traverse, hydraulically operated, provides an infinitely variable range of table speeds and can be adjusted exactly the requirements of the work.

The stroke and reversal of the table are controlled by adjustable dogs. The machine enables grinding up to a positive stop and provides means for compensating for wheel wear.

SPECIFICATIONS

Capacity Maximum swing over table, mm Distance between centers, mm Difference between wheel and work centers (without hy.	0 Maximum diameter 600
draulic back movement of wheel), mm:	Speeds 0. Work speeds, r. p. m
Minimum 23 Maximum 45 Diameter that can be ground, mm: Minimum with wheel	
450 mm diameter 1	0 Drive
Maximum with work rest	220/380 volt, 3 phase, 50 cycle A, C. motors: Wheel head:
diameter 30	0 Power, kW
Table, Headstock and Footstock	Power, kW 1.0 Speed, t.p.m 1000
Maximum traverse of table (hydraulic or by hand), mm Maximum swivel of table, degrees	Hydraulic pump: 1.7 Power, kW 1.7 Speed, r. p. m, 1500 6 Coolant pump: Power, kW 0.125
	Space Occupied
Wheel Head Maximum cross travel of	Floor space, mm
wheel head, mm: Manual 20	00 Weight 50 Net weight, kg approx. 4000



CYLINDRICAL PLUNGE-CUT GRINDING MACHINE

MODEL 3162



The 3162 Cylindrical Plunge-Cut Grinder is designed for center-type grinding operations. The machine meets all the requirements of external cylindrical and taper grinding in large or small lots of work, with assured accuracy and fine finish.

The work is set on dead centers and is driven by a driving dog fixed in

The work is set on dead centers and is driven by a driving dog fixed in the headstock face plate. The headstock spindle is driven by a constant speed motor mounted on the headstock. Three work speeds are available.

The rapid advance of wheel to the work, the slow cross feed of wheel (plunge-cut grinding) and the rapid back movement of the wheel to its starting position are operated hydraulically. Manual cross feed of wheel is also provided.

The machine enables grinding with automatic retraction of wheel after the final size of work (according to 3rd class of accuracy) is reached. The machine also enables manual grinding up to a positive stop and provides means for compensating for wheel wear.

СТАНКОИМПОРТ

The table can be swiveled for taper grinding. The traverse of the table is operated hydraulically. The machine can be used for both plunge-cut and traverse grinding.

SPECIFICATIONS

•			
Capacity Maximum swing over table,		Grinding wheel dimensions, mm: Minimum diameter	500
mm	300 1000	Maximum diameter	750
Distance between centers, mm Height of centers, mm	160	Face	75
Distance between wheel and	100	Hole diameter	305
work centers (without hy- draulic back movement of		Speeds and Feeds	
wheel), mm:	0.50	Work speeds, r. p. m 60:	120: 240
Minimum	250 500	Table traverse speeds (hy-	
Maximum Diameter that can be ground,	300	draulic), m/min.: Minimum	0.1
mm:		Maximum	10
Minimum with wheel		Range of wheel cross feeds	
500 mm diameter	10	(plunge-cut grinding), mm/min.	0.1 - 15
Maximum with work	60		
Maximum without work		Drive	
rest with wheel 750 mm		220/380 volt, 3 phase, 50 cycle	
diameter	250	A, C, motors: Wheel head:	
mate Western and Post	etock.	Power, kW	14
Table, Headstock and Foot	BIOCK	Speed, r. p. m.	1000
Maximum traverse of table (hydraulic and by hand), mm	1050	Headstock:	1.0
Maximum swivel of table,		Power, kW Speed, r. p. m	1000
degrees	7	Hydraulic pump:	
Taper hole in headstock and	arca No. 5	Power, kW	2.8
footstock spindles Mo) i sc 200. 5	Speed, r. p. m.	1500
Wheel Head		Coolant pump: Power, kW	0.125
Maximum cross travel of		Speed, r. p. m.	3000
wheel head, mm:			
Manual	250 50	Space Occupied	
Hydraulic (advance) . Graduation of cross feed dial,	50	Floor space, mm	20×2300 1500
mm	0.005	Height of machine, mm	1500
Maximum diameter reduction		Weight	
of work (plunge-cut grin-	1.6	Net weight, kg app	rox 6000
ding), mm	1.6	Net weight, kg app	



HYDRAULIC CYLINDRICAL GRINDING MACHINE

MODEL 3164



The 3164 Hydraulic Cylindrical Grinder is designed for precision centertype grinding operations. The machine meets in every detail all the requirements of plain cylindrical and taper grinding in large or small lots of work, with assured accuracy and fine finish.

The work is set on dead centers and is driven by a driving dog fixed in the headstock face plate. The headstock spindle is driven by a two-speed motor mounted on the headstock. Eight work speeds are available.

The grinding wheel head is supported by large, well spaced guides. The rapid advance of wheel slide to the work, the cross feed at each table reversal and the rapid back movement of the wheel to its starting position are operated hydraulically. Manual cross feed of wheel is also provided.

The table is in two sections, the traversing carriage and the upper portion, on which the headstock, footstock and steadies are mounted. The top table is privoted at its center and can be swiveled for taper grinding. The traverse of the table is automatic with hand motion for positioning purposes.

Power table traverse, hydraulically operated, provides an infinitely variable range of table speeds and can be adjusted exactly to the requirements of the work. The stroke and reversal of the table are controlled by adjustable dogs.

The machine enables grinding up to a positive ston and provides means.

adjustable dogs.

The machine enables grinding up to a positive stop and provides means for compensating for wheel wear.

СТАНКОИМПОРТ

SPECIFI	CATIONS
Capacity	Speeds
Maximum swing over table, mm	Work speeds, r.p. in. 30; 48; 60; 75; 90; 118; 150; 235 Table traverse speeds, m/min.: Minimum Maximum Maximum 6
wheel), mm: Minimum	Drive 220/380 volt, 3 phase, 50 cycle A. C. motors:
Minimum	Wheel head: Power, kW 14 Speed, r. p. m 1000
Table, Headstock and Footstock Maximum traverse of table, mm . 2000 Maximum svivel of table, degrees . 3 5 Taper hole in headstock and footstock spindles . Morse No. 6	Headstock: Power, kW. 2 3 Speeds, r, p. m. 750 1500 Hydraulie pump: Power, kW. 2.8 Speed, r, p. m. 1500 Coolant pump: Power, kW. 0 125
Wheel Head	Speed, r. p. m
Maximum cross travel of wheel head, mm: Manual	Space Occupied Floor space, mm
Minimum diameter 600 Maximum diameter 900 Maximum face 100 Hole diameter 305	Weight Net weight, kg approx, 10000



HYDRAULIC CYLINDRICAL GRINDING MACHINE

MODEL 3164 A



The 3164 A Hydraulic Cylindrical Grinding Machine is designed for precision center-type grinding operations. The machine meets in every detail all the requirements of plain cylindrical and taper grinding in large or small lots

the requirements of plain cylindrical and taper grinding in large or small lots of work, with assured accuracy and fine finish.

The work is set on dead centers and is driven by a driving dog fixed in the headstock face plate. The headstock spindle is driven by a two-speed motor mounted on the headstock. Eight work speeds are available.

The grinding wheel head is supported by large, well spaced guides. The rapid advance of wheel slide to the work, the cross feed at each table reversal and the rapid back movement of the wheel to its starting position are operated hydraulically. Manual cross feed of wheel is also provided. The table is in two sections, the traversing carriage and the upper portion, on which the headstock, footstock and steadies are mounted. The top table is pivoted at its center and can be swiveled for taper grinding. The traverse of the table is automatic with hand motion for positioning purposes.

Power table traverse, hydraulically operated, provides an infinitely variable range of table speeds and can be adjusted exactly to the requirements of the work. The stroke and reversal of the table are controlled by adjustable dogs.

СТАНКОИМПОРТ

The machine enables grinding up to a positive stop and provides means for compensating for wheel wear as well as for grinding with automatic stopping the pick feed action before the cross feed dial reaches zero, permit-

ting the operator to finish to size by hand.

The machine is equipped with five motors.

SPECIFICATIONS

Capacity Maximum swing over table, mm	Maximum diameter . 900 Maximum face . 100 Hole diameter . 305
Height of centers, mm 210	Speeds
Distance between wheel and work centers (without hy-	Work speeds, r. p. m. 30; 48; 60; 75; 90; 118; 150; 235
draulic back movement of	Table traverse speeds, m/min.:
wheel), mm:	Minimum 0.2
Minimum 320	Maximum 6
Maximum 650 Diameter that can be ground,	Drive
mm:	220/380 volt, 3 phase, 50 cycle
Minimum 40	A. C. motors:
Maximum 400	Wheel head:
	Power, kW 14
Table, Headstock and Footstock	Speed, r. p. m 1000
	Headstock (two-speed):
Maximum traverse of table	Power, kW 2 3
(hydraulic and by hand), mm 3000	Speed, r. p. m
Maximum swivel of table,	Hydraulic pump:
degrees	Power, kW 2.8
Typer hole in headstock and	Speed, r. p. m 1500
footstock spindles Morse No. 6	Coolant pump:
	Power, kW 0.125
Wheel Head	Speed, r. p. m 3000
Maximum cross travel of	Space Occupied
wheel head, mm:	Floor space, mm 8420 × 2560
Manual 305	Height of machine, mm
Hydraulic (advance) . 50	rieign of machine, min
Grinding wheel dimensions,	Weight
Minimum diameter 600	



HEAVY DUTY CYLINDRICAL GRINDING MACHINE

MODEL 3172



The 3172 Cylindrical Grinder is designed for center-type grinding opera-

tions. The machine meets all the requirements of plain cylindrical and taper grinding optical.

The work is set on dead centers and is driven by a driving dog fixed in the headstock face plate. Power for the headstock drive as well as for the table traverse is obtained from D.C. motors providing infinitely variable work and table traverse needs.

table traverse is obtained from D. C. motors providing infinitely variable work and table traverse speeds.

The grinding wheel head is supported by large, well spaced guides. The rapid advance of wheel to the work, the cross feed at each table reversal and the rapid back movement of the wheel to its starting position are operated hydraulically. Manual cross feed of wheel is also provided. The table is in two sections, the traversing carriage and the upper portion, on which the headstock, footstock and steadies are mounted. The top table is pivoted at its center and can be swiveled for taper grinding.

Power table traverse, electrically operated, provides an infinitely variable range of table speeds and can be adjusted exactly to the requirements of the work. The stroke and reversal of the table are controlled by adjustable dogs.

СТАНКОИМПОРТ

The machine enables grinding up to a positive stop and provides means for compensating for wheel wear.

The correct table and work speeds are indicated by direct reading instru-

ments mounted on the control panel.

SPECIFICATIONS

	3F LCII I	011110110	
Capacity		Speeds	
Maximum swing over table,		Work speeds (infinitely	
mm	550	variable), r. p. m:	
Distance between centers, mm	4000	Minimum	12
Height of centers, mm	300	Maximum	60
Distance between wheel and	000	Table traverse speeds (infini-	00
work centers (without hy-		tely variable), m/min.:	
draulic back movement of		Minimum	0.1
wheel). mm:			0.1 2.5
Minimum	380	Maximum	2.5
		Drive	
	830		
Diameter that can be ground,		220/380 volt, 3 phase, 50 cycle	
mm:		A. C. motors:	
Minimum with wheel		Wheel head:	
600 mm diameter	0	Power, kW	20
Maximum with wheel		Speed, r. p. m.	1000
900 mm diameter	550	Hydraulic pump:	
Maximum length that can be		Power, kW	2.8
ground, mm	4000	Speed, r. p. m.	1500
Maximum weight of work, kg	5000	Coolant pump:	1000
		Power, kW	0.65
Table, Headstock and Foo	tstock	Speed, r. p. m.	3000
Maximum traverse of table,	tstock	Wheel head lubricating	3000
Maximum traverse of table,	tstock 4500	Wheel head lubricating pump:	
Maximum traverse of table,		Wheel head lubricating pump: Power, kW	0.25
Maximum traverse of table, mm Maximum swivel of table,		Wheel head lubricating pump: Power, kW Speed, r. p. m.	
Maximum traverse of table, mm Maximum swivel of table, degrees	4500	Wheel head lubricating pump: Power, kW Speed, r. p. m. Center grinding fixture:	0.25 1500
Maximum traverse of table, mm Maximum swivel of table, degrees Taper hole in headstock and	4500 6	Wheel head lubricating pump: Power, kW Speed, r. p. m. Center grinding fixture: Power, kW	0.25 1500 0.6
Maximum traverse of table, mm Maximum swivel of table, degrees	4500	Wheel head lubricating pump: Power, kW Speed, r. p. m. Center grinding fixture: Power, kW Speed, r. p. m.	0.25 1500
Maximum traverse of table, mm Maximum swivel of table, degrees Taper hole in headstock and footstock spindles	4500 6	Wheel head lubricating pump: Power, kW Speed, r. p. m. Center grinding fixture: Power, kW Speed, r. p. m. D, C, motors:	0.25 1500 0.6
Maximum traverse of table, mm Maximum swivel of table, degrees Taper hole in headstock and	4500 6	Wheel head lubricating pump: Power, kW	0.25 1500 0.6 1500
Maximum traverse of table, mm Maximum swivel of table, degrees Taper hole in headstock and footstock spindles Wheel Head	4500 6	Wheel head lubricating pump: Power, kW . Speed, r.p. m. Center grinding fixture: Power, kW . Speed, r.p. m. D. C. motors: Headstock: Power, kW .	0.25 1500 0.6 1500
Maximum traverse of table, mm Maximum served of table, degrees. Taper hole in headstock and footstock served of table. Wheel Head Maximum cross travel of	4500 6	Wheel head lubricating pump: Power, kW Speed, r.p.m. Center grinding fixture: Power, kW D.C. Speed, r.p.m. D.C. Beed, r.p.m. Power, kW Speeds, r.p.m.	0.25 1500 0.6 1500
Maximum traverse of table, mm. Maximum swivel of table, degrees. Taper hole in headstock and footstock spindles. Wheel Head Maximum cross travel of wheel head, mm:	4500 6 Metric 80	Wheel head lubricating pump: Power, kW Speed, r.p.m. Speed, r.p.m. Power, kW Speed, r.p.m. D.C. motors: Headstork Fower, kW The Common the comm	0.25 1500 0.6 1500
Maximum traverse of table, mm Maximum swivel of table, degrees. Taper hole in headstock and footstock spindles. Wheel Head Maximum cross travel of wheel head, mm Manual	4500 6 Metric 80 250	Wheel head lubricating pump: Power, kW Speed, r.p.m. Center grinding fixture: Power, kW Speed, r.p.m. D. C. Speed, r.p.m. D. C. Boddstock: Power, kW Speeds, r.p.m. Table traverse: Power, kW	0.25 1500 0.6 1500 9 150—1500
Maximum traverse of table, min Maximum swivel of table, degrees. Taper hole in headstock and foot stock spindles. Wheel Head Maximum cross travel of wheel head, min: Hydraulic (advance)	4500 6 Metric 80	Wheel head lubricating pump: Power, kW Speed, r.p.m. Speed, r.p.m. Power, kW Speed, r.p.m. D.C. motors: Headstork Fower, kW The Common the comm	0.25 1500 0.6 1500 9 150—1500
Maximum traverse of table, mm Maximum swivel of table, degrees Taper hole in headstock and footstock spindles Wheel Head Maximum cross travel of wheel head, mm: Hydraulic (advance) Maximum travel of wheel	4500 6 Metric 80 250 100	Wheel head lubricating pump: Power, kW Speed, r.p. m. Center grinding fixture: Power, kW Speed, r.p. m. D. C. motors: Headstele, Speed, r.p. m. Table traverse: Power, kW Speeds, r.p. m. Table traverse: Power, kW Speeds, r.p. m.	0.25 1500 0.6 1500 9 150—1500
Maximum traverse of table, min Maximum swivel of table, degrees. Taper hole in headstock and footstock spindles wheel Head Maximum cross travel of wheel head, min Hydraulic (advance) Maximum travel of wheel side, mm	4500 6 Metric 80 250	Wheel head lubricating pump: Power, kW Speed, r.p.m. Center grinding fixture: Power, kW Speed, r.p.m. D. C. Speed, r.p.m. D. C. Boddstock: Power, kW Speeds, r.p.m. Table traverse: Power, kW	0.25 1500 0.6 1500 9 150—1500
Maximum traverse of table, mm Maximum swivel of table, degrees Taper hole in headstock and footstock spindles Wheel Head Maximum cross travel of wheel head, mm: Manual Maximum travel of wheel slide, mm Grinding wheel dimensions,	4500 6 Metric 80 250 100	Wheel head lubricating pump: Power, kW Speed, r. p. m. Certain Comments of the Comments Speed, r. p. m. D. C. motors: Headstock: Power, kW Speed, r. p. m. The Comments Speeds, r. p. m. Speeds, r. p. m. Speeds, r. p. m. Speeds, r. p. m. Space Occupied	0.25 1500 0.6 1500 9 150—1500 40—1000
Maximum traverse of table, mm Maximum swivel of table, degrees Taper fole in headstock and footstock spindles Wheel Head Maximum cross travel of wheel head, mm: Manual Hydraulic (advance) Maximum travel of wheel spindles, mm Glidg, mm Glidg, mm Glidg, mm Glidg, wheel dimension, mm;	4500 6 Metric 80 250 100 200	Wheel head lubricating pump: Power, kW Speed, r.p. m. Center grimling fixture: Power, kW Speed, r.p. m. D. C. motors: Hower, kW Speeds, r.p. m. Table traverse: Power, kW Speeds, r.p. m. Table traverse: Power, kW Speeds, r.p. m. Speeds, r.p. m. Table traverse: Power, kW Speeds, r.p. m. Table traverse: Power, kW Speeds, r.p. m. Table traverse: Power, kW Speeds, r.p. m.	0.25 1500 0.6 1500 150 150 16 40 1000 100×4100
Maximum traverse of table, mm Maximum swivel of table, degrees "aper hole in headstock and footstock spindles Wheel Head Maximum cross travel of wheel head, mm: Manual Marydraulic (advance) Maximum travel of wheel side, mm: Griding wheel dimension, and minimum diameter	4500 6 Metric 80 250 100 200 600	Wheel head lubricating pump: Power, kW Speed, r. p. m. Certain Comments of the Comments Speed, r. p. m. D. C. motors: Headstock: Power, kW Speed, r. p. m. The Comments Speeds, r. p. m. Speeds, r. p. m. Speeds, r. p. m. Speeds, r. p. m. Space Occupied	0.25 1500 0.6 1500 9 150—1500 40—1000
Maximum traverse of table, mm Maximum swivel of table, degrees Taper hole in headstock and footstock spindles Wheel Head Maximum cross travel of wheel head, mm Hydraulic (advance) Maximum travel of wheel slide, mm Grinding wheel dimension, mm Minimum diameter Maximum diameter Maximum diameter	4500 6 Metric 80 250 100 200 600 900	Wheel head lubricating pump: Power, kW Powerl, r. m. Contest, r. p. m. Contest, r. p. m. D. C. motors: Headstock: Headstock: Speeds, r. p. m. Table traverse: Power, kW Speeds, r. p. m. Speeds, r. p. m. Table traverse: Power, kW Speeds, r. p. m. Lead traverse: Ploor space, mm Lead traverse: Lead traverse: Power for the traverse: Lead t	0.25 1500 0.6 1500 150 150 16 40 1000 100×4100
Maximum traverse of table, mm Maximum swivel of table, degrees "aper hole in headstock and footstock spindles Wheel Head Maximum cross travel of wheel head, mm: Manual Marydraulic (advance) Maximum travel of wheel side, mm: Griding wheel dimension, and minimum diameter	4500 6 Metric 80 250 100 200 600	Wheel head lubricating pump: Power, kW Speed, r.p. m. Center grimling fixture: Power, kW Speed, r.p. m. D. C. motors: Hower, kW Speeds, r.p. m. Table traverse: Power, kW Speeds, r.p. m. Table traverse: Power, kW Speeds, r.p. m. Speeds, r.p. m. Table traverse: Power, kW Speeds, r.p. m. Table traverse: Power, kW Speeds, r.p. m. Table traverse: Power, kW Speeds, r.p. m.	0.25 1500 0.6 1500 $150-1500$ $40-1000$ 100×4100 2260



HEAVY DUTY CYLINDRICAL GRINDING MACHINE

MODEL 3174



The 3174 Cylindrical Grinder is designed for center-type grinding operations. The machine meets all the requirements of plain cylindrical and taper

grinding of large and heavy work, with assured accuracy and finish.

The work is set on dead centers and is driven by a driving dog fixed in the headstock face plate.

Power for the headstock drive as well as for the table traverse is obtained

from D.C. motors providing infinitely variable work and table traverse

The grinding wheel head is supported by large, well spaced guides. The The grinding wheel head is supported by large, well spaced guides. The rapid advance of wheel to the work, the cross feed at each table reversal and the rapid back movement of the wheel to its starting position are operated hydraulically. Manual cross feed of wheel is also provided.

The table is in two sections, the traversing carriage and the upper portion, on which the headstock, footstock and steadies are mounted.

The top table is pivoted at its center and can be swiveled for taper grinding.

Power table traverse, electrically operated, provides an infinitely variable range of table speeds and can be adjusted exactly to the requirements of the work. The stroke and reversal of the table are controlled by adjustable dogs.

The machine enables grinding up to a positive stop and provides means

for compensating for wheel wear.

The correct table and work speeds are indicated by direct reading instru-

ments mounted on the control panel.

СТАНКОИМПОРТ

Capacity		Speeds	
Maximum swing over table,		Work speeds (infinitely	
mm	750	variable), r. p. m.:	
Distance between centers, mm	5000	Minimum	
		Maximum	40
Height of centers, mm	400	Table traverse speeds (infini-	
Distance between wheel and		tely variable), m/min.:	
work centers (without hy.		Minimum	0.
draulic back movement of		Maximum	2.5
wheel), mm:		Maximum , ,	2
Minimum	400	Drive	
Maximum	725	220/380 volt, 3 phase, 50 cycle	
Diameter that can be ground,		A. C. motors:	
mm:		Wheel head:	
Minimum	100	wneer nead:	-
Maximum	700	Power, kW	20
Maximum weight of work, kg	7500	Speed, r. p. m.	1000
		Hydraulic pump:	
		Power, kW	2.4
		Speed, r. p. m.	1500
Table, Headstock and Foo	otstock	Coolant pump:	
Maximum traverse of table,		Power, kW	0.6
	6000	Speed, r. p. m.	3000
mm	0000	Wheel head lubricating	
degrees	4	pump:	
	4	Power, kW	0.25
Taper hole in headstock and	Martin 100	Speed, r. p. m.	1500
footstock spindles	Metric 100	Center grinding fixtur.	0.6
		Power, kW	1500
		Speed, r. p. m	1500
Wheel Head		Headstock:	
		Power, kW	
Maximum cross travel of		Speeds, r. p. m.	150-1500
wheel head, mm:		Table traverse:	1301300
Manual	250	Power, kW	1.0
Hydraulic (advance) .	100	Speeds, r. p. m.	40-1000
Maximum travel of wheel		Specus, 1. p. m	40-1000
slide, mm	200	Space Occupied	
Grinding wheel dimensions,			
mm:		Floor space, mm 14	2250
Minimum diameter	600	Height of machine, mm	2250
Maximum diameter	900	Weight	
Face	100		
Hole diameter	305	Net weight, kg app	orox, 40000



HEAVY DUTY CYLINDRICAL GRINDING MACHINE

MODEL XIII-80



The XIII-80 Cylindrical Grinder is designed for center-type grinding operations. The machine meets all the requirements of plain cylindrical grinding of large and heavy work, with assured accuracy and fine finish.

The work is set between dead centers and on special steady rests and is driven by a driving dog fixed in the headstock face plate. Power for the headstock drive as well as for the table traverse is obtained from D. C. motors

headstock drive as well as for the table traverse is obtained from D. C. motors providing infinitely variable work and table traverse speeds.

The grinding wheel head is supported by large, well spaced guides. The rapid advance of wheel to the work and the rapid back movement of the wheel to its starting position are operated hydraulically.

Power table traverse, electrically operated, provides an infinitely variable range of table speeds and can be adjusted exactly to the requirements of the work. The stroke and reversal of the table are controlled by adjustable dogs.

The machine enables grinding up to a positive ston and provides means

The machine enables grinding up to a positive stop and provides means for compensating for wheel wear.

The correct table and work speeds are indicated by direct reading instruments mounted on the control panel.

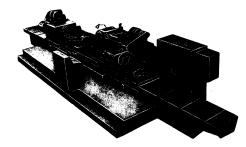
СТАНКОИМПОРТ

city Table traverse speeds (infini-	
r table, tely variable), m/min.:	
750 Minimum	0.1
ers, mm 8000 Maximum	2.5
400	
cel and	
Drive	
400 220/380 volt, 3 phase, 50 cycle	
A C motore	
ground, Wheel head:	
Down 1 W	20
100 Cooul so m	1000
can be Rydraulic pump: Power, kW	1.7
Speed, r. p. m.	1500
and Footstock Coolant pump:	
Power, kW	0.65
f table, Speed, r. p. m.	3000
Lubricating pump.	
Marie 100	0.25
	1500
Head Center grinding fixture:	
rower, KW	1.0
ivel of Speed, r. p. m	1500
D. C. motors: Headstock:	
nce) 100 Power kW	9
wheel Speeds, r. p. m 150—	
200 Table traverse:	1000
ensions, Power, kW	1.6
	-1000
ter 600	
eter 900	
100 Space Occupied	
	3700
Floor space, mm 20100 ×	
ds Height of machine, mm	2250
ds Height of machine, mm ly	
ds Height of machine, mm	2250



HEAVY DUTY CYLINDRICAL GRINDING MACHINE

MODEL XIII-84



The XIII-84 Cylindrical Grinder is designed for center-type grinding

The XIII-84 Cylindrical Grinder is designed for center-type grinding operations. The machine meets all the requirements of plain cylindrical and taper grinding of large and heavy work, with assured accuracy and finish. The work is set between dead centers and on special steady rests and is driven by a driving dog fixed in the headstock face plate.

Power for the headstock drive as well as for the table traverse is obtained from D.C. motors providing infinitely variable work and table traverse

The grinding wheel head is supported by large, well spaced guides. The rapid advance of wheel to the work and the rapid back movement of the wheel to its starting position are obtained from A. C. motor. Cross feed of wheel head is operated hydraulically.

The table is in two sections, the traversing carriage and the upper portion, on which the headstock, footstock and steadies are mounted.

The top table is pivoted at its center and can be swiveled for taper carrieling. grinding.

СТАНКОИМПОРТ

Power table traverse, electrically operated, provides an infinitely variable range of table speeds and can be adjusted exactly to the requirements of the work. The stroke and reversal of the table are controlled by adjustable dogs. The machine enables grinding up to a positive stop and provides means for compressing for the provides means.

for compensating for wheel wear.

The correct table traverse and work speeds are indicated by direct reading instruments mounted on the control panel.

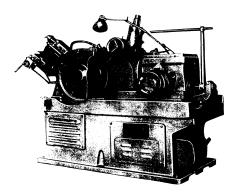
SPECIFICATIONS

Capacity Maximum swing over table, mm Distance between centers, mm Height of centers, mm Distance between wheel and	750 4000 400	Table traverse speeds (infinitely variable), m/min.: Minimum
work centers, mm: Minimum Maximum Diameter that can be ground, mm: Minimum Maximum Maximum Maximum weight of work, kg	320 830 80 750 5000	220/380 volt, 3 phase, 50 cycle A.C. motors: Wheel head: Power, kW 20 Speed, r.p.m. 1000 Hydraulic pump: 1.7 Power, kW 1.7 Speed, r.p.m. 1500
Table, Headstock and Foots Maximum traverse of table, mm Maximum swivel of table Taper hole in headstock and footstock spindles	4500 8	Wheel head traverse:
Wheel Head Maximum cross travel of wheel head, mm Maximum travel of wheel slide, mm Grinding wheel dimensions, mm: Minimum diameter Maximum diameter Maximum face Maximum face Hole diameter	310 200 600 900 75 200 305	Speed, r. p. m. 3000
Speeds Work speeds (infinitely variable), r. p. m.: Minimum Maximum	12 60	Space Occupied Floor space, min 12000 × 3850 Height of machine, min 2210 Weight Net weight, kg appox. 32000



CENTERLESS GRINDING MACHINE

MODEL 3180



The 3180 Centerless Grinding Machine is designed for external centerless grinding a very wide range of work including plain cylindrical, taper, shouldered, formed and multi-diameter in lot and mass production.

The machine has two wheels: a high speed grinding wheel and an opposed slowly rotating regulating wheel. A work rest supports the work during grinding. The grinding wheel serves solely for grinding purposes, while the regulating wheel controls sizing, speed of work rotation and the longitudinal feeding movement of the work.

regulating wheel controls sizing, speed of work obstacts and the feeding movement of the work.

There are three principal methods of grinding the work: through-feed, infeed, and combination infeed and through-feed. Plain cylindrical parts are ground by the through-feed method. The work pieces are fed in at one side and pass between the grinding and regulating wheels leaving the machine at the other side. Workpieces having a form or shoulder are ground by the

СТАНКОИМПОРТ

infeed method. The work is placed on the work rest with wheel withdrawn, the wheel receives then a cross feed up to a stop; on completion of operation the work is automatically ejected.

The work speed depends on the regulating wheel speed, this being changed

The work speed depends on the explanation by pick-off gears.

The angle at which the regulating wheel is set and its speed determine the longitudinal feed of work through the machine for through-feed method. Truing of the grinding and regulating wheels is performed with special

SPECIFICATIONS

Capacity Minimum and maximum diameter of work to be ground in standard attachment, mm	3—75	Number of regulating wheel speeds
Grinding Wheel		Drive 220/380 volt, 3 phase, 50 cycle
meter of grinding wheel, mm Maximum width of grinding	395—500 150	A. C. motors: Grinding wheel: Power, kW
wheel, mm Maximum swivel of grinding wheel truing device	±5°	Speed, r. p. m
Regulating Wheel Maximum swivel of regulating		Speed, r. p. m. 1500 Hydraulic pump: 0.6 Power, kW 0.6 Speed, r. p. m. 1500
wheel head Minimum and maximum dia- meter of regulating wheel, mm	260300	Coolant pump: Power, kW
Maximum width of regulating wheel, mm	150	Space Occupied Floor space, mm
Speeds Speed of grinding wheel,		Height of machine, mm 1620 Weight
r. p. m.	1200	Net weight, kg approx. 3600



CENTERLESS GRINDING MACHINE

MODEL 3 A 182



The 3 A 182 Centerless Grinding Machine is designed for centerless grinding a very wide range of work including plain cylindrical, taper, shouldered,

formed and multi-diameter.

The machine has two wheels: a high speed grinding wheel and an opposed slowly rotating regulating wheel, forming a grinding throat between them. A work rest in the throat supports the work during grinding. The grinding wheel serves solely for grinding purposes, while the regulating wheel controls sizing, speed of work rotation and the longitudinal feeding movement of the work.

There are three principal methods of grinding the work: through-feed, infeed, and combination infeed and through-feed. Plain cylindrical parts are ground by the through-feed method. The workpieces are fed in at one side and pass between the grinding and regulating wheels leaving the machine

at the other side.

Workpieces having a form or shoulder are ground by the infeed method. The workpiece is placed on the work rest with the wheel withdrawn, the wheel receives then a cross feed up to a stop; on completion of operation the work is automatically ejected.

The work speed depends on the number of revolutions per minute of the regulating wheel.

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The regulating wheel speed and the grinding wheel cross feed are changed by pick-off gears.

The angle at which the regulating wheel is set and its speed determine

the longitudinal feed of work through the machine for through-feed method.

Truing of the grinding and regulating wheels is performed with special truing devices.

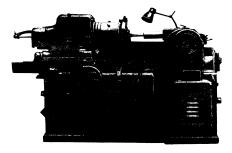
SPECIFICATIONS

Capacity Maximum grinding diameter, mm	150	Range of regulating wheel speeds, r.p.m 11—300
Range of recommended grin- ding diameters, mm	10-75	220/380 volt, 3 phase, 50 cycle
and diameters, init	20 .0	A. C. motors:
Grinding Wheel		Grinding wheel:
Grinding wheel dimensions,		Power, kW 40
mm:		Speed, r. p. m 1500
Maximum diameter	500	Regulating wheel:
Minimum diameter	380	Power, kW 4.5
Maximum width (sectio-	000	Speed, r. p. m 1500
nal wheel)	800	Grinding wheel feed:
Maximum travel of grinding	000	Power, kW 1
wheel head, mm	200	Speed, r. p. m 1000
,	200	Wheel truing devices
Regulating Wheel		(2 pcs.):
		Power, kW 0.15
Regulating wheel dimensions,		Speed, r. p. m 3000
mm:		Machine lubricating:
Maximum diameter	350	Power, kW 0.65
Minimum diameter	290	Speed, r. p. m
Maximum width (sec-		Coolant pump:
tional wheel)	800	Power, kW 0.65
Maximum swivel of spindle .	5°	Speed, r. p. m
Maximum travel of regulating		
wheel head, mm	150	Space Occupied
		Floor space, mm 3600 × 2310
Speeds		Height of machine, mm 1310
Grinding wheel speed, r. p. m.	1370	
Number of regulating wheel		Weight
speeds	7	Net weight kg approx. 11000



INTERNAL GRINDING MACHINE

MODEL 3A240



The 3A240 Hydraulic Internal Grinding Machine is designed for grinding straight and tapered holes.

The work to be ground is held in a chuck mounted on the spindle of the

In work to be ground is neld in a cruck mounted on the spinder of the work head. The work head spindle is driven by a Vee-belt from a three-speed motor mounted on the work head assembly. The work head base is of swiveling type providing for grinding a maximum included angle of 20°.

Power traverse of the table carrying the work head is operated hydrauli-

Fower traverse of the table carrying the work need is operated hydraulic cally, the speed being controlled by a hydraulic control valve.

Hand table travel used for positioning purposes is controlled with the large diameter handwheel. The stroke of the table is set by adjustable dogs. The hand travel and hydraulic traverse of the table are interlocked.

The grinding wheel spindle is driven from a motor mounted on the bed.

The automatic cross feed to the cross slide carrying the wheel head is applied through a ratchet mechanism. Sensitive hand motion is also provided. The automatic feed mechanism operates at every other reversal of the table. The wheel truing device has micrometer adjustment to the diamond. The machine is equipped with three motors.

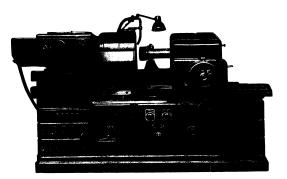
СТАНКОИМПОРТ

SPECIFICATIONS			
Capacity		Speeds and Feeds	
Diameter of hole that can be		Work head spindle speeds, r.p.m 180: 290; 570	
ground, mm: Minimum Maximum Maximum Hagth that can be	$^{12}_{100}$	Wheel head spindle speeds, r.p.m. 15000 Table speeds (hydraulic),	
ground, mm	130	m/min.: Minimum 0.3	
Maximum swing, mm: Inside water guard Without water guard .	240 500	Maximum 8 Wheel head cross feed per	
Distance from center of spindle to table, mm Grinding wheel cross move-	268	stroke of table, mm: Minimum . 0.001 Maximum . 0.005	
ment to center of work		Drive	
head, mm: Forward Backward Maximum distance from work	25 15	380 volt, 3 phase, 50 cycle A. C. motors: Wheel head and hydraulic	
head spindle to wheel head flange, mm	670	pump: Power, kW 2.8 Speed, r. p. m	
Table, Work Head, Wheel Head	d	Work head (three-speed):	
Maximum traverse of table, mm Swivel of work head for taper	380	Power, kW 0.35'0.35'0.42 Speeds, r. p. m 1000'1500'3000 Coolant pump:	
grinding, degrees	10	Power, kW 0.125 Speed, r, p, m, 3000	
Work head spindle hole dia- meter, mm	27	Space Occupied	
wheel head slide, mm Grinding wheel dimensions, mm:	40	Floor space, mm 2100×1105 Height of machine, mm	
Minimum diameter Maximum diameter	10 80	Weight	
Maximum diameter Maximum face	50	Net weight, kg approx. 1900	



INTERNAL GRINDING MACHINE

MODEL 3A 250



The 3A250 Hydraulic Internal Grinding Machine is designed for grinding straight and tapered holes.

The work to be ground is held in a chuck mounted on the spindle of the work head. The work head spindle is driven by a two-speed motor, the work speeds being stepless regulated by means of a Vee-belt variable speed unit. The work head base is of swiveling type providing for grinding a maximum included angle of 60°.

Power traverse of the table carrying the wheel head is operated hydraulically, the speed being controlled by a hydraulic control valve. Hand table travel used for positioning purposes is also provided. The stroke of the table is set by adjustable dogs.

The grinding wheel spindle is driven from a separate electric motor. The automatic cross feed to the cross slide carrying the wheel head is applied

СТАНКОИМПОРТ

through a ratchet mechanism. The automatic feed mechanism operates at

riffough a fatcher mechanism. The automatic red incumains operators every other reversal of the table. Sensitive hand motion is also provided.

Truing of the grinding wheel is effected by means of a special wheel truing device by either a diamond or dresser.

The machine is equipped with four motors.

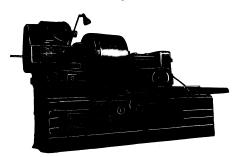
SPECIFICATIONS

Capacity Diameter of hole that can be		Range of work head spindle speeds (infinitely variable),
ground, mm: Minimum Maximum Maximum length that can be	50 200	r.p. m.: First range
ground, mm	200 420 620	Minimum 0.8 Maximum 10 Wheel head cross feed per stroke of table mm:
spindle to table, mm Maximum distance from work head spindle to wheel head	315	Minimum 0.0025 Maximum 0.0125
flange, mm Grinding wheel cross move- ment to center of work head mm:	900	Drive 380 volt, 3 phase, 50 cycle A.C. motors: Wheel head:
Forward Backward	$\begin{array}{c} 25 \\ 110 \end{array}$	Power, kW 4.5 Speed, r. p. m 3000 Work head (two-speed):
Table, Work Head, Wheel Head Maximum traverse of table (hydraulic and by hand),		Power, kW 0.7/1.2 Speeds, r.p.m
mm Swivel of work head for taper	500 30	Power, kW 2.8 Speed, r. p. m 1500 Coolant pump:
grinding, degrees Grinding wheel dimensions, mm:		Power, kW 0.125 Speed, r. p. m 3000
Minimum diameter Maximum diameter Maximum face	40 150 50	Space Occupied Floor space, mm 2700 × 1350 Height of machine, mm 1420
Speeds and Feeds		Troight of third party and
Wheel head spindle speed, r.p.m	0000	Weight Net weight, kg approx. 3300



INTERNAL GRINDING MACHINE

MODEL 3260



The 3260 Hydraulic Internal Grinding Machine is designed for grinding

The 3260 Hydraulic Internal Grinding Machine is designed for grinding straight and tapered holes.

The work to be ground is held in a chuck mounted on the spindle of the work head. The work head spindle is driven by a belt from a three-speed motor mounted on the work head. The work head base is of swiveling type providing for grinding a maximum included angle of 60°.

Power traverse of the table carrying the wheel head is operated hydraulically, the speed beind controlled by a hydraulic control valve. Hand table travel used for positioning purposes is also provided. The stroke of the table is set by adjustable dogs.

The grinding wheel spindle is driven by an endless belt from a separate electric motor.

electric motor.

The automatic cross feed to the cross slide carrying the wheel head is applied through a ratchet mechanism. The automatic feed mechanism operates at every other reversal of the table. Truing of the grinding wheel is effected by means of a special wheel truing device by either a diamond or dresser.

The machine is equipped with four motors.

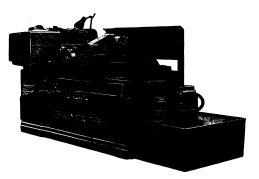
СТАНКОИМПОРТ

	I DOLL TO		
Capacity Diameter of hole that can be ground, mm: Minimum Maximum length that can be ground, mwing, mm: Inside water guard Without water guard	150 500 500 680 780	Work head spindle speeds, r. p. m. 27; 35; 53; 95; 122: 187 Table speeds (hydraulic), m/min: 0.3 Maximum 10 Wheel head cross feed per stroken 40 Minimum 0,000 Minimum 0,000 Minimum 0,000	5
Distance from center 01	400	Drive	
spindle to table, mm Maximum distance from work head spindle to wheel head flange, mm Grinding wheel cross movel	1620	380 volt, 3 phase, 50 cycle A. C. motors: Wheel head: 4.	
ment to center of work head, mm: Forward Backward	200 200	Speed, r. p. m. 300 Work head (three-speed): Power, kW 2.7 3.2 4. Speeds, r. p. m. 750 1000/150	.0
Table, Work Head, Wheel Maximum traverse of table (hydraulic and by hand),		Hydraulic pump: Power, kW	3.5
mm Swivel of work head for taper grinding, degrees Grinding wheel dimensions,	800 30	Power, kW	
mm: Minimum diameter Maximum diameter Maximum face	125 200 100	Space Occupied Floor space, mm	i5
Speeds and Feeds Wheel head spindle speed, r.p.m.	3000	Weight Net weight, kg approx. 52	20



AUTOMATIC CENTERLESS INTERNAL GRINDING MACHINE

MODEL 3263



The 3263 Automatic Centerless Internal Grinding Machine is designed for grinding cylindrical and tapered bores of ball and roller bearing races and other similar parts in lot and mass production.

The workpiece is set up between three rolls mounted on the work head: a support roll, a pressure roll and a regulating roll, the latter for driving the work.

To set the work to a given angle for taper grinding the work head is swiveled in a horizontal plane.

Longitudinal traverse of the table and cross feed of the wheel head are operated hydraulically.

СТАНКОИМПОРТ

The machine is equipped with a loading magazine and operates on the following automatic cycle: work feeding to working position: rough grinding; wheel truing; finish grinding, and work unloading.

The grinding wheel wear is compensated for by a corresponding setting of the feed mechanism.

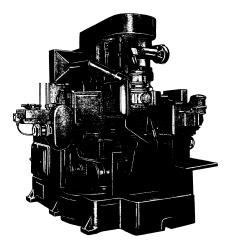
SPECIFICATIONS

Capacity		Speeds and Feeds
Outside diameter of work ground, mm: Minimum Maximum Diameter of hole ground, mm: Minimum Maximum Maximum Maximum Maximum length of hole	70 200 60 175	Range of regulating roll speeds, r.p.m
ground, mm	100	Drive
traverse, mm	500	Power of electric motors, kW 7.85
Maximum cross traverse of grinding wheel, mm	100 30°	
mm: Minimum Maximum	30 100	Weight Net weight, kg approx. 5600



VERTICAL DOUBLE SPINDLE PISTON RING GRINDING MACHINE

MODEL 3317



The 3317 Piston Ring Grinding Machine is designed for the precision finish grinding of piston ring sides in mass manufacture at a very high rate of production.

Two grinding wheels with offset spindles running in the vertical position and revolving in the same direction at the same speed grind both piston ring sides simultaneously. The rings are fed to the grinding wheels by a work

СТАНКОИМПОРТ

feed mechanism of the semi-automatic magazine type equipped with endless feed chains. The feeds are changed by suitable interchangeable chain sprockets. Entering the grinding zone the ring receives a rotation in the clockwise direction; then, in the middle of the grinding zone the ring is rotated counter clockwise and when leaving the grinding zone the work is again rotated clockwise. This produces very accurately ground rings, flat, parallel and of a high degree of finish.

The machine has both manually operated and power driven wheel spindle

feeds.

The machine is equipped with a wheel truing device and with an exhausting system for the vapour of kerosene which is part of the coolant fluid.

SPECIFICATIONS

Capacity		Drive	
Diameter of piston rings ground, mm: Minimum Maximum	75 180	220/380 volt, 3 phase, 50 cycle A.C. motors: Grinding wheels: Power, kW Speed, r. p. m. Wheel spindle rapid mo.	7 1500
Wheel Heads Maximum vertical travel of	50	vement: Power, kW Speed, r.p. m Work feed mechanism:	0.41 1500
grinding spindle, mm Distance from grinding wheel face to grinding surface, mm: Minimum	0	Power, kW	0.25 1500 0.25 1500
Maximum Grinding wheel dimensions, mm: External diameter	50 750	Exhausting system: Power, kW. Speed, r. p. m. Wheel truing device:	0.25 1500
Hole diameter Minimum height Maximum height	350 15 40	Power, kW	0.25 1500 0.65
Speeds and Feeds		Speed, r. p. m	3000
Grinding wheel speed, r. p. m. Wheel spindle feed, mm/min. Rapid movement of wheel	465 0.6	Floor space, mm 298 Height of machine, mm	0 × 2865 2865
spindle, mm/min	40 22.4; 31 6		ox. 9500



SWING FRAME GRINDING MACHINE

MODEL 3374 K



The 3374 K Swing Frame Grinding Machine is designed for cleaning, rough grinding and buffing castings, sheets, tubings, bars, shapes, etc. which are too large and unwieldy for the usual standard floor grinders.

The machine is suspended by a chain or wire rope from a floor crane, movable hoist, regular shop crane, or any overhead arrangement, thus it can

movable host, regular shop crane, or any overhead arrangement, those a combe freely swing in any direction.

The wheel head can be swiveled and locked in any position up to 45° . The machine is supplied with a steel guard over the wheel, which together with the all rigid construction ensures maximum possible safety.

The weight of the motor and the counter balancing weights make operation

of the machine light and easy to handle and do not tire the operator.

SPECIFICATIONS

Grinding Wheel		Drive
Grinding wheel dimensions,		220/380 volt, 3 phase, 50 cycle A. C. motor:
mm:		Power, kW 4.5
Minimum diameter	270	Speed, r. p. m
Maximum diameter	400	Overall Dimensions
Face	40	Overall length, mm
Grinding wheel speed, r. p. m.	2120	Height, mm 660
Grinding wheel surface speed,		Weight
m/sec,	30 - 44.5	Net weight, kg approx. 270

СТАНКОИМПОРТ



FLEXIBLE SHAFT PORTABLE GRINDER

MODEL 3382



The 3382 Flexible Shaft Portable Grinder is designed for many different grinding, cleaning, buffing, etc. operations on large parts in any shop. In foundries it may be used for removing excess metal, blending various radii, removing parting lines, cleaning, etc. In welding shops it may be used for grinding of the high spots left by the welding process. Machine shops use it for burring and cleaning of castings, blending of metal parts, breaking corners, and for many other different operations.

The grinding wheel spindle is driven by electric motor mounted on carriage through Vee-belt drive and flexible shaft. The flexible shaft is left rotating. Two handles at each side of the grinding wheel head are designed for holding the wheel head during operation. After finishing the operation the grinding wheel head is laid on two supports of the electric motor housing.

The carriage is mounted on three wheels and may be easily moved from place to place as needed.

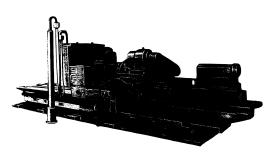
place to place as needed.

	SPECIFIC	ATTONE
Grinding Wheel		Space Occupied
Grinding wheel diameter, mm Grinding wheel width, mm Grinding wheel speed, r. p. m	200 25 2160	Floor space, mm
Drive		
220/380 volt, 3 phase, 50 cycle A. C. motor: Power, kW	2.8	Weight
Speed, r. p. m.	1500	Net weight, kg , approx. 175



ROLL GRINDING MACHINE

MODEL 3415 E



The 3415 E Roll Grinding Machine is designed for the grinding of large mill rolls with either straight, concaved or crowned bodies. Parallel or taper roll journals and the adjacent radii from 5 to 50 mm may also be ground in this machine. The machine is of the moving wheel head type in which the grinding wheel is traversed up and down the length of the roll, which is rotated but does not move lengthwise.

The three fundamental motions — the work revolving movement, the grinding wheel and the grinding saddle traverse — each have an independent variable stepless drive from D. C. motors. The wheel head traverses speed and the number of revolutions in minute of both the work and grinding wheel are indicated by special instruments on the control panel.

The machine is equipped with a center grinding attachment which is driven by a separate motor.

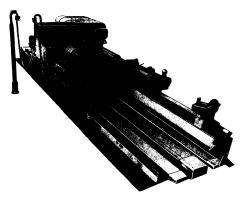
СТАНКОИМПОРТ

Capacity Height of centers over bed, mm . 60 Maximum length of work ground, mm . 450 Diameter of work ground, mm:	Minimum 0.05
Maximum, with 600 mm diameter wheel 100	Drive
Minimum, with 900 mm	D. C. electric motors:
diameter wheel 20	
Maximum concavity or crown	Power, kW 29
	1 Speeds, r. p. m. 500—1000
Maximum length of taper ground, mm 50	Work revolving mecha- nism:
Maximum weight machine will	Power, kW 34
carry, kg 2000	Speed, r, p, m,
	Grinding saddle traverse:
Grinding Saddle and Wheel Head	Power, kW 5.6
Maximum grinding saddle	Speed, r. p. m
traverse, mm 450	A. C. motors:
Grinding saddle travel per one revolution of hand-	Footstock travel:
	Power, kW 1.7
Wheel head cross movement,	" Speed, r. p. m 1000
mm	Coolant pump (two mo- tors):
Grinding wheel diameter, mm:	Power I-W 0.66
Maximum 90	Speed - p m 3000
Minimum 45	Wheel head movement:
Headstock and Footstock	Power, kW 1.0
	Speed, r. p. m
Taper hole in headstock and footstock spindles Metric 14	Hydraulic pump:) Power, kW 1.0
Maximum movement of foot-) Power, kW 1.0 Speed, r. p. m 1500
stock spindle, mm 150	
	ment:
Speeds and Feeds	Power, kW 1
Grinding wheel spindle speeds	Speed, r. p. m 1000
(infinitely variable), r, p, m,:	Space Occupied
Minimum 500	
Maximum 1000 Work speeds (infinitely	Height of machine, mm
variable), r. p. m.:	
Minimum	Weight
Maximum 50	



ROLL GRINDING MACHINE

MODEL 3415 K



The 3415 K Roll Grinding Machine is designed for the grinding of large mill rolls with either straight, concaved or crowned bodies.

Parallel or taper roll journals and the adjacent radii from 5 to 50 mm may also be ground in this machine.

The machine is of the moving wheel head type in which the grinding wheel is traversed up and down the length of the roll, which is rotated but does not move lengthwise.

The three fundamental motions — the work revolving movement, the grinding wheel and the grinding saddle traverse — each have an independent variable stepless drive irom D. C. motors.

The wheel head traverse speed and the number of revolutions in minute

СТАНКОИМПОРТ

of both the work and grinding wheel are indicated by special instruments on

The machine is equipped with a center grinding attachment which is driven by a separate motor.

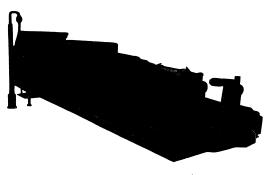
SPECIFICATIONS

Height of centers over bed, mm length of work ground, mm length of wor	600 7500	Grinding saddle traverse speeds (infinitely variable), m/min.: Minimum	0.05 2.5 0.005
Maximum, with 600 mm diameter wheel	1000	Drive	
Minimum, with 900 mm diameter wheel Maximum concavity or crown	200	D. C. electric motors: Grinding wheel: Power, kW	29
machine will grind, mm	1	Speed, r. p. m	1000
Maximum length of taper	500	nism:	
ground mm Maximum weight machine	300	Power, kW	34
will carry, kg	20000	Speed, r. p. m	1580 5.6
Grinding Saddle and Whee	l Head	Power, kW	1000
Maximum grinding saddle traverse, mm	7500	220/380 volt, 3 phase, 50 cycle A. C. motors: Footstock travel:	
revolution of handwheel, mm	1	Power, kW	1.7 1000
Wheel head cross move- ment, mm	550	Speed, r. p. m	0.65
Maximum	900	Power, kW	3000
Minimum	450	Wheel head movement:	
		Power, kW	1.0
Headstock and Footsto	ock	Speed, r. p. m.	1500
Taper hole in headstock and	Metric 140	Hydraulic pump: Power, kW	10
footstock spindles Maximum movement of foot-	150	Speed, r. p. m. Center grinding attach-	1500
stock spindle, mm	150	ment:	
Speeds and Feeds		Power, kW	1.0
Grinding wheel spindle speeds		Speed, r.p.m	1000
(infinitely variable), r. p. m.: Minimum Maximum	500 1000	Space Occupied Floor space, mm	12680 × 4320 2500
Work speeds (infinitely variable), r. p. m.:			
Minimum	6	Weight	F0000
Maximum	40	Net weight, kg a	pprox. 70000



ROLL GRINDING MACHINE

MODEL 3417 B



The 3417 B Roll Grinding Machine is designed for the grinding of large mill rolls with either straight, concaved or crowned bodies.

Parallel or taper roll journals and the adjacent radii from 5 to 50 mm may also be ground in this machine.

The machine is of the moving wheel head type in which the grinding wheel is traversed up and down the length of the roll, which is rotated but

wheel is traversed up and down the rength of the following movement, the does not move lengthwise.

The three fundamental motions — the work revolving movement, the grinding wheel and the grinding saddle traverse — each have an independent variable stepless drive from D. C. motors.

The wheel head traverse speed and the number of revolutions in minute.

of both the work and grinding wheel are indicated by special instruments on the control panel.

The machine is equipped with a center grinding attachment which is driven by a separate motor.

СТАНКОИМПОРТ

Capacity		Grinding saddle traverse	
Height of centers over bed,		speeds (infinitely variable),	
mm	800	r, p. m.:	
Maximum length of work		Minimum	0.05
ground mm	6000	Maximum	2.5
Diameter of work ground, mm:		Wheel head cross feed, per one tooth of ratchet, mm .	0.005
Maximum, with 600 mm			
diameter wheel	1500	Drive	
Minimum, with 900 mm		D. C. electric motors:	
diameter wheel	200	Grinding wheel:	
Maximum concavity or crown		Power, kW	29
machine will grind, mm	1	Speeds, r. p. m.	500-1000
Maximum length of taper	500	Work revolving mecha- nism:	
ground, mm	500	Power, kW	64
carry, kg	40000	Speeds, r. p. m	200-1925
c, ag	40000	Grinding saddle traverse:	200-1525
		Power, kW	5.6
Grinding Saddle and Whee	el Head	Speeds, r. p. m	20-1000
		220/380 volt, 3 phase, 50 cycle	
Maximum grinding saddle tra-		A, C, motors:	
Grinding saddle travel per one	6000	Footstock travel:	
revolution of handwheel, mm	1	Power, kW	1.7
Wheel head cross movement,		Speed, r. p. m	1000
mm	550	Power, kW	1.0
Grinding wheel diameter, mm:	000	Speed, r. p. m.	1500
Maximum	900	Fan drive:	1300
Minimum	450	Power, kW	1.0
		Speed, r. p. m.	1500
		Coolant pump (two mo-	
Headstock and Footsto	ock	tors):	
Taper hole in headstock and		Power, kW	0.65
footstock spindles	Metric 140	Speed, r. p. m Hydraulic pump:	3000
Diameter of headstock face		Power, kW	1.0
plate, mm	985	Speed, r. p. m.	1500
		Center grinding attach-	1000
		ment:	
Speeds and Feeds		Power, kW	1.0
Grinding wheel spindle speeds		Speed, r. p. m	1000
(infinitely variable), r. p. m.			
Minimum	500	Space Occupied	
Maximum	1000	Floor space, mm 1	3500×4700
Working speeds (infinitely		Height of machine, mm	2500
variable), r. p. m.:		Weight	
Minimum	6		
Maximum	60	Net weight, kg ap	Drox. 90000



HYDRAULIC CRANKPIN GRINDING MACHINE

MODEL 3A421



The 3A421 Hydraulic Crankpin Grinding Machine is designed for the rapid production grinding of automotive crankpins at the plants of mass production. The machine is delivered set-up for grinding the pins of a certain crankshaft. The crankshaft to be ground is held in special chucks, mounted on the spindles of the right and left work heads.

Hydraulic power is utilized to a considerable extent as it operates the rapid advance and withdrawal of the wheel, cross feed of wheel head, traverses the work table, operates the work clamping, work rest shoes, etc. Hand movement of table is also provided.

The work is clamped mechanically by means of powerful springs acting through a system of levers. The machine is provided with interlock mechanisms which prevent damage to machine if operator through error fails to follow proper sequence of lever operation.

The measuring of the ground pin diameter is performed during the opera-

The machine is equipped with five motors.

СТАНКОИМПОРТ

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SPECIFICATIONS

Capacity		Speeds	
Height of centers over table,	-	Work spindle speed, r. p. m.	70
mm	255	Table traverse speed (hy-	
Maximum work swing, mm	450	draulic), m/min.	34
Maximum length of cranks-			
haft, mm	1100	Drive	
Crankshaft throw, mm:			
Minimum	40	220/380 volt, 3 phase, 50 cycle	
Maximum	80	A. C. motors:	
Distance between work and		Wheel head:	
wheel centers (without hy-		Power, kW	20
draulic withdrawal), mm:		Speed, r. p. m.	1000
Minimum	400	Work head:	1.7
Maximum	600	Power, kW	
m		Speed, r. p. m	1000
Table		Hydraulic pump:	1.7
Maximum table traverse (hy-		Power, kW	1000
draulic and by hand), mm .	900	Speed, r. p. m.	1000
		Coolant pump:	0.13
Wheel Head		Power, kW	3000
Maximum cross travel of		Speed, r. p. m.	3000
wheel head, mm:			
Manual	200	Space Occupied	
Hydraulic (advance) .	100		9798
Grinding wheel dimensions,		Floor space, mm 4480 >	162
mm:		Height of machine, mm	102
Minimum diameter	750		
Maximum diameter	1100	Weight	
Face according to	set-up		990
Hole diameter	305	Net weight, kg approx	. 020



HEAVY DUTY CRANKPIN GRINDING MACHINE

MODEL 3428



The 3428 Crankpin Grinding Machine has been designed for the grinding of crankpins of heavy engine and diesel crankshafts. The machine is delivered set-up for grinding the pins of a certain crankshaft. To set up the machine for grinding another type of crankshaft it is necessary to change the work head chucks and to reset the center steadyrest for the center main bearing. Each work head may be moved longitudinally on the top of the work table and crankshafts of varying lengths may as a consequence be ground on the

and crankshafts of varying lengths may as a consequence be ground on the same machine.

Rapid movement of the wheel head toward or away from the work and fine feed during the actual grinding are performed hydraulically. Two D. C. motors are provided: one for traversing the work table and the other for driving the work heads giving an infinite number of work speeds ranging from 10 to 30 r.p. m. Grinding up to a stop with wheel head setting to compensate for wheel wear may be performed in this machine.

SPECIFICATIONS

Capacity Maximum work swing, mm Length of crankshaft, mm: Minimum Maximum Distance between work and	1220 2000 5500	Diameter that can be ground (in steadyrest), mm: Minimum Maximum	150 300
wheel centers, mm:		Maximum table traverse, mm	4300
Minimum	575 1150	Table travel per 1 revolution of hand wheel, mm	5

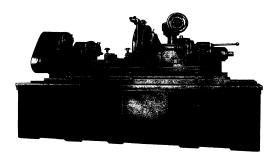
СТАНКОИМПОРТ

Wheel Head Maximum cross travel of wheel head, mm: By hand. Hydraulically (advance) Grinding wheel dimensions, mm immum diameter. Maximum diameter. Face Speeds Infinitely variable work speeds, r.p.m. from 10	200 350 1280 1400 75	Hydraulic pump: Power, kW
Mechanical table traverse speeds, m/min.: Minimum Maximum	0·1 2.5	Speeds, r. p. m
Maximum	2.0	Space Occupied
Drive 220/380 volt, 3 phase, 50 cycle A. C. motors:		Floor space, mm 15500 × 4000 Height of machine, mm
Wheel head: Power, kW Speed, r. p. m	28 750	Weight Net weight, kg approx. 55000



CRANKSHAFT REGRINDING MACHINE

MODEL 3420



The 3420 Crankshaft Regrinding Machine is designed for regrinding both pins and line bearings of automotive crankshafts. It may also be used for plain, cylindrical grinding of many other automotive parts.

While regrinding pins the crankshaft is held in chucks mounted on the headstock and footstock spindles. The chucks and balance weights are mounted on slides, the positions of which are adjustable in order that the required off-center distance may be secured when grinding pins of different crankshafts. When regrinding line bearings the crankshaft is held in centers.

Power from the motor to the work spindle is transmitted by means of a belt drive with three-step pulleys.

The longitudinal movement of the table and the cross movement of the wheel head are performed manually.

A wheel truing device, equipment for horizontal and vertical adjustment of the crankshaft to be ground and a work drive dog for center grinding are supplied with the machine.

The machine is equipped with three motors.

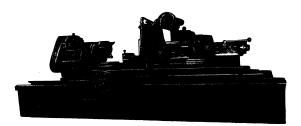
СТАНКОИМПОРТ

SPECIFICATIONS			
Capacity		Maximum face 44	
Height of centers, mm	215	Hole diameter 305	
Distance between centers, mm Distance between wheel and	1100	Speeds	
work centers, mm: Minimum	240	Work speeds, r. p. m 40; 75; 140	
Maximum ,	480	Drive	
Diameter that can be ground (in steadyrest), mm: Minimum	30	220/380 volt, 3 phase, 50 cycle A. C. motors: Wheel head:	
Maximum	90	Power, kW 7.0	
Maximum length of work, mm Maximum weight of work, kg	1100 80	Speed, r. p. m 1500 Headstock:	
Table		Power, kW 1.0	
Maximum table travel (by hand), mm	1100	Speed, r. p. m 1000 Coolant pump:	
nand), mm	1100	Power, kW 0.125	
Wheel Head		Speed, r. p. m 3000	
Maximum cross travel of		Space Occupied	
wheel head, mm Grinding wheel dimensions, mm:	240	Floor space, mm	
Minimum diameter Maximum diameter	480 750	Weight	
Minimum face	33	Net weight, kg approx. 4200	



CRANKSHAFT REGRINDING MACHINE

MODEL 3423



The 3423 Crankshaft Regrinding Machine is designed for regrinding both pins and line bearings of automotive crankshafts. It may also be used for plain cylindrical grinding of many other automotive parts. While regrinding pins the crankshaft is held in chucks mounted on the headstock and footstock spindles. The chucks and balance weights are mounted on slides, the positions of which are adjustable in order that the required off-center distance may be secured when grinding pins of different crankshafts. When regrinding line bearings the crankshaft is held in centers.

Power from the motor to the work spindle is transmitted by means of a belt drive with three-step pulleys.

The longitudinal movement of the table and the cross movement of the wheel head are performed manually.

The swiveling table permits grinding of tapered surfaces.

A wheel truing device, equipment for horizontal and vertical adjustment of the crankshaft to be ground and a work drive dog for center grinding are supplied with the machine.

The machine is equipped with three motors. The 3423 Crankshaft Regrinding Machine is designed for regrinding both

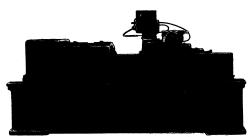
СТАНКОИМПОРТ

Capacity Height of centers, mm Distance between centers, mm Distance between wheel and	300 1600	Minimum face 33 Maximum face 40 Hole diameter 305 Speeds
work centers, mm: Minimum	275 595 595	Work speeds, r. p. m 30; 65; 115
(in steadyrest), mm: Minimum Maximum	30 100	220/380 volt, 3 phase, 50 cycle A. C. motors: Wheel head:
Maximum crankshaft throw, mm Maximum length of work, mm Maximum weight of work, kg	110 1600 125	Power, kW 7.0 Speed, r. p. m 1000 Headstock:
Table Maximum table travel, mm .	1600	Power, kW
Maximum swivel of table, degrees	5	Speed, r. p. m
Wheel Head		Space Occupied
Maximum cross travel of wheel head, mm Grinding wheel dimensions,	320	Floor space, mm 3930 × 1795 Height of machine, mm 1620
mm: Minimum diameter Maximum diameter	550 900	Weight Net weight, kg approx. 6000



AUTOMATIC HYDRAULIC CAM GRINDING MACHINE

MODEL XIII-170



The XIII-170 Cam Grinder is a hydraulically operated automatic machine for rough and finish grinding the cam contours of automotive engine camshafts at plants of mass production. The cycle of operation is automatic although the machine may be manually operated. With a camshaft in place the operator presses a button and moves a lever which starts the machine's automatic functions.

The machine can be stopped at any time during the cycle and any particular cam on the shaft can be ground independently of the others if desired. The following automatic functions of the machine during the cycle of operation are controlled hydraulically: shifting the table to bring the next cam into position for grinding, locking the table, swinging the cradle into

operation are controlled hydraulically: snitting the table to bring the leave cam into position for grinding, locking the table, swinging the cradle into the forward inoperative position, disengagement of table hand movement mechanism, rapid movement of the wheel head toward or away from the work and fine feed during the actual grinding, wheel truing and wheel head setting to compensate for wheel wear, stopping the grinding wheel reciproca-tion, interlocking the starting lever during the wheel truing.

A two-speed motor drives the work.

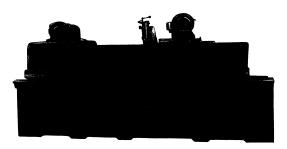
СТАНКОИМПОРТ

SPECIFICATIONS				
Capacity Height of centers over cradle, mm	75 900	Minimum face 25 Maximum face 40 Hole diameter 305 Speeds		
work centers, mm: Minimum Maximum Maximum radius of rotation,	260 360	Work speeds, r. p. m		
mm	60	Drive		
Maximum lift of cam, mm Diameter that can be ground (in steadyrest), mm:	15	220/380 volt, 3 phase, 50 cycle A. C. motors: Wheel head:		
Minimum	20	Power, kW		
Maximum	60	Speed, r. p. m 1500		
Maximum weight of work, kg	30	Headstock (two-speed):		
		Power, kW 1.7/2.0		
Table, Headstock and Footstock Maximum traverse of table (hydraulic and manual), mm Taper hole in headstock and footstock spindles Morse	900	Speeds, r, p, m. 1500/3000 Hydraulic pump: 2.8 Power, kW. 2.8 Speed, r, p, m. 1500 Coolant pump: 0.125 Power, kW. 0.125		
Wheel Head		Speed, r. p. m 3000		
Maximum cross travel of wheel head, mm: Manual	120 14			
mm: Minimum diameter Maximum diameter	500 600	Weight Net weight, kg approx. 7000		



CAMSHAFT REGRINDING MACHINE

MODEL 3433



The 3433 Camshaft Regrinding Machine is designed for regrinding the cam contours of automotive camshafts. The cam grinding is performed by the copying method. The contour is produced by swinging the work as it revolves, toward and away from the grinding wheel, by means of a master cam in contact with a roller.

Various types and kinds of cam shapes can be ground in this machine using a set of interchangeable master cam blocks furnished with the machine and mounted on the headstock spindle. A master block consists of a master exhaust cam, a master inlet cam and an eccentric (in case the camshaft has such an eccentric). The longitudinal movement of the table and the cross movement of the wheel head are performed manually.

Power from the motor to the work spindle is transmitted by means of a belt drive with two-step pulleys.

a belt drive with two-step pulleys.

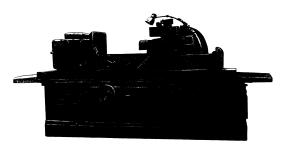
СТАНКОИМПОРТ

Capacity		Maximum diameter 600
Height of centers over cradle,		Minimum face 25 Maximum face 40
mm	95	
Distance between centers, mm	1260	Hole diameter 305
Distance between wheel and		
work centers, mm:		Speeds
Minimum	260	Work speeds, r. p. m 16; 32
Maximum	500	17 O'R Speeds, 1. p. m
Maximum radius of rotation,		
mm	90	Drive
Maximum lift of cam, mm	15	220/380 volt, 3 phase, 50 cycle
Diameter that can be ground		A. C. motors:
(in steadyrest), mm:		Wheel head:
Minimum	30	Power, kW 4.5
Maximum	75	Speed, r. p. m
Maximum weight of work, kg	30	Headstock:
		Power, kW 0.7
Table, Headstock and Foot	stock	Speed, r. p. m 1000
Maximum traverse of table (by		Coolant pump:
hand), mm	1260	Power, kW 0.125
Taper hole in headstock and		Speed, r. p. m
footstock spindles Mo	rse No. 4	
		Space Occupied
Wheel Head		·
Maximum cross travel of		Floor space, mm 2800 × 1860
wheel head (by hand), mm .	240	Height of machine, mm 1500
Grinding wheel dimensions,	210	
mm:		Weight
Minimum diameter	500	Net weight, kg , approx. 4200



SPLINE GRINDING MACHINE

MODEL 345 A



The 345 A Spline Grinder is designed for accurate and fine finish grinding of every type of spline shaft in both small and large quantities.

The working cycle of the machine includes: hydraulic table traverse, indexing of spline shaft at end of table traverse, rough grinding, down feed of grinding wheel at end of each complete revolution of work, truing of grinding wheel, changing table traverse speed for finish grinding, changing rough feed of grinding wheel to finish feed and stopping machine when final size of splines is reached.

The machine is equipped with four electric motors.

SPECIFICATIONS

Capacity		Maximum length ground, mm 800 Number of splines ground 4; 6; 8; 12; 16
Height of centers, mm	210	Number of sprines ground 4, 0, 6, 12, 10
Distance between centers, mm	1000	Wheel Head
Diameter of work ground, mm:		Maximum travel of wheel head mm:
Minimum	28	Horizontal 40
Maximum	120	Vertical 125

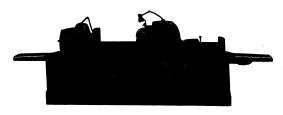
СТАНКОИМПОРТ

Grinding wheel dimensions, mm: Minimum and maximum diameter	75—200	Drive 220/380 volt, 3 phase, 50 cycle A. C. motors: Grinding wheel drive:
Minimum and maximum		Power, kW 2.8
width	1025	Speed, r. p. m 3000
Hole	32	Hydraulic pump:
		Power, kW 4.5
Table		Speed, r. p. m 1000
Working surface of table, mm		Indexing mechanism:
Maximum table traverse, mm	1100	Power, kW 0.6
		Speed, r. p. m
Speeds and Feeds		Power, kW 0.125
Grinding wheel speeds, r. p. m.	2850; 4300;	Speed, r. p. m
	5700	Speca, 1. p. m
Table traverse speeds (infini- tely variable), m/min.:		Space Occupied
Minimum	2	Floor space, mm 4500 × 1425
Maximum	20	Height of machine, mm . 1765
Range of grinding wheel		
feeds (by hand), mm per		Weight
revolution of work	0.005 - 0.1	Net weight, kg approx. 6000



SPLINE GRINDING MACHINE

MODEL 3451 A



The 3451 A Spline Grinder is designed for accurate and fine finish grinding of every type of spline shaft in both small and large quantities.

The working cycle of the machine includes: hydraulic table traverse, indexing of spline shaft at end of table traverse, rough grinding, down feed of grinding wheel at end of each complete revolution of work, truing of grinding wheel, changing table traverse speed for finish grinding, changing rough feed of grinding wheel to finish feed and stopping machine when final size of splines is reached.

The machine is equipped with four electric motors.

SPECIFICATIONS

Capacity Height of centers, mm	Horizontal	40 125
Minimum 28 Maximum 120 Maximum 120 Maximum 1300 Number of splines ground 4: 6: 8: 12: 16	Minimum and maximum diameter Minimum and maximum width	75—200 10—25 32
Wheel Head	Table	
Maximum travel of wheel head, mm:	Working surface of table, mm Maximum table traverse, mm	$2840 \times 300 \\ 1600$

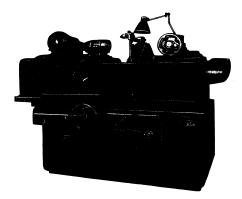
СТАНКОИМПОРТ

Speeds and Feeds Grinding wheel speeds, r. p. m.	2850; 4300; 5700	Hydraulic pump: Power, kW 4.5 Speed, r. p. m 1000
Table traverse speeds (infinitely variable), m/min.: Minimum Maximum	2 20	Indexing mechanism: Power, kW 0.6 Speed, r. p. m 1500 Coolant pump:
Range of grinding wheel feeds (by hand), mm per revolution of work	0.005-0.1	Power, kW 0.125 Speed, r. p. m 3000
Drive 220/380 volt, 3 phase, 50 cycle A. C. motors:		Space Occupied Floor space, mm 6000 × 1425 Height of machine, mm
Grinding wheel drive: Power, kW	2.8 3000	Weight Net weight, kg approx. 6300



DISC CAMS GRINDING MACHINE

MODEL XIII-81



The XIII-81 Grinding Machine is designed for grinding the contour on

The XIII-81 Grinding Machine is designed for grinding the contour on disc cams.

The machine employs the copying method. The master cam is mounted on the front part of the work head spindle. For each type of cam a special master cam is necessary. The workpiece to be ground is mounted on a special arbor and fastened, and is inserted into the tapered hole of the work spindle. Approach and withdrawal of the headstock with the spindle and master cam from the roller support, slow in-feed of the wheel head, planter cam from the roller support, slow in-feed of the wheel head (plunge-cut) are effected hydraulically.

Another feature of the machine is that it can be arranged to grind to a pre-set limit and then withdrawing the wheel head the accurate size of the workpiece has been ensured.

СТАНКОИМПОРТ

The wheel head spindle has oscillating motion, which can be disengaged when the wheel is being dressed

The machine is furnished with a special device by the help of which worn-out master cams can be reground.

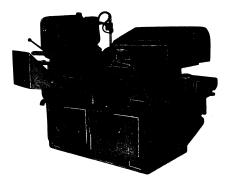
SPECIFICATIONS

Capacity		Speeds	
Maximum diameter of work,		Work spindle speeds, r. p. m. 12; 2	4
_ mm	400	Drive	
Distance between wheel and work centers (without hy-			
draulic withdrawal), mm:		220/380 volt, 3 phase, 50 cycle electric motors:	
Minimum	285	Wheel head:	
Maximum	485	Power, kW	7
Maximum diameter of work		Speed, r. p. m	ю
ground, mm	250	Work head:	
Maximum lift of cam ground,	30		0.
mm	50	Speed, r. p. m 100	00
Maximum length ground, mm	50	Drive for grinding master	
Table and Work Head		cams:	.0
Maximum longitudinal travel		Power, kW	
of table (by hand), mm	300	Hydraulic pump:	
Taper hole in work head . Morse	No. 6	Power, kW 2	8
•		Speed, r. p. m 150	90
Wheel Head		Coolant pump:	
Maximum travel of wheel		Power, kW 0.12	
head, mm:		Speed, r. p. m 300	00
By hand	150		
Hydraulic (approach)	50	Space Occupied	
Grinding wheel dimensions,		Floor space, mm 1900 × 195	50
mm: Minimum diameter	500	Height of machine, mm 155	90
Maximum diameter	600	***	
Face	50	Weight	
Hole diameter	305	Net weight, kg approx. 420	90



INTERNAL AUTOMATIC BALL RACE GRINDER

MODEL Л 3-5 M



The $\rm I\!I 3-5 \ M$ Ball Race Grinder is designed for grinding ball race-ways

in external ball bearing rings.

Grinding is based upon the principle of oscillation of the workpiece. The working cycle is controlled by means of an electrical sizing device, which changes the feed, shows the progress of the grinding wheel in removing stock and indicates the completion of the operational sizing. It then withdraws the wheel head and stops all electric motors, except that of the wheel head.

СТАНКОИМПОРТ

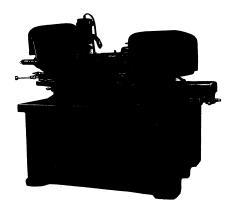
SPECIFICATIONS

Capacity	Drive
Diameter of external ring ground, mm:	220/380 volt, 3 phase, 50 cycle A. C. motors: Grinding wheel: Power, kW . 2.8 Speed, r. p. m. 3000 Rapid approach: Power, kW . 1.0
Wheel Head	Speed, r. p. m 1500
Longitudinal rapid power approach, mm . 100 Cross rapid power approach, 20 Grinding wheel speeds, 5,00 and 9000 Range of feeds, mm/min. 015—24 Table	Rotation of work:
Number of complete oscilla-	Space Occupied
tions per min	Floor space, mm
Work Head	Weight
Speeds of work, r. p. m 200 and 300	Net weight, kg approx. 2500



INTERNAL AUTOMATIC BALL RACE GRINDER

MODEL $_{\rm JI\ 3^{-8}\ M}$



The JI 3-8 M Ball Race Grinder is designed for grinding ball race-ways in

The JI 3-8 M Ball Race Grinder is designed for grinding oan face ways in external ball bearing rings.

The working cycle of the machine is completely independent of the operator, which makes it possible for one operator to work on several machines.

The automatic cycle of the machine is controlled by means of an electrical sizing device through changes in the size of the race-way being ground.

СТАНКОИМПОРТ

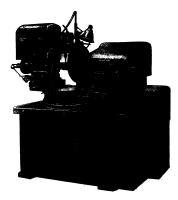
SPECIFICATIONS

Capacity Capacity	Drive 220/380 volt, 3 phase, 50 cycle A. C. motors: Grinding wheel: 1.7 Flower, kW 1.7 Solution of work: Power, kW 0.85 Powe
Wheel Head	Speed, r. p. m
Longitudinal rapid power approach, mm	Power, kW 1.0 Speed, r. p. m 1000 Oscillating drive:
mm	Power, kW
Range of feeds, mm/min 0.13-2.4	Power, kW 0.125 Speed, r. p. m 3000
Table	Space Occupied
Number of complete oscilla- tions per min 30; 40; 50 Maximum swivel angle 60°	Floor space, mm 1740 × 1070 Height of machine, mm 1480
Work Head Speeds of work, r.p.m 530 and 800	Weight Net weight, kg approx. 2100



EXTERNAL AUTOMATIC BALL RACE GRINDER

MODEL $_{\rm JI\,3^{-9}\,M}$



The A 3-9 M Ball Race Grinder is designed for grinding ball race-ways on internal ball bearing rings.

The working cycle of the machine is completely independent of the operator, which makes it possible for one operator to work on several machines.

The automatic cycle of the machine is controlled by means of an electrical sizing device through changes in the size of the race-way being ground.

СТАНКОИМПОРТ

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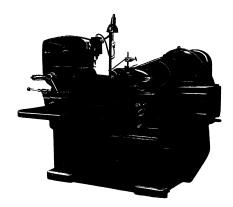
SPECIFICATIONS

Capacity	Drive
Diameter of internal ring ground, mm:	220/380 volt, 3 phase, 50 cycle A. C. motors:
Maximum 140 Minimum 40	Grinding wheel: Power, kW 2.8
Maximum radius of race-way ground, mm 20	Speed, r. p. m 1500 Rotation of work:
	Power, kW 0.65 Speed, r, p. m
Wheel Head	Rapid approach:
Longitudinal rapid power ap- proach, mm 85	Power, kW 1.0 Speed, r. p. m 1000
Grinding wheel speed, r. p. m. 1450 Range of feed, mm/min. 0.15—2.4	Oscillating drive: Power, kW 1.0
Range of feed, innovini.	Speed, r. p. m
Table	Power, kW 0.125 Speed, r.p.m 3000
Number of complete oscilla- tions, per min 30: 40: 50	Space Occupied
Maximum swivel angle 60°	Floor space, mm 1600×1480 Height of machine, mm 1580
Work Head	Weight
Speeds of work, r. p. m 290 and 540	Net weight, kg approx. 2100



AUTOMATIC BALL RACE GRINDER

MODEL J 3-10 M



The JI 3-10 M Ball Race Grinder is designed for grinding ball race-ways of ball thrust bearings. The working cycle, which consists of rough and finish grinding to size, is completely automatic. This makes it possible for one operator to work on several machines.

The automatic cycle of the machine is controlled by means of an electrical sizing device, which actuates the necessary mechanisms in the process of the grinding operation.

СТАНКОИМПОРТ

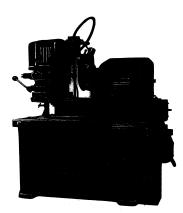
SPECIFICATIONS

Capacity	Drive
Maximum outside diameter of bearing washer ground, mm 350 Minimum inside diameter of bearing washer ground, mm 120	220/380 volt, 3 phase, 50 cycle A. C. motors: Grinding wheel: Power, kW 2.8 Speed, r. p. m 3000 Oscillating drive:
Wheel Head	Power, kW 1.0 Speed, r. p. m 1500
Longitudinal rapid approach, mm	Rotation of work:
Table Number of complete oscilla-	Power, kW 0.125 Speed, r. p. m 3000
tions per min 18 and 30 Maximum swivel angle 50°	$\begin{array}{cccc} \textbf{Space Occupied} \\ \textbf{Floor space, mm} & & 1900 \times 1285 \\ \textbf{Height of machine, mm} & & 1550 \end{array}$
Work Head	Weight
Speeds of work, r.p.m 150 and 300	Net weight, kg approx. 3150



EXTERNAL AUTOMATIC BALL RACE GRINDER

MODEL Л3-26



The A3-26 Ball Race Grinder is designed for grinding ball race-ways on internal ball bearing rings.

The working cycle of the machine is completely independent of the operator, which makes it possible for one operator to work on several machines.

The automatic cycle of the machine is controlled by means of an electrical sizing device through changes in the size of the race-way being ground.

СТАНКОИМПОРТ

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SPECIFICATIONS

SPECIFICATIONS		
Capacity		Drive
Diameter of internal ring ground, mm: Maximum Minimum	40 10	220/380 volt, 3 phase, 50 cycle A.C. motors: Grinding wheel: Power, kW 1.7
Maximum radius of race-way	10	Speed, r. p. m
5 ,		Speed, r. p. m
Wheel Head		Power, kW 1.0 Speed, r. p. m 1000 Rotation of work:
Rapid approach, mm Grinding wheel speed, r.p.m.	85 2100	Power, kW 0.6 Speed, r. p. m 1500 Feed drive:
Range of feeds, mm/min	0.15-2.4	Power, kW 0.1 Speed, r. p. m
		Space Occupied
Table		Floor space, mm 1470×1345 Height of machine, mm 1440
Number of complete oscilla- tions per min	30 and 50	Weight
Maximum swivel angle	60°	Net weight, kg approx. 2000



BEARING RACE SUPERFINISHING MACHINE

MODEL Л 3-15 М



The JI 3-15 M Bearing Race Superfinishing Machine is designed for superfinishing the race-ways of external and internal rings of roller bearings. Superfinishing is carried out with abrasive sticks held in a special holder. The sticks oscillate along the generatrix of the race-way of the work, while the latter revolves about its axis.

СТАНКОИМПОРТ

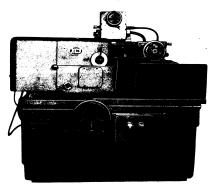
SPECIFICATIONS

0. 2011	.011110110
Capacity	Drive
Diameter of external ring to be machined, mm:	220/380 volt, 3 phase, 50 cycle
Minimum 50	A. C. motors:
	Work head (two speed):
Maximum 175 Diameter of internal ring to	Power, kW 0.7/1.2
be machined, mm:	Speeds, r. p. m
	Oscillation of abrasive
	stick:
Maximum 150	Power, kW 0.25
TIT: 1 TT: 1	Speed, r. p. m 1500
Work Head	Slide approach:
Speeds of work, r. p. m.:	Power, kW 0.41
Roughing 65; 175; 270; 430	Speed, r. p. m 3000
Finishing 130: 350: 540: 860	Abrasive stick dresser:
	Power, kW 0.15
Slide	Speed, r. p. m 3000
Travel of slide, mm 390	Coolant pump:
Travel of strate, initi	Power, kW 0.125
Oscillating Head	Speed, r. p. m 3000
Range of oscillations per min. 500-1000	Space Occupied
Pressure of abrasive stick, kg 2-20	
Amplitude of oscillation, mm:	Floor space, mm 1500 × 900
For oscillations from	Height of machine, mm 1550
700 to 1000 0—3	
For oscillations from	Weight
500 to 700 3—5	Net weight, kg approx. 1600



EXTERNAL ROLL RACE GRINDING MACHINE

MODEL 3486



The 3486 Roll Race Grinding Machine is designed for rough and finish grinding race-ways on internal rings of cylindrical and taper roller bearings with inside diameters ranging from 17 to 120 mm.

Rings with bores less than 45 mm are gripped in collet chucks, and those with bores greater than 45 mm are gripped in membrane chucks.

The machine operates upon the plunge-cut principle to a positive stop

The machine operates upon the punificate principle to a positive scoparrangement.

The work head has angular adjustment for taper grinding.

The working cycle of the machine is semi-automatic.

Rapid power approach and withdrawal of wheel head, rough and finish grinding, dwell, release of work, wheel truing, intermittent in-feed of wheel and diamond dressing are accomplished hydraulically.

СТАНКОИМПОРТ

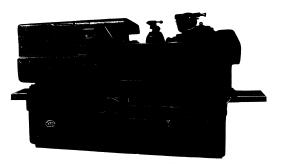
SPECIFICATIONS

Capacity		Maximum face 6 Minimum face 2
Maximum diameter of work, mm	300	Minimum face 2 Hole diameter 30
Distance between wheel and work centers (without hy-	500	Speeds
draulic withdrawal), mm: Minimum	225	Work spindle speeds, r. p. m. 150; 21
Maximum	375	Drive
Diameter that can be ground, mm: Maximum	150	220/380 volt, 3 phase, 50 cycle electric motors: Grinding wheel head:
Minimum	20	Power, kW
Maximum length ground, mm	63	Speed, r. p. m 150 Work head:
Table and Work Head Maximum longitudinal travel of table (by hand), mm . Maximum swivel of work head (on one side)	400 20°	Power, kW 1. Speed, r. p. m. 150 Hydraulic pump: Power, kW 1. Speed, r. p. m. 150 Coolant pump: Power, kW 0.12
Wheel Head		Speed, r. p. m 300
Maximum travel of head, mm: By hand Hydraulie (approach) Grinding wheel dimensions,	150 50	$\begin{array}{cccc} \textbf{Space Occupied} \\ \textbf{Floor space, mm} & . & . & . & . & . 1800 \times 195 \\ \textbf{Height of machine, mm} & . & . & . & . & 172 \\ \end{array}$
mm: Maximum diameter	600	Weight
Minimum diameter	450	Net weight ker annrox 410



EXTERNAL ROLLER BEARING RINGS **GRINDING MACHINE**

MODEL 3487 A



The 3487 A Roller Bearing Rings Grinding Machine is designed for rough and finish grinding race-ways on internal and external rings of cylindrical and taper roller bearings.

The machine has a capacity for grinding rings ranging from 150 to 500 mm in diameter and up to 200 mm in width.

Surface finish and accuracy of work ground are in accordance with both

conventional and precision grinding requirements.

The working cycle of the machine is semi-automatic.

The table reciprocating movements are infinitely variable; and the approach (plunge-cut grinding) and withdrawal of the wheel head or the intermittent in-feed of the wheel are effected hydraulically.

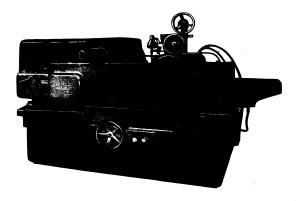
СТАНКОИМПОРТ

Capacity Maximum face 2.5	SPECIFICATIONS		
Distance between wheel and work centers (without hydraulic withdrawal), mm: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75: 100: 150: 300 71able traverse speeds (infinite speeds, r. p. m. 50: 75:	Maximum diameter of work,	• 600	Hole diameter 305
Diameter that can be ground, mm: Maximum 50	Distance between wheel and work centers (without hy- draulic withdrawal), mm: Minimum	300	Work head spindle speeds, r. p. m 50; 75; 100; 150; 300 Table traverse speeds (infini- tely variable), m/min:
Minimum 150	Diameter that can be ground,		
Maximum weight of ring ground, kg 60 electric miotors: wheel head: 14 14 Table Power, kW 1 4 Maximum longitudinal travel of table (hydraulic or hand), mm 500 Speed, r, p, m. 1500 Maximum swivel of table 18 Hydraulic pump: 1000/1500/3000 1.17 Speed, r, p, m. 1000/1500/3000 Maximum travel of wheel head, mm: head, mm: By hand Hydraulically (approach) 280 Speed, r, p, m. 1000 Grinding wheel dimensions, mm 500 Speed, r, p, m. 3000 Maximum diameter 50 Space Occupied Floor space, mm 2760 × 2350 Highly of machine, mm 2760 × 2350 Maximum diameter 600 Weight	Minimum	150	
Table	Maximum weight of ring		electric motors: Wheel head:
Maximum swivel of table			Speed, r. p. m 1500 Work head:
Wheel Head	mm		Speeds, r. p. m 1000/1500/3000 Hydraulic pump:
head, mm: By hand			Speed, r. p. m 1000 Coolant pump:
(approach) 50 Grinding wheel dimensions, mm: Floor space, mm . 2760 × 2350 Maximum diameter 600 Weight Winimum diameter 400 Weight	head, mm: By hand	280	
Maximum diameter 600 Weight	(approach)	50	Floor space, mm 2760 × 2350
	Maximum diameter Minimum diameter	400	5



ROLLER RING SHOULDERS GRINDING MACHINE

MODEL 3497



The 3497 Roller Ring Shoulders Grinding Machine is designed for grinding taper and spherical shoulders on internal rings of taper roller bearings. Power approach and withdrawal of wheel head, working feed of wheel head (plunge-cut grinding), wheel truing, compensation for wheel wear when diamond dressing are effected hydraulically.

The workpiece is both gripped and released by an air-operated chuck. The machine operating cycle is semi-automatic, and the wheel head is withdrawn when the predetermined, accurate sizing of the work is obtained. The machine is provided with a special loading device for mounting heavy rings (weighing over 8 kg).

СТАНКОИМПОРТ

When hand feed to the wheel head is employed (when grinding to a positive stop), it is possible to compensate for wheel wear.

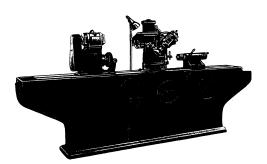
SPECIFICATIONS

2.20.		
Capacity		Speeds
Maximum diameter of work, mm Diameter that can be ground,	500	Work spindle speeds, r, p, m 50; 75; 100; 150; 300
mm:		Drive
Maximum	450 150	220/380 volt, 3 phase, 50 cycle electric motors: Wheel head: Power, kW 2.8
Table and Work Head		Speed, r. p. m
Maximum longitudinal travel of table (by hand), mm	500	Work head: Power, kW 1.1/1.35/1.75 Speeds, r. p. m. 1000/1500/3000 Hydraulic pump:
Wheel Head		Power, kW 1.0
Maximum travel of wheel head, mm:		Speed, r. p. m 1000 Coolant pump:
By hand Hydraulically	100	Power, kW 0.125 Speed, r. p. m
(approach)	150	Space Occupied
mm: Maximum diameter	350	Floor space, mm
Minimum diameter	200 16	Weight
Face	127	Net weight, kg approx. 6200



UNIVERSAL **BROACH SHARPENING MACHINE**

MODEL 360



The 360 Broach Sharpening Machine is designed for sharpening and regrinding either flat or cylindrical broaches including round, spline, serrated or other types. The machine has been especially developed to assist shops in doing their own broach sharpening by providing a rapid and accurate means of maintaining the same tooth form and cutting effectiveness as are originally provided by the broach maker.

Cylindrical and profile broaches are set in headstock and tailstock centers. Flat broaches are clamped in vices or other clamping fixtures fastened to the machine table. The change-over from round to flat broaches is accomplished quickly and conveniently with a few adjustments and without special tools or equipment.

or equipment.

The tailstock center has a vertical adjustment to set the broach to a desired angle.

СТАНКОИМПОРТ

The work table has two manual traverse speeds: the slow table traverse The work table has two manual traverse specus: the slow table traverse is intended for grinding purposes and the faster traverse for indexing. Universal positioning and movement of the grinding wheel are obtained by the state of a rotatable vertical column, a cross slide mounted on a graduated support and a graduated wheel head mounting.

Convenient handwheels on the front of the machine control the travel of the work table and both vertical and traverse movements of the cross slide.

the work table and both vertical and traverse movements of the cross slide. The swivel head slide and table roll on ball bearings mounted between

ways.

A special device is provided for truing the grinding wheel to the desired angle or radius. The machine is equipped with two motors.

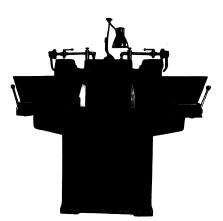
SPECIFICATIONS

_			
Capacity Maximum length of broach, mm Maximum diameter of broach, mm Maximum width of flat broach, mm	1560 100 260	Wheel head: Power, kW Speed, r. p. m. Headstock: Power, kW Speed, r. p. m,	0.65 3000 1.0 1000
Wheel Head Grinding wheel swivel in horizontal plane	20 □	Space Occupied Floor space, mm 4085 Height of machine, mm	× 1400 1600
Drive 220/380 volt, 3 phase, 50 cycle A. C. motors:		Weight Net weight, kg approx	x. 1900



CARBIDE TOOL GRINDING MACHINE

MODEL 3628



The 3628 Tool Grinding Machine is designed for grinding carbide tipped

The 3628 Tool Grinding Machine is designed for grinding carbide tipped tools.

The machine is provided with two grinding wheels. An adjustable table is located at each wheel provided with both angular and horizontal adjustments. Angular adjustments is made by hand. Graduated scales are provided at the sides of the tables to enable the operator to set the tables at the required angle. The scale reading is t°.

Each table is mounted on two slides. The lower slides have a cross movement controlled by hand through nut and screw.

СТАНКОИМПОРТ

The longitudinal movement of the top slides along the working surface of the grinding wheels is also controlled by hand.

The machine is provided with a complete wet grinding system. Suitable deep water trays cast integral with the lower slides return the coolant from the work to the water tank.

SPECIFICATIONS

Capacity		Drive
Maximum size of tools ground,	30 × 45	220/380 volt, 3 phase, 50 cycle A. C. motors: Main drive:
		Power, kW 2.8
		Speed, r. p. m 1500
Grinding Wheels		Coolant pump:
		Power, kW 0.125
Number of wheels	2	Speed, r. p. m 3000
Grinding wheel dimensions, mm:		Space Occupied
Diameter	250	Floor space, mm 1510 × 1125
Face	150	Height of machine, mm 1440
Hole diameter		
noie mameter	100	Weight
Speed of wheel spindle, r. p. m.	1250	Net weight of machine, kg . approx. 980



ELECTRIC EROSION CARBIDE TOOL GRINDER

MODEL 4352



The 4352 Carbide Tool Grinder is designed for sharpening hard alloy tipped tools. Sharpening is accomplished by a steel disc with application of electric current.

The sharpening process is carried out in a special electrolyte by the electric erosion method and comprises: roughing, finishing and lapping coperations.

operations.

СТАНКОИМПОРТ

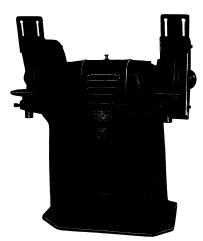
SPECIFICATIONS

Capacity	Drive
Maximum dimensions of tool sharpened, mm:	220/380 volt, 3 phase, 50 cycle A. C. motors:
Minimum 10 × 10	
Maximum 30 × 45	
Maximum length of tool, mm 315	Speed, r. p. m
Distance, axis of spindle to	Table drive:
table, mm 180	Power, k\\' 0.25
	Speed, r. p. m. 1500
	Electrolyte pump:
Sharpening disc	Power, kW 0.1
Material of sharpening disc . Steel 45	Speed, r. p. m 3000
Diameter of sharpening disc,	Total power required, kW . approx. 4
mm 180	Space Occupied
Speeds	Floor space, mm 1080 × 870 Height of machine, mm 1460
	777 - 1 - 1
Sharpening disc speeds,	Weight
r. p. m	Net weight, kg approx. 850



DOUBLE-ENDED DISC GRINDER

MODEL 3 M 634



The 3 M 634 Double-Ended Disc Grinder is designed for snagging and cleaning castings, forgings, etc. The machine is provided with two tables, one for each wheel.

The wheel spindle is mounted on ball bearings and is driven by a motor housed in the base of the machine through a Vee-belt drive.

The motor is mounted on a plate which is provided with screw adjustment to easily regulate the tension of the Vee-belts used on the drive.

СТАНКОИМПОРТ

Truing of the grinding wheels is performed by a dresser mounted in a

Starting and stopping of the machine is through a push-button station mounted on the front of the machine base.

The machine is provided with safety hoods constructed of welded steel

SPECIFICATIONS

Grinding Wheels and Tabl	es	Drive
Number of grinding wheels . Dimensions of grinding wheels,	2	220/380 volt, 3 phase, 50 cycle A. C. motor:
mm:		Power, kW 2.8
Diameter	400	Speed, r. p. m
Face	40	
Hole diameter	203	Space Occupied
Height, floor to center line of wheel spindle, mm Distance between grinding	850	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
wheels, mm	700×80	Weight
Grinding wheel speed, r.p. m.	1398	Net weight, kg approx. 450



DOUBLE-ENDED DISC GRINDER

MODEL 3 M 636



The 3 M 636 Double-Ended Disc Grinder is designed for snagging and cleaning castings, forgings, etc. The machine is provided with two tables, one for each grinding wheel.

The large wheel spindle is mounted on ball bearings and is driven by a motor housed in the base of the machine through a Vee-belt drive and two-

motor housed in the base of the machine through a received with screw adjustment to easily regulate the tension of the Vee-belts used on the drive. Truing of the grinding wheels is performed by a dresser mounted in a special device. Starting and stopping of the machine is through a push-button station mounted on the front of the machine base.

The machine is provided with safety hoods constructed of welded steel

plate.

СТАНКОИМПОРТ

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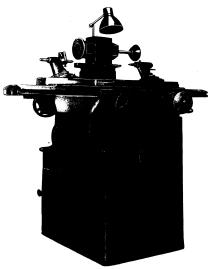
SPECIFICATIONS

Grinding Wheels and Tables	Drive
Number of grinding wheels . Dimensions of grinding wheels, mm:	2 220/380 volt, 3 phase, 50 cycle A. C. motor: Power, kW
Face	00 Speed, r. p. m 1500 75 05
Distance between grinding	50 Space Occupied Floor space, mm 1280 × 750
	00 Height of machine, mm 1340
Working surface of table, mm 200 × 1 Grinding wheel speeds,	10 Weight
r, p, m 955 and 14	25 Net weight, kg approx. 830



UNIVERSAL CUTTER AND TOOL GRINDING MACHINE

MODEL 3A64



The 3 A 64 Universal Cutter and Tool Grinder is designed for sharpening cutting tools, such as: reamers, taps, twist drills, counterborers, radial and tangential chasers, milling cutters, hobs, gear shaper cutters, etc.

СТАНКОИМПОРТ

Cylindrical, surface and internal grinding can also be performed on this machine.

Sharpening and grinding of tools are accomplished by means of standard and special attachments. The attachments are mounted on the table which is

traversed by hand.

The machine may be operated from the front or either side with equal

ease and accuracy.

The table and wheel head have swivel movement.

Two grinding wheels of different shape can be mounted on the ends of the spindle.

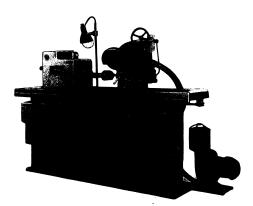
SPECIFICATIONS

Capacity Height of centers, mm 125 Distance between right- and	Maximum swivel of wheel head
left-hand footstock centers, mm	Speeds Grinding wheel spindle speeds, r. p. m
Table	Drive
$\begin{array}{llllllllllllllllllllllllllllllllllll$	220/380 volt, 3 phase, 50 cycle A. C. motors: Power, kW
Maximum swivel of table . +90°: -30°	Space Occupied
Wheel Head Maximum vertical movement	Floor space, mm 1700×1460 Height of machine, mm 1600
of wheel head, mm: Above center of work . 150 Below center of work . 55	Weight Net weight, kg approx. 1000



AUTOMATIC HOB GRINDING MACHINE

MODEL 3 A 642



The 3 A 642 Automatic Hob Grinder is designed for sharpening straight

The 3 A 642 Automatic Hob Grinder is designed for snarpening straight or helical gashed hobs.

The working cycle of the machine (except loading and unloading of the hob) is fully automatic. The automatic cycle includes: traverse of table with hob; indexing of hob in accordance with the number of hob gashes: rotation of hob during grinding to provide the required helix angle of gash; circumferential hob feed and its disengagement after a given amount of stock is removed (pilot light is provided).

The machine is equipped with a special attachment for truing the grinding

wheel.

СТАНКОИМПОРТ

SPECIFICATIONS		
Capacity Height of centers above table, mm	Maximum speed of table traverse, m/min	
that can be sharpened, mm . 200 Maximum face of hob, mm . 200 Number of hob gashes . 8: 9: 10: 12 Helical gash leads, mm . 2500 and higher	Drive 220/380 volt, 3 phase, 50 cycle A. C. motors:	
Table Maximum longitudinal table traverse, mm 400	Grinding wheel: 1.7	
Wheel Head Grinding wheel dimensions,	Power, kW 0.1 Speed r. p. m 3000 Hydraulic pump:	
mm	Power, kW 2.8 Speed, r. p. m 1500	
head + 25	Space Occupied	
Maximum vertical travel of grinding wheel, mm 150	Floor space, mm 2065 × 945 Height of machine, mm 1655	
Speeds and Feeds Speed of grinding wheel,	Weight	



TWIST DRILL GRINDING MACHINE

MODEL 3 B 652



The 3 B652 Twist Drill Grinder is designed for grinding right- and left-hand twist drills.

The surface of the ground drill point forms a cone with an axis at a con-stant angle of 45° to the drill axis, both these axes not being crossed.

The ground cone surface is formed by hand rotation of the drill holder spindle about its own axis.

СТАНКОИМПОРТ

The machine can be advantageously applied for grinding drills with various point and helix angles. Each lip of the drill is ground in consecutive order by hand turning the drill clamped in a drill holder through an angle of 180°. The amount of stock removed per setting does not exceed 0.1 mm. The grinding wheel spindle, in addition to a constant speed rotary motion, has a reciprocating motion which is required to secure uniform wear of the grinding wheel face.

The longitudinal and cross movements of the work slide as mall as forward.

grinding wheel face.

The longitudinal and cross movements of the work slide as well as forward and reverse rotation of the drill holder spindle are hand operated.

To grind left-hand drills, a special chuck is mounted on the slide.

The spindle of the machine is driven by a separate motor.

SPECIFICATIONS

BI ESTITIONS		
Capacity Diameter of drill ground, mm: Minimum Maximum Point angle: Minimum Maximum	Maximum angle drill holder 100	
Grinding Wheel	procating motion, strokes per minute	
Maximum diameter of grin- ding wheel, mm	125 16 220 380 volt, 3 phase, 50 cycle A, C, motor; Power, kW 0.65 Speed, r. p. m 3000	
Slide Maximum travel of slide, mm: Along spindle axis Normally to spindle axis For depth of cut	Space Occupied Floor space, mm	



AUTOMATIC TWIST DRILL GRINDING MACHINE

MODEL 3659 A



The 3659 A Automatic Twist Drill Grinder is designed for grinding righthand twist drills and three- and four-lip core drills.

Grinding is effected by bevel surface of the grinding wheel and is carried

out in five combined motions:
rotary motion of drill clamped in chuck;
planet motion of grinding wheel spindle in plane perpendicular to wheel
axis;

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oscillating motion of grinding wheel spindle in direction parallel to its

axis:

feeding drill to grinding wheel in direction parallel to spindle axis;

rotary motion of grinding wheel.

All the motions are performed automatically. The first three motions are synchronized and serve for forming clearance angles. The second motion, in addition, serves for uniform wear of the grinding wheel.

Grinding double angle point drills can be carried out in this machine as well

as well.

The machine is driven by a motor installed inside the base of the machine.

SPECIFICATIONS

Capacity		For grinding three-lip	
Diameter of drills and core		core drills	30
drills ground, mm: Minimum Maximum	10 80	core drills	32.5
Range of drill point angles . Range of clearance angles . Angle of double angle point	70—140° 6—17°	of grinding wheel spindle, strokes per minute Number of automatic feeds	94.5 8
drills ground	70° 2, 3 and 4	Automatic feed per lip ground (at beginning of working cycle), mm:	
ground	right-hand	Minimum Maximum	. 0.005 0.04
Maximum stock removed per one automatic cycle, mm .	2.5	Drive	0.01
		220/380 volt, 3 phase, 50 cycle	
Work Slide and Grinding	Wheel	A. C. motors:	
Maximum travel of slide (by hand), mm	Wheel	A. C. motors: Main drive: Power, kW Speed, r, p, m.	2.8 1500
Maximum travel of slide (by hand), mm	100 300	A. C. motors: Main drive: Power, kW	
Maximum travel of slide (by hand), mm Grinding wheel dimensions, mm:	100	A. C. motors: Main drive: Power, kW Speed, r. p. m. Coolant pump: Power, kW Speed, r. p. m.	1500 0.125
Maximum travel of slide (by hand), mm	100 300 200	A. C. motors: Main drive: Power, kW	0.125 3000
Maximum travel of slide (by hand), mm	100 300 200	A. C. motors: Main drive: Power, kW Speed, r. p. m. Coolant pump: Power, kW Speed, r. p. m. Space Occupied Floor space, mm	$\begin{array}{c} 1500 \\ 0.125 \\ 3000 \\ \end{array}$ 1475×780



FINE MODULE HOB GRINDING MACHINE

MODEL 3660



The ${\it 3}660~{\it Hob}$ Grinder is designed for sharpening fine module hobs with straight gashes, as well as disc milling cutters.

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The machine is arranged for sharpening fine module hobs with 10, 12 and 14 gashes. For hobs with other number of gashes a corresponding index plate should be mounted on the work spindle of the machine.

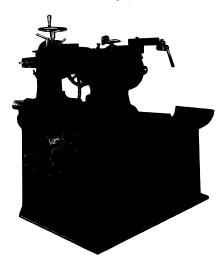
SPECIFICATIONS

AIIOND	PECIFIC	
Speeds		Capacity
Speed of grinding wheel, r, p, m, Speed of wheel head traverse,	45 30	Maximum diameter of hob that can be sharpened mm Maximum face of hob, mm
mm/min.: Minimum Maximum	e	Number of teeth that can be sharpened (at corresponding index plate):
	90	Minimum Maximum
Drive		Distance between wheel and work spindle axes, mm:
220/380 volt, 3 phase, 50 cycle A. C. motors:	40 60	Minimum
Speed, r. p. m.		Wheel Head
Space Occupied Floor space, mm	30 50 75	Traverse of wheel head along work axis, mm: Minimum Maximum Diameter of grinding wheel, mm
		Work Spindle
Weight		Angular movement of work spindle per revolution of
Net weight, kg	3 50'	planetary mechanism disc .
	Speeds Speed of grinding wheel, r.p.m. wheel head traverse, mm/min; Minimum Maximum Drive 220/380 volt, 3 phase, 50 cycle A. C. motors: Power, kW. Speed, r, p, m. Speed, r, p, m. Height of machine, mm Weight	Speed of grinding wheel, r.p. m. 30 Speed of grinding wheel, r.p. m. Minimum Maximum Drive 220/380 volt, 3 phase, 50 cycle A. C. motors: Rever, kW Speed, r.p. m. 30 Space Occupied Floor space, mm Height of machine, mm



AUTOMATIC FACE MILLING CUTTER GRINDING MACHINE

MODEL 3667



The 3667 Cutter Grinder is designed for grinding face milling cutters up to 700 mm in diameter with a maximum blade length of 120 mm. The cutter to be ground is mounted on the work head spindle and the grinding wheel on the grinding head spindle. The wheel head has a reciprocating motion

СТАНКОИМПОРТ

along the tooth cutting edge. The working cycle of the machine is completely automatic. It is only necessary to clamp the cutter to be ground, the machine goes through the operations of indexing and grinding each tooth in succession until the cutter is completely and accurately ground.

The work head feed is effected continuously until a very small grinding stock is left. The feed is then diminished and after reaching the predetermined

depth of grinding it is automatically disengaged.

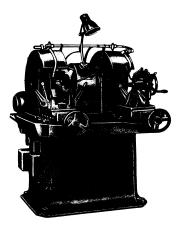
SPECIFICATIONS

Capacity Diameter of face cutter ground, mm: Minimum Maximum Number of teeth which can be ground: Minimum Maximum	100 700 4 48	Wheel head table strokes per minute: Minimum . 24 Maximum . 38 Range of work head table feeds, mm per revolution of cutter . 0.02—0.20
Length of blade which can be		Drive
ground, mm	120	220/380 volt, 3 phase, 50 cycle A.C. motors:
Wheel Head and Table		Grinding wheel:
Maximum wheel head travel on table, mm	550 73 154	Power, kW 1.0
Grinding wheel spindle swivel	± 30°	
Work Head and Table		Space Occupied
Work head table travel, mm Work head rotation through	330 ± 90°	Floor space, mm 1590 1240 Height of machine, mm 1400
Speeds and Feeds		Weight
Grinding wheel spindle speed,	2860	Net weight, kg approx. 1500



ROCK DRILL SHARPENING MACHINE

MODEL 367



The 367 Rock Drill Sharpening Machine is designed for sharpening chisel

The 367 Rock Drill Sharpening Machine is designed for sharpening chisel single-edged and four-edged drilling bits.

A spindle for bit clamping and a hand feed mechanism are provided at both sides of the machine.

When sharpening a four-edged bit the latter is automatically indexed through an angle of 90° after its full withdrawal from the grinding wheel. The machine is equipped with a separate electric motor.

The spindle is driven through a Vee-belt drive.

СТАНКОИМПОРТ

SPECIFICATIONS

Capacity Diameter of grinding wheel, mm Slide travel, mm Automatic indexing of four- edged bit Swivel of four-edged bit	500 145 90°	Drive 220/380 volt, 3 phase, 50 cycle A. C. motor: Power, kW
spindle at circumference sharpening . Swivel of chisel single-edged bit spindle at circumference sharpening	± 10° 0—15°	$\begin{array}{cccc} \textbf{Space Occupied} \\ Floor space, mm & . & . & . & . 1200 \times 1500 \\ Height of machine, mm & . & . & . & 1500 \end{array}$
Speed of grinding wheel, r, p, m.	1070	Weight Net weight, kg approx. 1200



CIRCULAR SAW SHARPENING MACHINE MODEL 3692



The 3692 Saw Sharpening Machine is designed for accurate face sharpening and backing-off the teeth of circular saws.

Alternate low and high teeth with a double level grind on the top of the teeth can be also performed in this machine.

The machine is of massive, rigid construction insuring a steady smooth action in bringing the grinding wheel into contact with the saw teeth.

The grinding head moves up and down and the grinding action when sharpening the tooth is by the plunge-cut method.

СТАНКОИМПОРТ

When grinding by this method, each tooth is fed to grinding position and the saw then remains stationary while the face of tooth is being ground, and then the next tooth is fed to position and the operation repeated.

The saw arbor is fitted to an adjustable slide.

The working cycle of the machine is fully automatic.

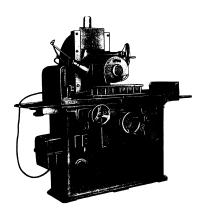
SPECIFICATIONS

Capacity		Feeds
Diameter of circular saws, mm: Minimum Maximum Number of circular saw teeth	300 1200	Range of saw arbor slide feeds, mm per one revolution of saw 0-0.25
which can be sharpened:		Drive
Minimum	56 240	220/380 volt, 3 phase, 50 cycle A. C. motors:
Wheel Head		Wheel head drive:
Grinding wheel dimensions.		Power, kW 0.65
mm:		Speed, r. p. m 3000 Saw feed drive:
Diameter	200	Power, kW 1
Face	10 32	Speed, r. p. m
Maximum swivel of wheel	32	
head	20°	Space Occupied
mm:		Floor space, mm 1765 × 900
Minimum	4	Height of machine, mm 740
Maximum	12	
Saw Arbor Slide		Weight
Maximum slide travel, mm .	500	Net weight, kg approx. 1050



HYDRAULIC SURFACE GRINDING MACHINE

MODEL 371 M 1



The 371 M I Surface Grinding Machine is designed for grinding with the periphery of the wheel plane surfaces of parts held on working surfaces of the table or magnetic chuck.

the table or magnetic chuck.

Both the longitudinal table traverse and the cross feed of the wheel head are operated either hydraulically or by hand.

The vertical feed of the wheel head (for depth of grinding) is accomplished by hand and is adjusted in accordance with the graduations of the hand-wheel dial.

The machine is equipped with three electric motors.

СТАНКОИМПОРТ

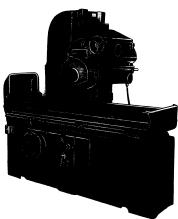
SPECIFICATIONS

SPECIFICATIONS		
Capacity Maximum dimensions of		Table speeds (hydraulic),
Maximum dimensions of work ground (length × width × height), mm 600 >	× 200 × 300	Minimum 0 Maximum 18 Wheel head column inter-
Work Table		mittent cross feed (hydrau-
Working surface of table (length × width), mm Table traverse (hydraulic),	600 × 200	lic), mm per table stroke: Minimum 0.2 Maximum 2
mm:	100	Wheel head vertical feed (by hand), mm per graduation
Maximum	650	of dial 0.01
Distance from spindle axis to table surface, mm:		Drive
Minimum	65 425	220/380 volt, 3 phase, 50 cycle A. C. motors: Wheel head (built in
Wheel Head		motor):
Maximum cross travel of wheel head (by hand and		Power, kW 2.8 Speed, r. p. m 3000 Hydraulic pump:
hydraulically), mm Maximum vertical travel of	240	Power, kW
wheel head (by hand), mm Grinding wheel dimensions, mm:	360	Coolant pump: Power, kW 0.125 Speed, r. p. m 3000
Minimum diameter	130	Speed, 1. p. m.,
Maximum diameter	250	Space Occupied
Face	20	Floor space, mm 2500 × 1590
Speeds and Feeds		Height of machine, mm 2000
Speed of grinding wheel		Weight
spindle, r. p. m	2870	Net weight, kg approx. 1950



HYDRAULIC SURFACE GRINDING MACHINE

MODEL 372 B



The 372B Surface Grinding Machine is designed for precision grinding plane surfaces of parts held on working surfaces of the table or magnetic chuck.

chuck.

Both the longitudinal table travel and the cross feed of the wheel head are hydraulically actuated; the cross feed of the wheel head may also be operated by hand.

The cross feed of the grinding wheel may be set so as to operate at each table reversal or continuously. The amount of intermittent cross feed is con-

СТАНКОИМПОРТ

trolled by a hand wheel, the speed of continuous feed by a hydraulic control valve. The vertical feed of the wheel head is accomplished by hand. The amount of vertical feed is indicated on a fine feed dial or on a handwheel dial. The machine is equipped with three motors.

SPECIFICATIONS

Capacity Maximum dimensions of work ground, mm: Length	1000	Table speeds (hydraulic), m/min,: Minimum Maximum	3
Width	300 400	Wheel head cross feeds (hy- draulic): Intermittent, mm per table	
Work Table		stroke:	
Working surface of table, mm: Length Width Table traverse (hydraulic), mm:	1000 300	Minimum Maximum Continuous, mm/min.: Minimum Maximum	3 30 500 4500
Minimum Maximum Distance, spindle axis to wor-	200 1100	Wheel head vertical feed (hand operated), mm per graduation of dial	0.01
king surface of table, mm:	125	Drive	
Minimum	585	220/380 volt, 3 phase, 50 cycle	
		A. C. motors:	
Wheel Head		Wheel head (built-in mo-	
Maximum movement of wheel		Wheel head (built-in mo- tor): Power, kW	4.5
Maximum movement of wheel head, mm: Cross, hydraulic and		Wheel head (built-in motor): Power, kW	4.5 1500
Maximum movement of wheel head, mm: Cross, hydraulic and hand operated	350	Wheel head (built-in motor): Power, kW	1500 2.8
Maximum movement of wheel head, mm: Cross, hydraulic and hand operated. Vertical, hand operated Grinding wheel dimensions,	350 460	Wheel head (built-in motor): Power, kW Speed, r. p. m Hydraulic pump. Power, kW Speed, r. p. m Coolant pump:	1500 2.8 1000
Maximum movement of wheel head, mm: Cross, hydraulic and hand operated Vertical, hand operated		Wheel head (built-in motor): Power, kW Speed, r.p.m. Hydraulic pump: Power, kW Speed, r.p.m. Coolant pump: Power, kW	1500 2.8 1000 0.125
Maximum movement of wheel head, mm: Cross, hydraulic and hand operated. Grinding wheel dimensions, mm: Immum diameter Maximum diameter Face	250 350 40	Wheel head (built-in motor): Power, kW Speed, r. p. m Hydraulic pump. Power, kW Speed, r. p. m Coolant pump:	1500 2.8 1000
Maximum movement of wheel head, mm: Cross, hydraulic and hand operated. Vertical, hand operated Grinding wheel dimensions, mm: Minimum diameter . Maximum diameter .	460 250 350	Wheel head (built-in mo- tor): Power, kW Speed, r. p. m. Hydraulic pump- Power, kW Speed, r. p. m. Coolant pump: Power, kW Speed, r. p. m. Space Occupied	2.8 1000 0.125 3000
Maximum movement of wheel head, mm: Cross, hydraulic and hand operated . Hole dimensions, minimum diameter . Maximum diameter . Hole diameter . Hole diameter .	250 350 40	Wheel head (built-in mo- tor): Power, kW Speed, r. p. m. Hydraulic pump. Power, kW Speed, r. p. m. Compart kW Speed, r. p. m.	1500 2.8 1000 0.125 3000 3505×1845
Maximum movement of wheel head, mm: Cross, hydraulic and hand operated. Grinding wheel dimensions, mm: Immum diameter Maximum diameter Face	250 350 40	Wheel head (built-in mo- tor): Power, kW Speed, r, p, m. Hydraulic pump- Power, kW Speed, r, p, m. Cover, kW Speed, r, p, m. Speed, r, p, m. Space Occupied Floor space, mm	1500 2.8 1000 0.125 3000 3505×1845



HYDRAULIC VERTICAL SPINDLE **SURFACE GRINDING MACHINE**

MODEL 373



The 373 Hydraulic Vertical Spindle Surface Grinding Machine is designed for accurate and rapid grinding of flat surfaces of parts held on working surfaces of the table or magnetic chuck and is used on a wide variety in both mass and lot production.

The machine has a vertical spindle with a segmental grinding wheel and a reciprocating hydraulically operated table. The table speeds are infinitely variable, and any predetermined slow speed for finish grinding is instantly obtained by means of the table hydraulic control. The length of the table stroke is controlled by adjustable does. stroke is controlled by adjustable dogs.

СТАНКОИМПОРТ

The feed to the wheel head may be applied automatically or by hand. A wheel dressing device is mounted on the wheel head. The machine is equipped with direct motor drive, a totally enclosed motor being incorporated in the grinding wheel head, and the oil hydraulic drive to the work table having an independent motor. A separate motor is provided for the cooling system.

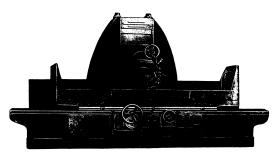
SPECIFICATIONS

Width	Table speeds (hydraulic), mmini. mmini. 3 3 3 3 3 3 3 3 3
Work Table	
Width	Drive 50 220 380 volt, 3 phase, 50 cycle 00 A. C. motors:
Table traverse (hydraulic), mm; Minimum 2 Maximum 11	
Wheel Head	Speed, r. p. m
Maximum vertical movement of wheel head, mm	Coolant pump: Power, kW 0.125 Speed, r, p. m, 3000
segments	6 Space Occupied 50 Floor space, mm 3450 - 1645
Speeds and Feeds	Height of machine, mm 2135
Grinding wheel spindle speed, r. p. m. 14	Weight 50 Net weight, kg approx. 5000



HYDRAULIC SURFACE GRINDING MACHINE

MODEL 3724



The 3724 Surface Grinding Machine is designed for precision grinding plane surface of parts held on working surfaces of the table or magnetic chuck. The extra heavy base of the machine cast as a single unit is of rigid design and is heavily braced with substantial cross girths. Massive double-column castings rigidly bolted to the rear part of the base and reinforced at the top by a heavy connecting brace make the sturdy support for the wheel head assembly.

Both the longitudinal table travel and the cross feed of the wheel head are hydraulically actuated; the cross feed of the wheel head may also be operated by hand.

The cross feed of the grinding wheel may be set so as to operate at a city.

operated by hand.

The cross feed of the grinding wheel may be set so as to operate at each table reversal or continuously. The amount of intermittent cross feed and speed of continuous feed are controlled by two levers.

The vertical feed of the wheel head is accomplished by hand. The amount

of vertical feed is indicated on a hand wheel dial.

СТАНКОИМПОРТ

Work can be ground to very close limits of accuracy by means of a small vernier dial with graduation in 0.0025 mm.

The wheel head has a power-operated raising and lowering device.

The machine is equipped with four motors and a motor-generator set for

magnetic chuck operation.

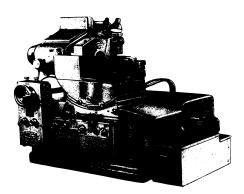
SPECIFICATIONS

Capacity		Speeds
Maximum dimensions of work		Grinding wheel spindle speed,
ground, mm:		r. p. m
Length	2000	Table speeds (hydraulic),
Width	400	m/min.:
Height	600	Minimum S Maximum 33
		Maximum
Work Table		feeds (hydraulic), mm per
Working surface of table, mm:		table stroke 3—50
Length	2000	
Width	400	Drive
Table traverse (hydraulic),		220/380 volt, 3 phase, 50 cycle
mm:	800	A. C. motors:
Minimum	300 2300	Wheel head:
Maximum	2300	Power, kW 28
		Speed, r. p. m. 1500
Wheel Head		Wheel head rapid traverse: Power, kW 1.1
Maximum movement of wheel		Power, kW
head mm:		Hydraulic pump:
Cross:		Power, kW 9.1
Hydraulic Hand operated	500	Speed, r. p. m 1000
Vertical (hand operated)	520 670	Coolant pump:
Wheel head travel per one	670	Power, kW 0.65
graduation of dial, mm:		Speed, r, p. m, 3000
Cross	0.02	Motor-generator set:
Vertical	0.01	Power, kW
Wheel head travel per one		Speed, r. p. m
revolution of hand wheel,		volts:
mm:		Power, kW 2.6
Cross	2.5	Speed, r. p. m
Grinding wheel dimensions.		
mm:		Space Occupied
Minimum diameter	375	Floor space, mm 5000 × 2505
Maximum diameter	500	Height of machine, mm 2955
Minimum face	60	Weight
Maximum face	100	3
Hole diameter	305	Net weight, kg approx. 17000



ROTARY SURFACE GRINDING MACHINE

MODEL 3740



The 3740 Rotary Surface Grinding Machine is designed for grinding flat, convex or concave surfaces on a wide variety of parts and assures high precision, perfect finish and maximum production.

It is especially recommended for grinding the faces of piston rings up to 400 mm in diameter.

The machine grinds with the periphery of the wheel, thus producing a concentric finish.

oncentric finish.

The wheel spindle unit is mounted on a vertically adjustable slide which is supported on the column of the machine. The vertical movement of the wheel slide may be accomplished either manually or hydraulically.

СТАНКОИМПОРТ

The work to be ground is held on a rotating magnetic chuck which is carried on a reciprocating table. The rotary motion of the chuck and the reciprocating motion of the table are effected by hydraulic means, thus allowing on infinitely variable range of speeds.

The grinding wheel spindle is driven by a built-in electric motor.

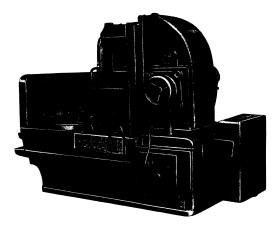
SPECIFICATIONS

Capacity		Range of table reciprocating
Diameter of magnetic chuck, mm Maximum dimensions of work	400	speeds (infinitely variable), m/min 0.6—4 Range of wheel slide power feeds, mm per revolution of
that can be ground, mm: Diameter	400	chuck 0.005—0.03
Height	175	
Maximum swivel of table:	110	Drive
Concave surfaces	15℃	220/380 volt, 3 phase, 50 cycle
Convex surfaces	10	A. C. motors:
Maximum travel of wheel		Grinding wheel spindle:
slide, mm	205	Power, kW
Maximum table travel (hy-		Speed, r. p. m
draulic), mm	374	Hydraulic pump:
Grinding wheel dimensions,		Power, kW 5
mm:		Speed, r. p. m 1000
Maximum outside dia-		Coolant pump:
meter	350	Power, kW 0.15
Hole diameter	127	Speed, r. p. m 3000
Face	40	
		Space Occupied
Speeds and Feeds		Floor space, mm
Grinding wheel spindle speed,		Height of machine, mm 1900
r, p, m, Range of chuck speeds (infini-	1440	Weight
tely variable) r. n. m.	40-210	Net weight kg approx 3750



VERTICAL ROTARY SURFACE GRINDING MACHINE

MODEL 3756



The 3756 Single Spindle Rotary Table Vertical Surface Grinding Machine is used on a wide variety in both mass and lot production. The work is laid on a rotary magnetic chuck and the table is moved horizontally to bring its centre under the face of the cylinder wheel. In this position the chuck rotates continuously while the wheel head is gradually and automatically fed downward until the desired size of the work is reached. Size may be determined by setting an automatic feed stop.

The main motor is built into the wheel head.

СТАНКОИМПОРТ

The compact and rigid construction of the machine gives the necessary support to wheel and work. Finely finished and accurate surfaces, both as to size and as to flatness, are produced by the machine. Rapid production is another point in favour of the machine.

The machine is equipped with five motors.

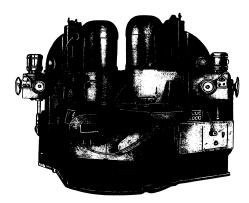
SPECIFICATIONS

Capacity Distance, table top to bottom of grinding wheel, mm: Minimum Maximum Distance, center line of spindle to column ways, mm	0 360 384	Wheel head vertical feeds, mm'min. 0.16—1.7 Table longitudinal rapid traverse speed, m/min, 3.3 Wheel head vertical rapid speed, m'min, 0.10 table speed, 0.10 table s
Maximum dimensions of work		Drive
ground, mm: Height	350 750	220/380 volt, 3 phase, 50 cycle A. C. motors: Wheel head:
Magnetic chuck diameter, mm	750	Power, kW 2
Maximum longitudinal travel of table, mm	550 600 110	Speed, r. p. m 1000 Table longitudinal move- ment: Power, kW 1.7
Wheel Head	110	Speed, r. p. m 1000
Maximum vertical travel of wheel head (mechanically and		Chuck rotation: Power, kW 2.8 Speed, r, p, m,
by hand), mm Vertical travel of wheel head per one graduation of dial,	450	Wheel head movement: Power, kW 28
mm Grinding wheel dimensions,	0.01	Speed, r. p. m 1000 Coolant pump: Power, kW 0.65
mm: External diameter Internal diameter	450 380	Speed, r. p. m
Maximum height	150	Space Occupied
Minimum height	35	Floor space, mm 2600×1565 Height of machine, mm
Grinding wheel speed, r. p. m.	975	
Magnetic chuck speeds,	14; 20; 29	Weight Net weight, kg approx. 7300



AUTOMATIC TWO SPINDLE ROTARY SURFACE GRINDING MACHINE

MODEL 3772 9



The 3772 9 Automatic Rotary Surface Grinder is designed for the continuous surface grinding of a very wide range of ferromagnetic workpieces in

both mass and large lot manufacture.

The workpieces pass in succession underneath two grinding wheels for rough and finish stock removal in selected steps to close tolerances in size, rough and imish stork removal in searched steps to close doct-cances in size flatness and finish. Thus, the work is completely processed in one pass through the machine.

The working cycle of the machine is completely automatic, once the work is loaded on the feeding table. Conveying the workpieces from the feeding

СТАНКОИМПОРТ

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table to the magnetic chuck, rough and finish face grinding, measuring the work size, compensation for wheel wear, unloading and demagnetizing of work are all performed by the machine automatically.

The machine is equipped with a washing attachment; this is to wash work as it comes from the Automatic Grinder.

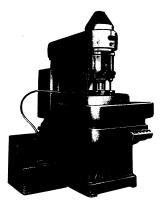
SPECIFICATIONS

Capacity Dimensions of work ground, mm:		Wheel head movement per one revolution of dial, mm 1.5
Work must lie within two circles, diameter . Height of work, grin-	6601000	Speeds Speed of grinding wheel spindles, r. p. m
ding with demagnetizer and automatic sizer. Height of work grin- ding without demagne-	50	Number of magnetic chuck speeds
tizer and automatic sizer	200	speeds, r. p. m 0.24—1.3 Speed of wheel head rapid movement m/min 0.586
Magnetic Chuck		movement, m/min 0.586
Inner diameter of magnetic chuck, mm	660 1000	Drive 220.380 volt, 3 phase, 50 cycle A. C. motors: Wheel head (2 motors):
Wheel Heads		Power, kW 28
Number of wheel heads Grinding wheel dimensions,	2	Speed, r. p. m
mm. External diameter Internal diameter	450 250	Speed, r. p. m. 1000
Maximum height	250 125	Space Occupied
Maximum vertical travel of wheel head (mechanically	120	Floor space, mm 2780 × 2380 Height of machine, mm 2550
and by hand), mm . Wheel head movement per one	200	Weight
graduation of dial, mm	0.01	Net weight, kg approx. 13000



VERTICAL HYDRAULIC LAPPING MACHINE

MODEL 3816



The 3816 Hydraulic Lapping Machine is designed to produce flat or cylindrical surfaces within extremely close tolerances and with a high degree of finish.

The principal characteristics of the machine which distinguish it from a grinding machine is the movement of the work relative to the laps. By means of a driving mechanism the work is passed along an ever changing, horizontal path between two revolving laps which slightly reduce its size and refine its surface. This action climinates completely the parallel grain marks in the work surface left by grinding.

СТАНКОИМПОРТ

The machine is constructed to use either fine grain cast-iron laps in conjunction with a special emulsion, or abrasive laps in conjunction with a

suitable cooling and lubricant fluid.

The upper lap is mounted on a heavy spindle carried in a sliding quill.

The drive is through a multiple Vee-belt. The upper lap is counterweighed so that only hydraulic pressure is applied to the work. A stop limits the downward position of the upper lap. One motor drives both the upper and

downward position of the upper lap. One motor drives both the upper and the lower laps and the work.

The machine is equipped with a special device which automatically stops the laps and raises the upper lap when the work is finished. The arrangements of the machine for flat or cylindrical work are slightly different.

When lapping flat workpieces the workholder receives a combined rotation and eccentric movement. When cylindrical work are lapped the workholder drive is disengaged and the difference in speeds of the rotating laps through frictional contact with the work causes the workholder to rotate about a stationary vertical pin set eccentrically with the lap axis.

A special truing device trues the upper and lower abrasive lap faces.

SPECIFICATIONS

Capacity Maximum diameter or thick-		Workholder speeds, r. p. m 11.5: 22 Rapid axial movement of
ness of work to be lapped, mm	95	upper lap spindle, m/min. 2.25
Maximum length of work to be lapped, mm	160	Drive
be tapped, min	100	220/380 volt, 3 phase, 50 cycle
Laps		A. C. motors:
Diameter of laps, mm:		Main drive: Power kW 7.0
External	600	
Internal	305	Speed, r. p. m 1500 Hydraulic pump:
Face width of laps, mm:		Power, kW 1.0
Cast-iron laps:	33	Speed, r. p. m 1000
Minimum	53	Coolant pump:
Abrasive laps:	55	Power, kW 0.15
Minimum	23	Speed, r. p. m 3000
Maximum	63	
Maximum upper lap spindle		Space Occupied
axial movement, mm:	4.40	
Hydraulic	148 225	Floor space, mm
By hand	225	Height of machine, min 2020
Speeds		
Upper lap speeds, r. p. m	53; 102	Weight
Lower lap speeds, r. p. m.	58; 112	Net weight, kg approx. 4300



TOOL LAPPING MACHINE

MODEL 3818



The 3818 Tool Lapping Machine is designed for lapping various types of sharpened carbide tipped tools.

Lapping is done by a disc made of special cast iron charged with paste compound.

Diamond dust, boron carbide, carborundum, etc. are used as lapping materials.

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The tool to be lapped is placed on the swiveling table of the machine and lapped by hand.

and lapped by hand.

The lapping disc is driven by a separate electric motor through a belt drive, a worm gearing and a flexible coupling.

A reservoir with kerosene intended for wetting the lapping disc is located in the upper part of the disc guard.

In conditions of mass production when a great number of similar tools are to be lapped it is recommended to use special fixtures for lapping the faces and back flanks of the tools.

SPECIFICATIONS

Capacity	Drive
Diameter of lapping disc, mm Height of disc center over table, mm 20 Size of tools to be lapped, mm: Minimum 6 × 6 Maximum 40 × 40 40 × 40 40 × 40 40 × 40 40 × 40 40	220/380 voit, 3 phase, 50 cycle A. C. motor: Power, kW 0.65 Speed, r. p. m 1500
Table Swivel of table $\pm 30^{\circ}$: -10°	
Speeds Speed of disc, r. p. m	Weight Net weight, kg approx. 270



VERTICAL SINGLE SPINDLE HYDRAULIC HONING MACHINE

MODEL ΟΦ-20



The OΦ-20 Vertical Honing Machine is designed for the honing bores in various workpieces of cast iron, unheat-treated and hardened steel.

Extreme precision and fine surface finish in bores are obtained by the following combined simultaneous motions: rotary motion of the tool, reci-

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procating motion of the spindle head and continuous oscillation of the tool spindle relative to the spindle head of an amplitude varying from 0 to 4 mm. The machine is provided with a device for adjusting the honing time. The machine cycle is completely automatic, and is distinguishable for high output.

It is designed primarily for

It is designed primarily for mass and large lot production.

SPECIFICATIONS

Capacity		Dilve	
Distance, spindle axis to co- lumn ways, mm Distance, end of spindle to working surface of table,	78	220/380 volt, 3 phase, 50 cycle A. C. motors: Spindle rotation: Power, kW	1.0 1500
mm: Minimum Maximum	405 655	Speed, r. p. m Hydraulic feed of spindle head:	
Maximum diameter of bore		Power, kW	1.7
honed, mm	50	Speed, r. p. m	1500
Maximum travel of spindle head, mm	250	Power, kW	0.125 3000
Speeds and Feeds		Space Occupied	
Number of spindle speeds	500: 780	Floor space, mm Height of machine, mm	$885 \times 795 \\ 1900$
speeds, m/min Number of complete oscilla-	0-12	Weight	
tions of spindle per min Size of oscillations, mm	0-4	Net weight (without set-ups), kg ap	prox. 1000



VERTICAL SINGLE SPINDLE HYDRAULIC HONING MACHINE

MODEL 383



The 383 Hydraulic Honing Machine is designed for the honing of a wide variety of parts and especially for cylinders of internal combustion engines, including automobile, Diesel and airplane engines, cylinder liners, tractor motor sleeves, etc. Honing is accomplished by simultaneous rotation and

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reciprocation of the hone abrasives under pressure in the bore. The heavy cast-iron base provides rigid foundation for the machine and a large reservoir for the coolant.

The rigid box-section cast-iron column has accurately machined ways and

for the coolant.

The rigid box-section cast-iron column has accurately machined ways and maintains accurate alignment of spindle.

Separate motors are used for rotations and for reciprocations of the spindle. The rotation and reciprocation of the hone may be started and stopped independently of each other.

A vertical motor mounted on the top of the machine and an enclosed gear box provide three changes of spindle speeds. These changes are instantly obtained by a conveniently placed lever. Readily accessible pick-off gears, supplied as extra equipment, provide means for changing the rate of spindle speeds. A hydraulic cylinder provides balanced hydraulic pressure for reciprocating the hone steadily and reversing direction of movement without shocks, so necessary in obtaining a high degree of accuracy. The reciprocating speeds are infinitely variable through adjustment of a feed control valve. A single lever controls all the hydraulic movements of the spindle, including gradually lowering the hone, reciprocating, return up stroke and stopping. A conveniently located push-button station provides accurate control of the electrical system for starting and stopping the spindle.

A motor driven pump and filtering device furnish a copious flow of clean coolant to the work bore during the honing operation.

SPECIFICATIONS

Capacity Diameter of bore honed, mm: 85 Minimum 85 Maximum 160	Standard spindle speeds, r, p, m. 114: 180: 284
Spindle and Table	Drive
Reciprocating travel of spindle,	
mm: Minimum 60 Maximum 450 Distance, center of spindle to	220/380 volt, 3 phase, 50 cycle A. C. motors: Spindle rotation: Power, kW 10
face of column, mm 350	Speed, r. p. m 1500
Distance, spindle to plain raising screw table, mm: Minimum	Hydraulic pump: Power, kW
Taper in spindle Morse No. 4 Working surface of plain rai-	Power, kW
sing table, mm	Space Occupied
sing table, mm 450	Floor space, mm 1570 × 1200 Height of machine, mm 3050
Speeds	Weight
Number of spindle rotation	
speeds 3	Net weight, kg approx. 2450



VERTICAL SINGLE SPINDLE HONING MACHNIE

MODEL 3 A 833



The 3 A 833 Internal Honer is a mechanically actuated machine designed for honing a wide variety of parts and especially for reconditioning after service cylinders of internal combustion engines, including automobile, Diesel

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and airplane engines, cylinder liners, tractor motor sleeves, etc. Honing is accomplished by simultaneous rotation and reciprocation of the hone abrasives under pressure in the bore.

The heavy cast-iron base provides rigid foundation for the machine and a reservoir for the coolant. The rigid box-section cast-iron column maintains except the diagramment of spindle.

a reservoir for the coolant. The rigid box-section cast-iron column maintains accurate alignment of spindle.

An electric motor mounted behind the column is used for rotations and for reciprocations of the spindle. The rotation and reciprocation of the hone may be started and stopped independently of each other.

An enclosed gear box provides three changes of spindle speeds. These changes are instantly obtained by a conveniently placed lever. The reciprocating motion of the spindle is produced mechanically through a screw and two friction clutches. The spindle stroke is easily set by means of adjustable dogs.

A conveniently located push-button station provides accurate control of the electrical system for starting and stopping the spindle. A motor-driven pump and filtering device furnish a copious flow of clean coolant to the work bore during the honing operation. The machine is supplied with a fixture for securing tractor motor sleeves.

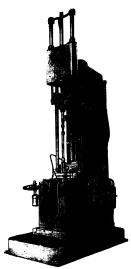
SPECIFICATIONS

SPECIFICATIONS		
Capacity Maximum diameter of bore honed, mm	Spindle speeds, r, p, m, 125: 185: 259	
Spindle and Table Maximum vertical travel of spindle, mm	220 360 V01, or plants of A. C. motors: Minimum KW 4.5 Speed, r. p. m. 1500 Coolant pump: Power, kW 0.125 Speed, r. p. m. 3000	
Minimum 1050 Taper in spindle Morse No. 4 Working surface of table, mm 1000 × 450 Speeds Number of spindle rotation speeds 3	Space Occupied Floor space, mm	



VERTICAL SINGLE SPINDLE HYDRAULIC HONING MACHINE

MODEL 384



The 384 Hydraulic Honing Machine is designed for the honing of a wide variety of parts and especially for long or heavy cylinders of internal com-

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bustion engines, including automobile, tractor and Diesel engines, cylinder liners, tractor motor sleeves, etc. The machine successfully hones bores up to 160 mm diameter and 1100 mm long.

Honing is accomplished by simultaneous rotation and reciprocation of the hone within the bore, with the hone abrasives under hydraulically controlled pressure.

The rigid cast-iron column has accurately machined ways and maintains accurate alignment of spindle. Six changes of spindle speeds are provided. A hydraulic cylinder provides balanced hydraulic pressure for reciprocating the hone steadily and reversing direction of movement without shocks, ting the hone steadily and reversing direction of movement without shocks, so necessary in obtaining a high degree of accuracy. The following movements are operated hydraulically: gradually lowering the hone, reciprocating, hone expansion, return up stroke, speed changing and work table travel.

The working cycle of the machine is completely automatic. The automatic cycle includes: gradually lowering the hone, starting spindle rotation and reciprocation, expanding hone feed to the desired bore size, honing without further expansion of hone, hone contraction and lift out.

A short stroking mechanism is provided to remove tapers or to make any desired correction in cylinder bore.

The machine is equipped with a work carrying table moved in and out.

The machine is equipped with a work carrying table moved in and out by means of the hydraulic cylinder. This table serves a convenience for gauging and for reloading.

SPECIFICATIONS

Capacity Diameter of bore honed, mm: 65 Minimum 65 Maximum 160	Spindle reciprocating speeds, m'min.: Minimum
Spindle and Table Reciprocating travel of spindle, num: Minimum 100	Drive 220 380 volt, 3 phase, 50 cycle A.C. motors: Spindle rotation:
Maximum	Power, kW
table, mm: Minimum 1205 Maximum 2425 Taper in spindle Morse No. 5 Working surface of in and out	Speed, r. p. m 1000 Coolant pump: Power, kW 0.6 Speed, r. p. m 3000
table, mm	Space Occupied
Speeds Number of spindle rotation speeds 6	Floor space, mm 2350 × 1260 Height of machine, mm 4870
Range of spindle speeds, r.p.m. 75—400	Weight Net weight, kg approx. 7000



OPTICAL PROJECTION FORM GRINDING MACHINE

MODEL 395 M



The 395 M Optical Projection Form Grinder is a precision machine designed for grinding most accurately every desired profile within its range, directly from the drawing. It is especially suited for the grinding of both circular and flat form tools, templates, profile gauges, cams, dies, etc., from

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hardened materials including tungsten carbide. The machine is not limited by the regularity or irregularity of the work, nor by straight lines, circular or irregular curves. The machine has a large screen of 500×500 mm area on which a layout

The machine has a large screen of 500×500 mm area on which a layout drawing of the work profile made to scale of 50 to 1 is placed. An optical device projects the work to be ground and the grinding wheel on the screen with a $50 \times$ magnification. The work is clamped and squared to the work table, the screen then squared with the work by a simple adjustment, and the wheel is then set to traverse at any required angle by the universal compound adjustments in the wheel head.

The wheel head slides are traversed along the work profile either manually

The wheel head slides are traversed along the work profile either manually or by power by means of D. C. motors with infinitely variable speeds. The reciprocating motion of the wheel spindle slide is effected by a motor

The reciprocating motion of the wheel spindle slide is effected by a motor through a crank mechanism.

SPECIFICATIONS

DI DOM TOND		
Capacity		Speeds
Maximum working range, nim: Direct, at one setting of work slides	10 × 10	Grinding wheel speed, r, p, m. 3500 Wheel head slide speed,
Indirect, at several set- tings of work slides by		mm/min,: Minimum 0.2 Maximum 20
means of gauge blocks Maximum thickness of work	150×60	Range of wheel spindle slide strokes per min
accomodated, mm	48	•
Grinding Wheel and Head		Drive
Maximum travel of wheel head		220/380 volt, 3 phase, 50 cycle A. C. motors:
lower slide, mm Angular adjustment of wheel	150	Grinding wheel:
head lower slide	45°	Power, kW 0.6 Speed, r. p. m 3000
Maximum travel of wheel head upper slide, mm	130	Dust exhausting system: Power, kW 0.65
Angular adjustment of wheel head upper slide	± 45°	Speed, r. p. m
Wheel head angle of tilt, for		Generator set: Power, kW 0.6
side clearance Wheel spindle slide angle of	±10°	Speed, r. p. m 1500 Wheel head slide D. C.
tilt, for front clearance . +:	10 : —30	motor:
Minimum diameter of grin- ding wheel, mm	85	Power, W
Maximum diameter of grin-		Speed, 1. p. m
ding wheel, mm	125	Space Occupied
Work Table Work table travel, mm:		Floor space, mm 1485 1600 Height of machine, mm 2000
Vertical	100	•
Longitudinal	60	Weight
Cross	150	Net weight, kg approx. 1560

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Design and specifications of the machine tools illustrated herein are subject to change without notice.

Order N 156

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